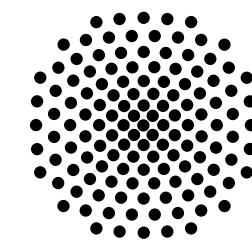


# Robust detection of an entanglement transition in the projective transverse field Ising model

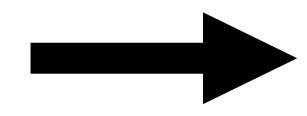
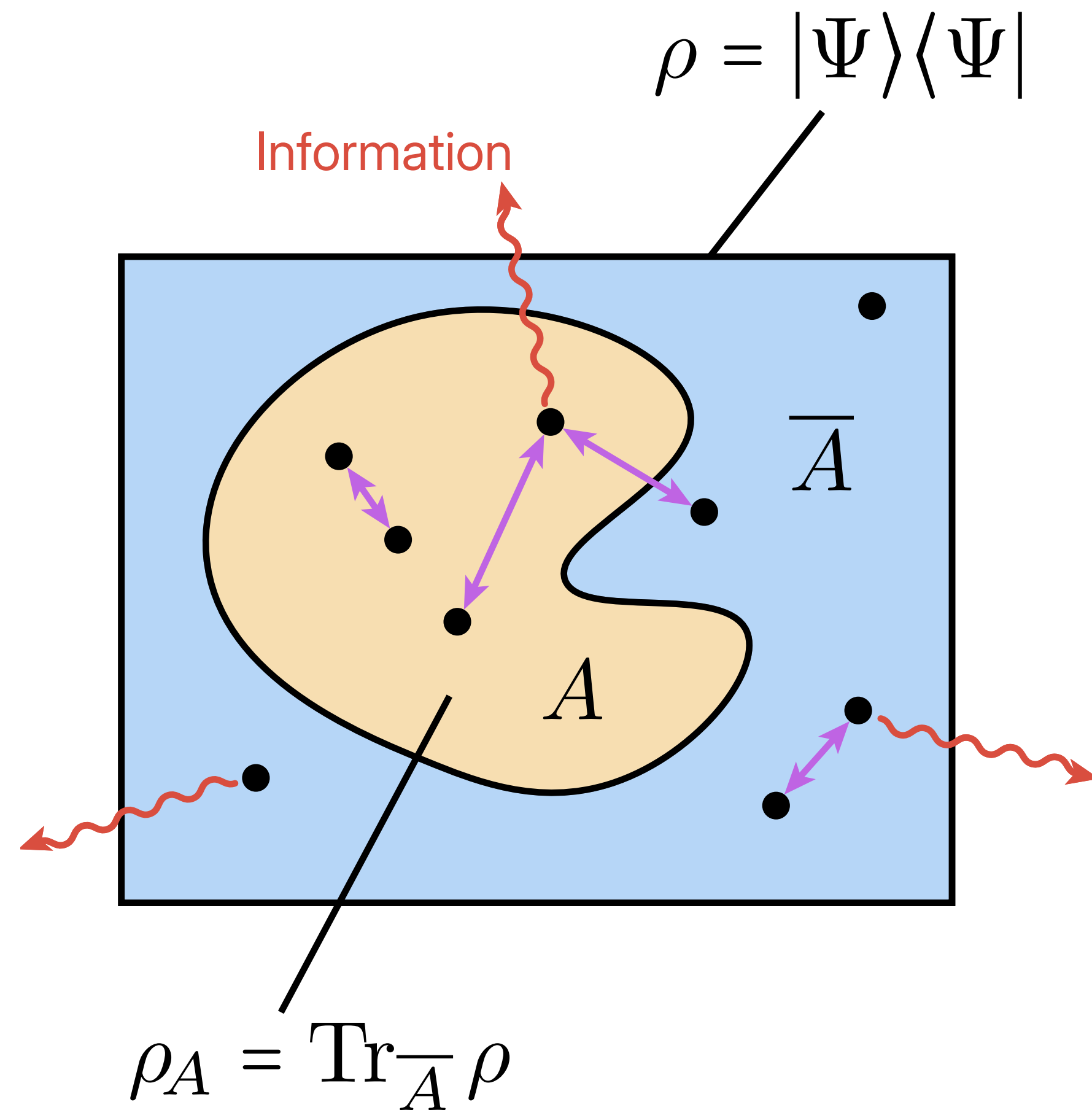
Felix Roser, 20.02.2026



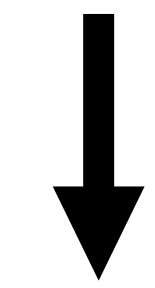
Universität Stuttgart

Institute for  
**Theoretical**  
Physics

# Can quantum properties survive decoherence?



Can quantum entanglement survive under monitoring?

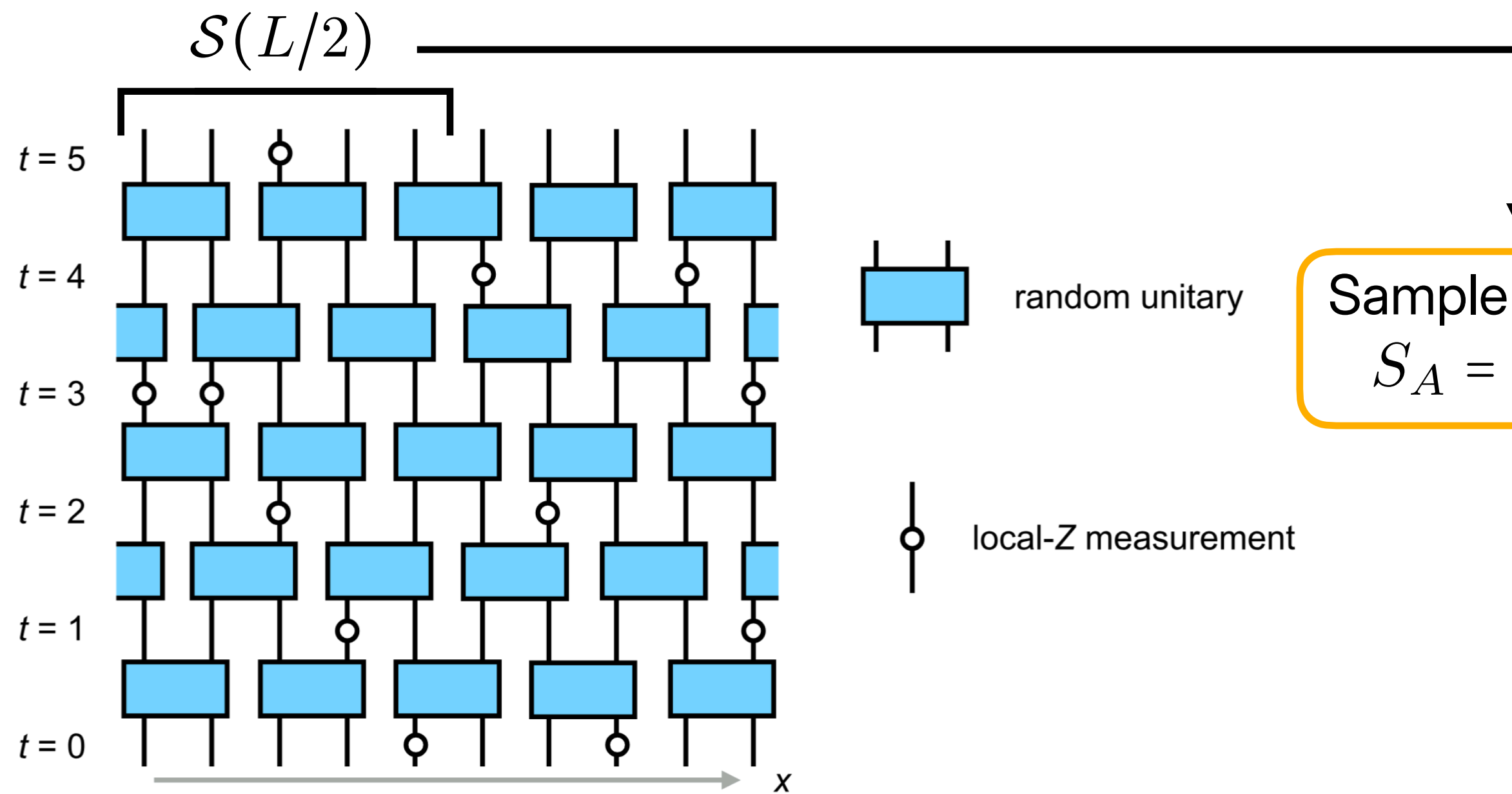


Von Neumann entanglement entropy

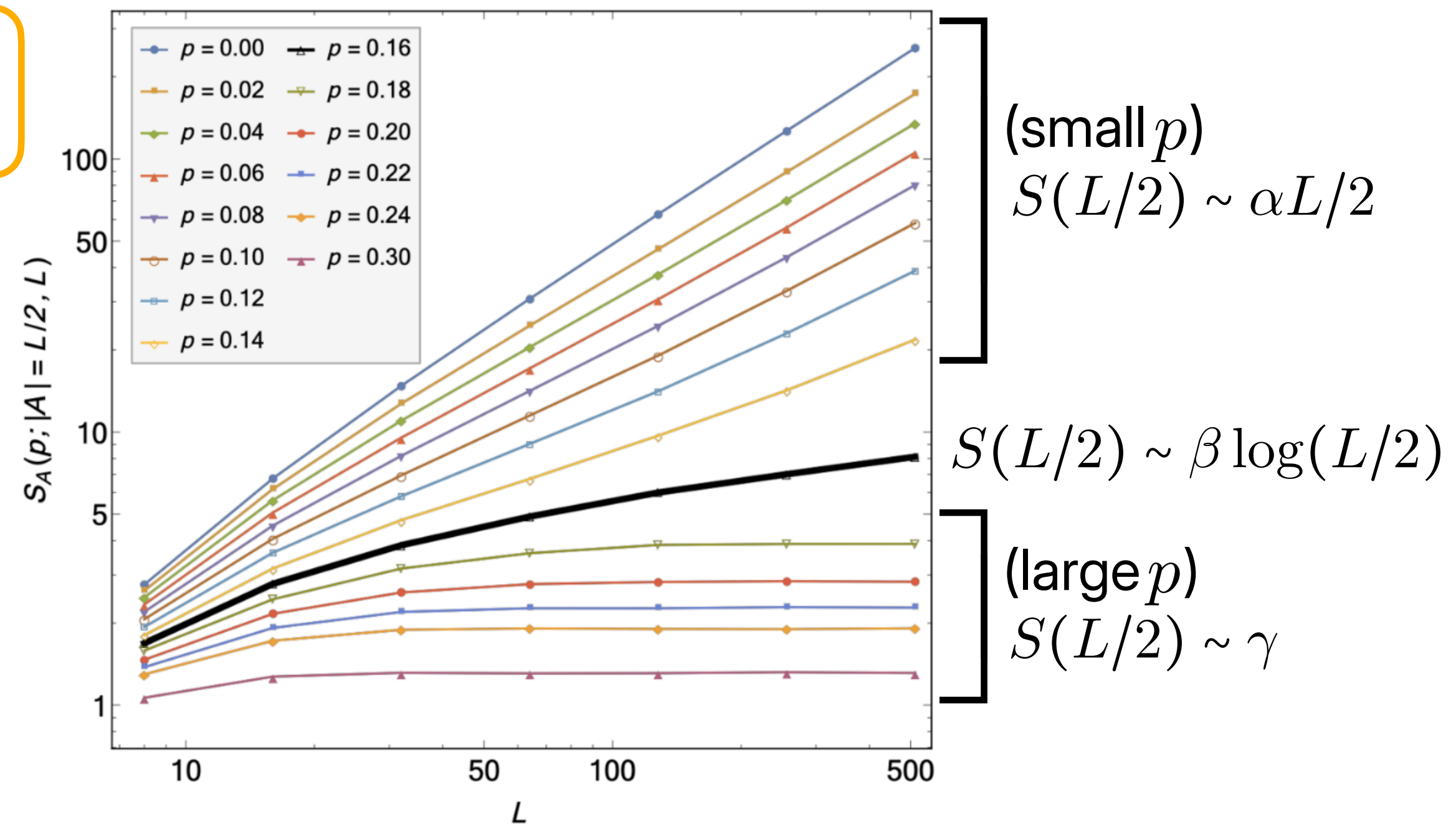
$$S_A = -\text{Tr} [\rho_A \log_2 \rho_A]$$

# Entanglement transitions

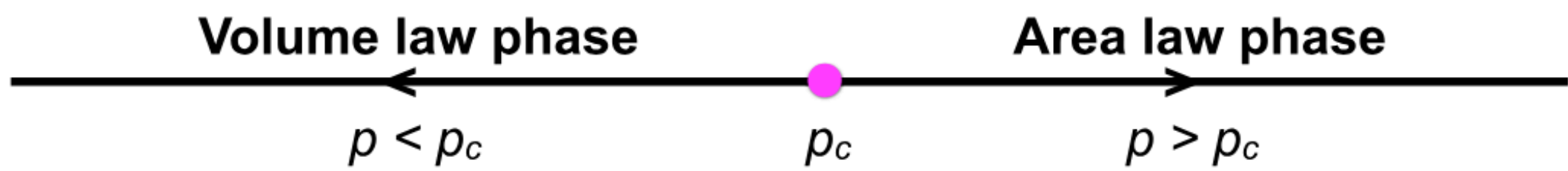
## Hybrid random quantum circuits



Sample average  
 $S_A = \langle\langle S_A \rangle\rangle$

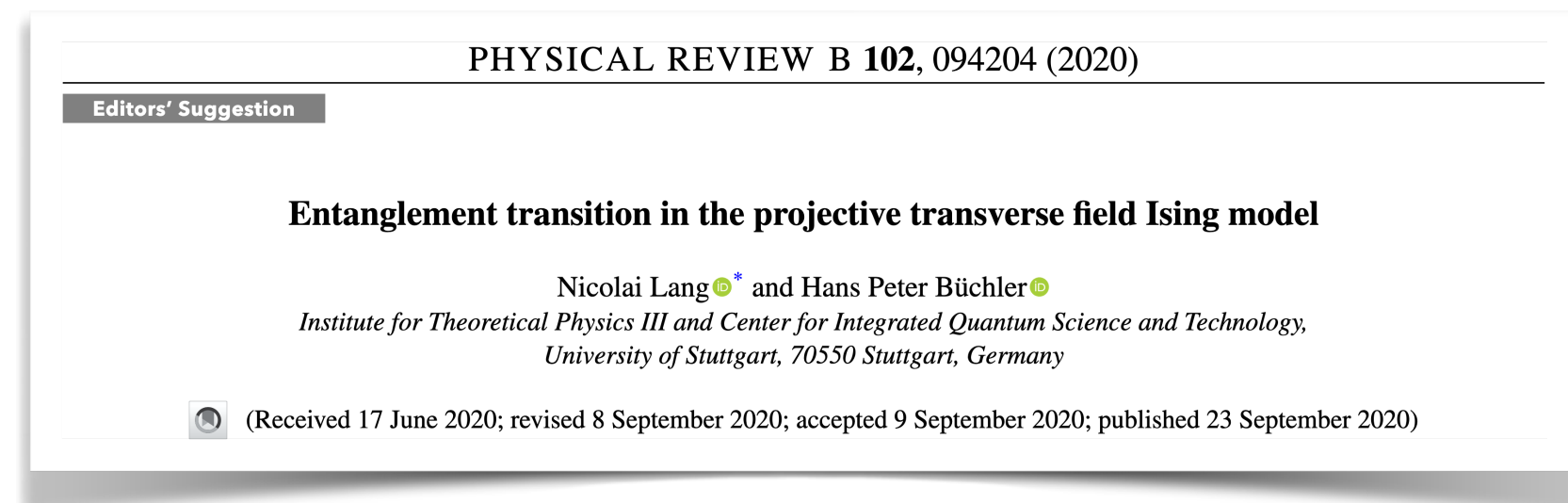
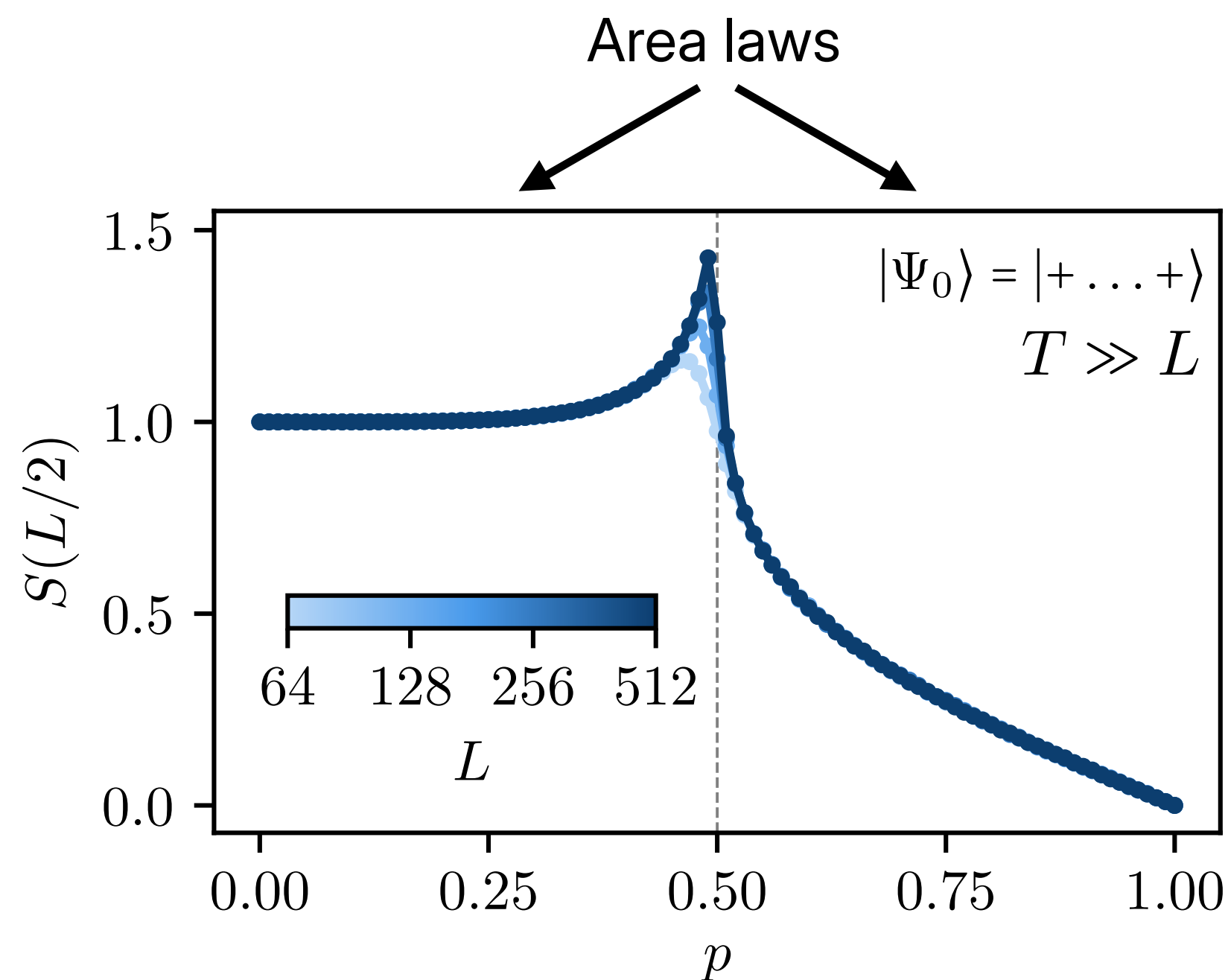
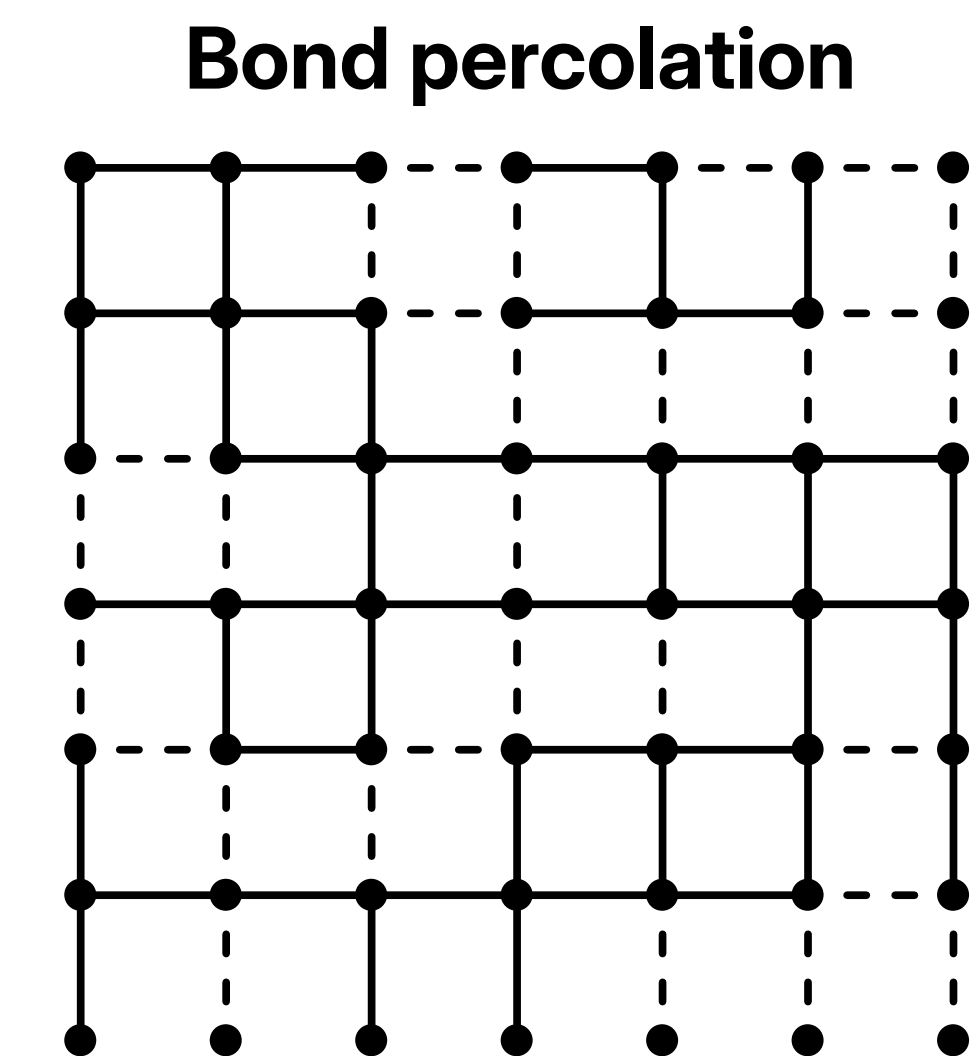
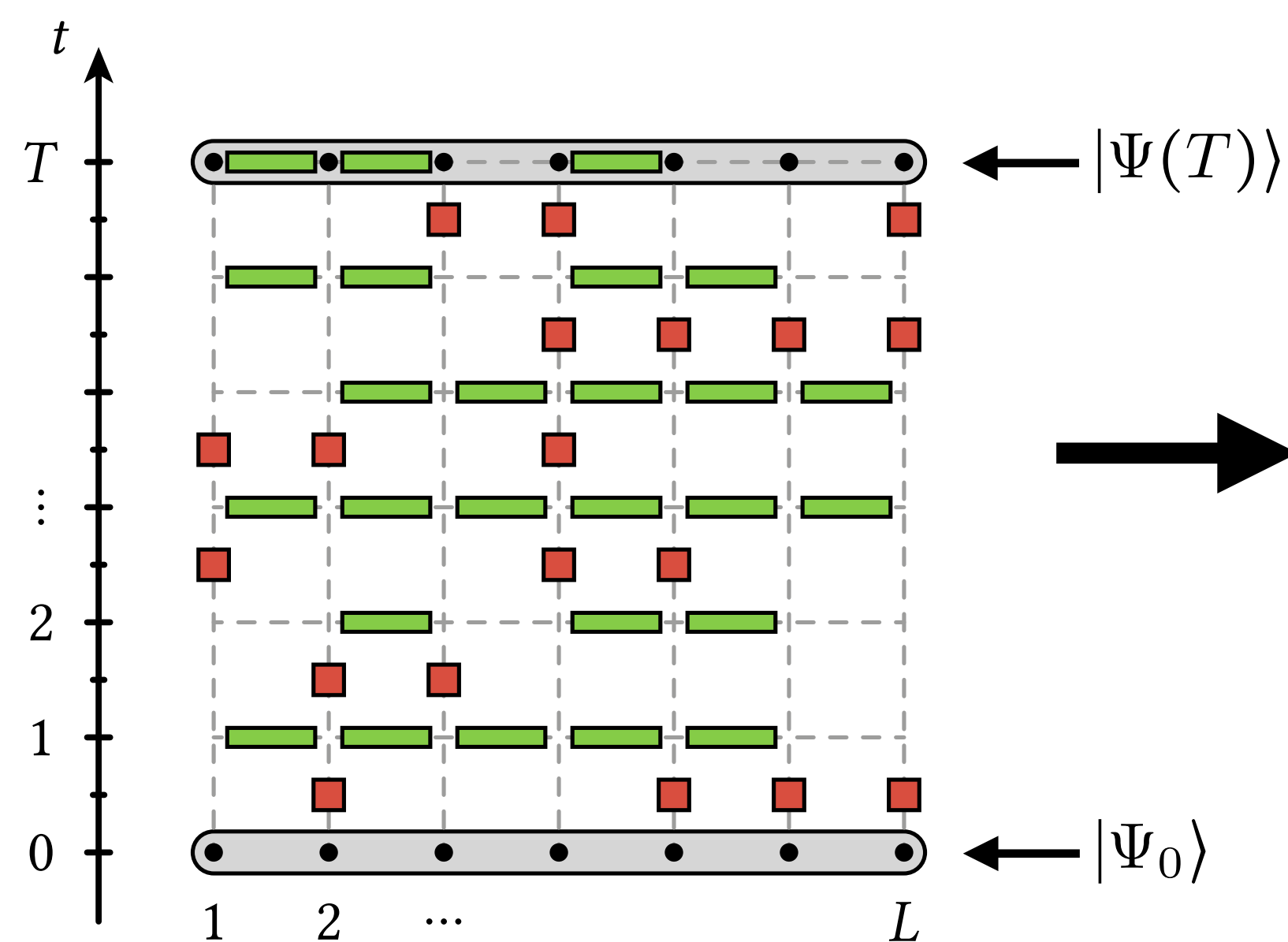


- Random unitaries  
 → entangle multiple qubits
- Measurements (with probability  $p$ )  
 → disentangle single qubits



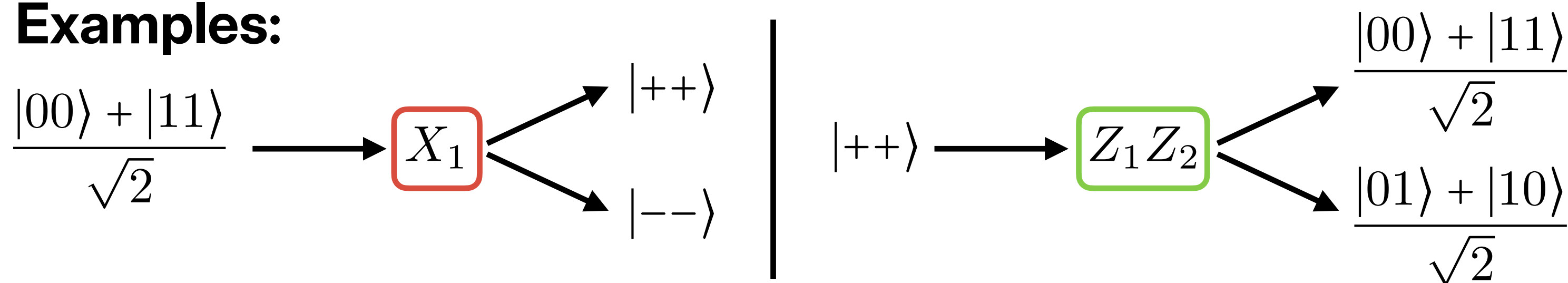
# Projective transverse field Ising model (PTIM)

- :  $X_i$  measurement (probability  $p$ )
- :  $Z_i Z_{i+1}$  measurement (probability  $1 - p$ )

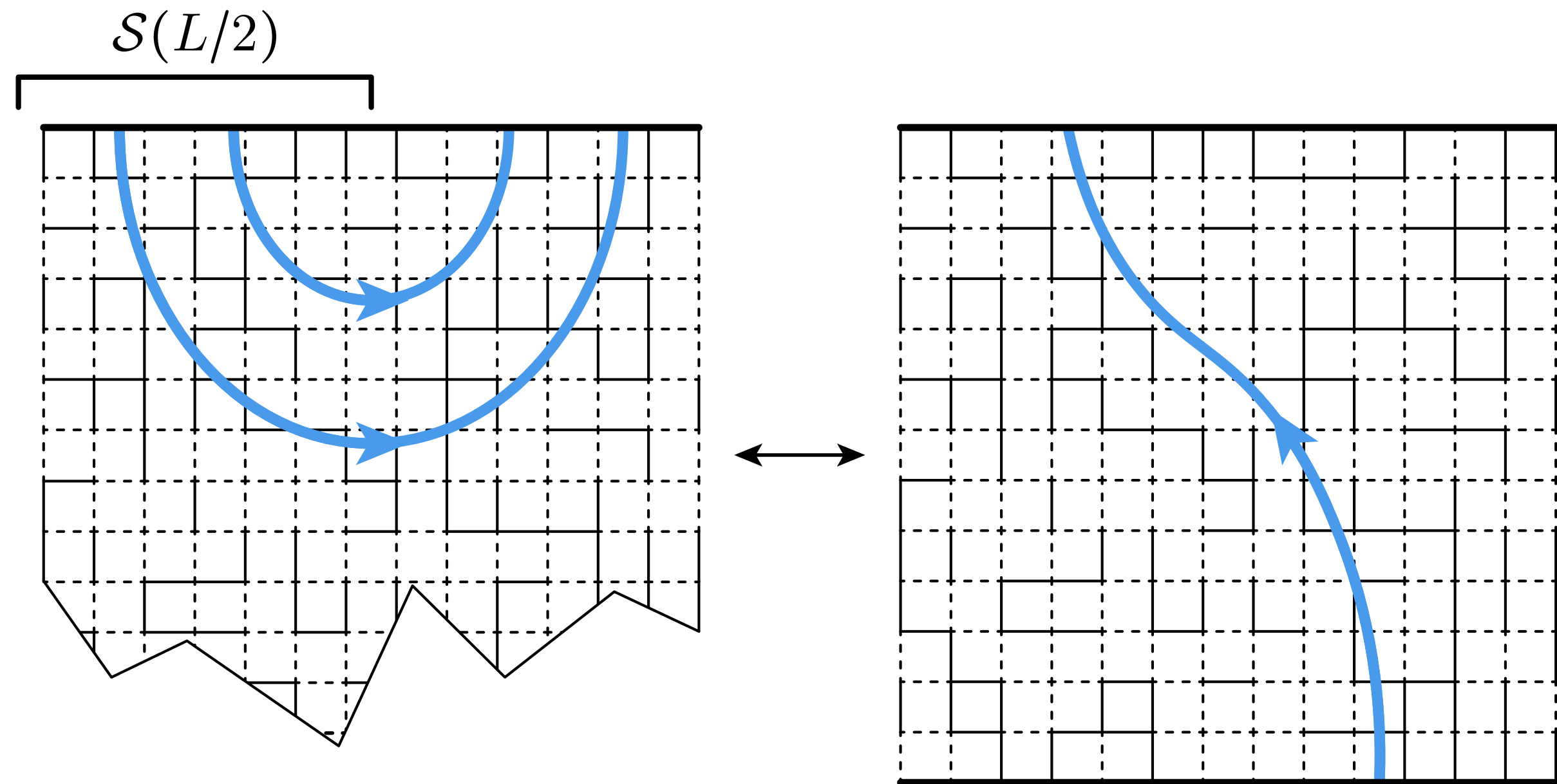


Nahum & Skinner, PRR 2, 023288 (2020)

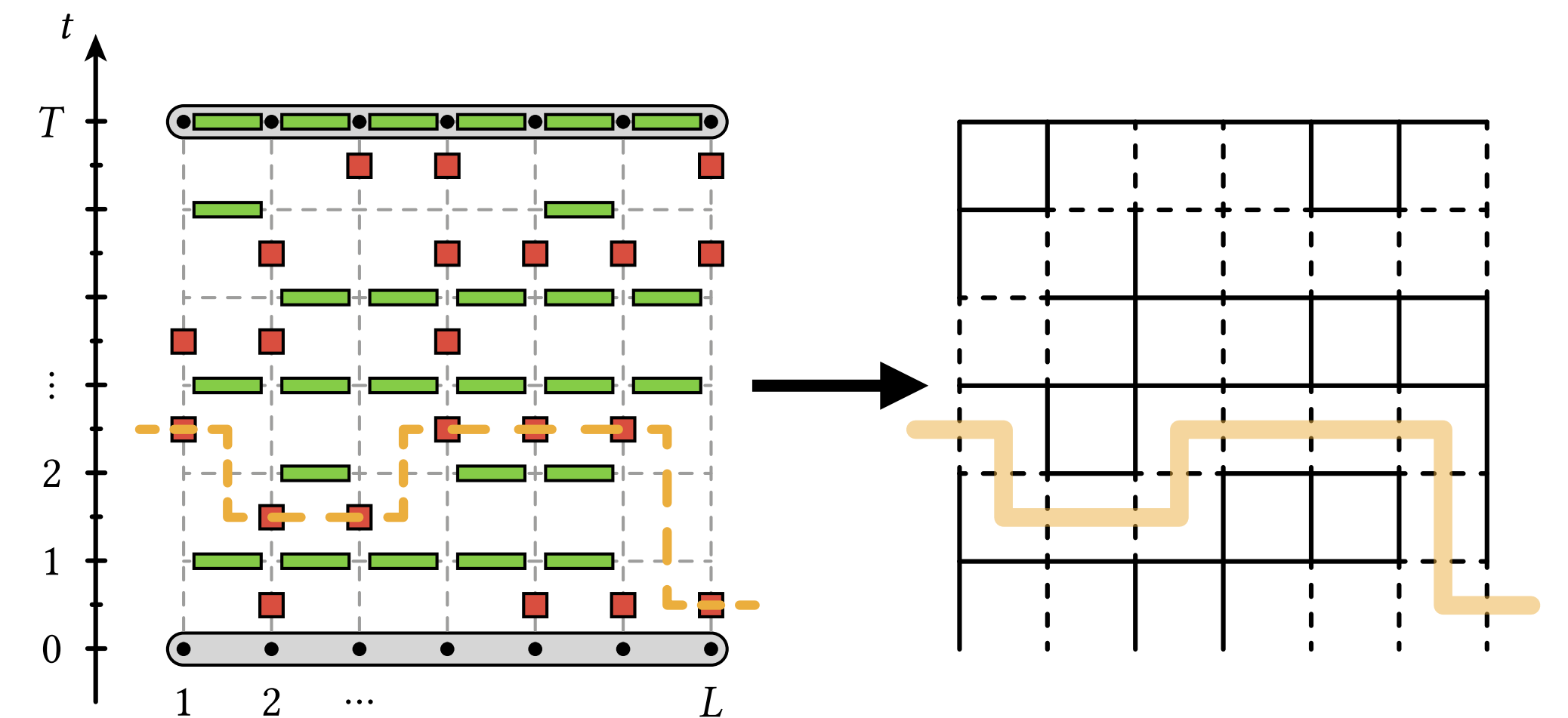
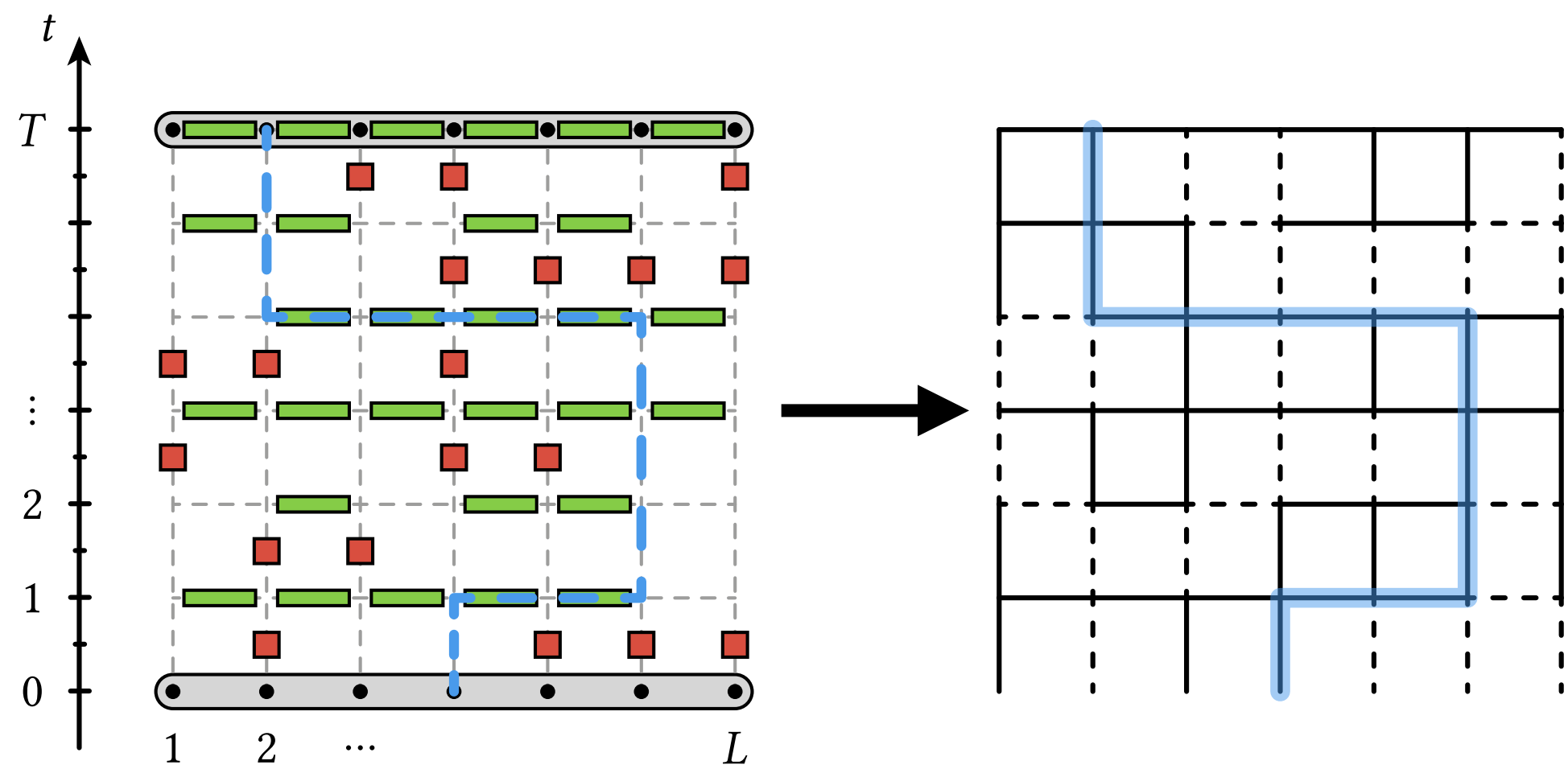
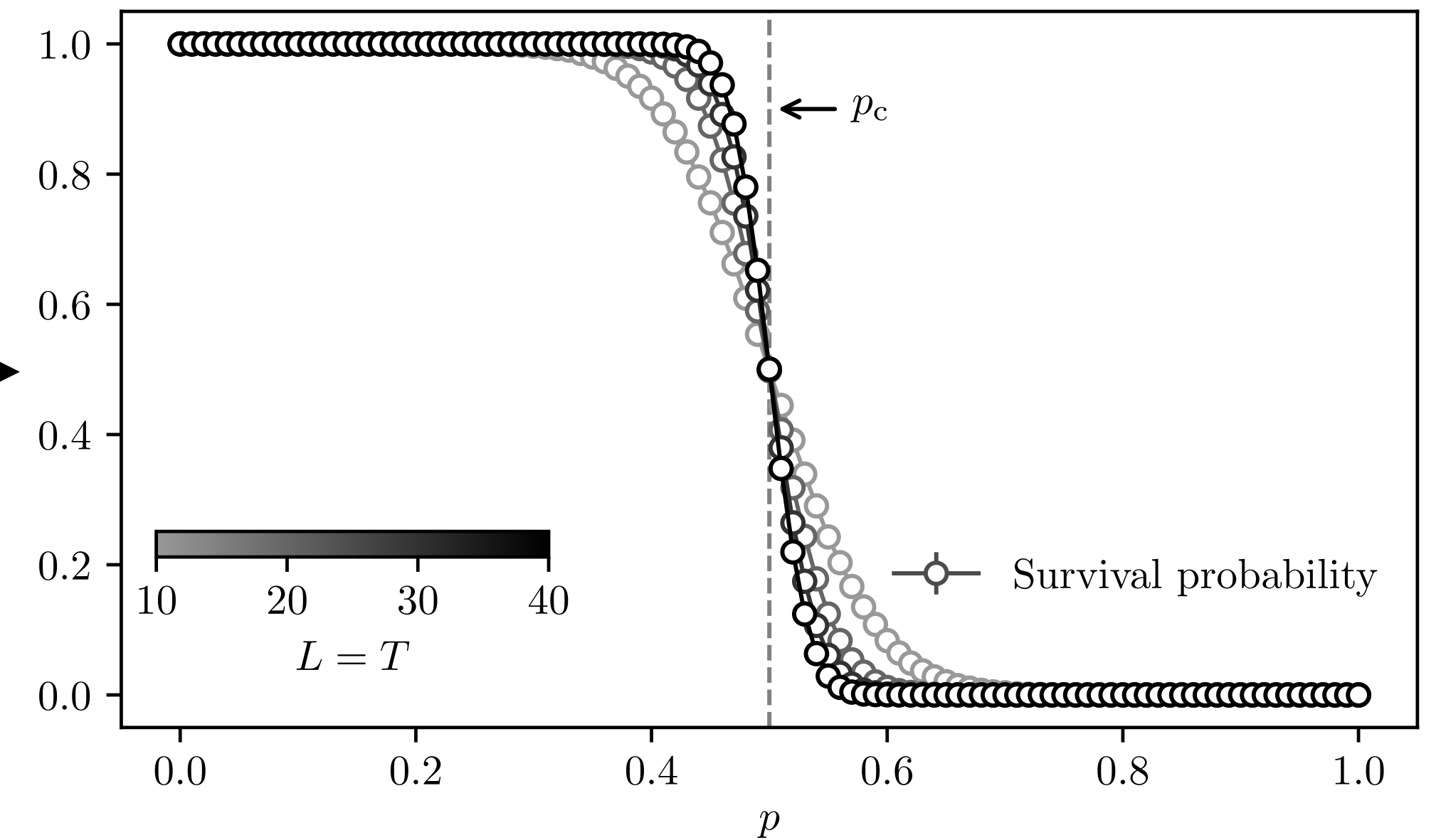
## Examples:



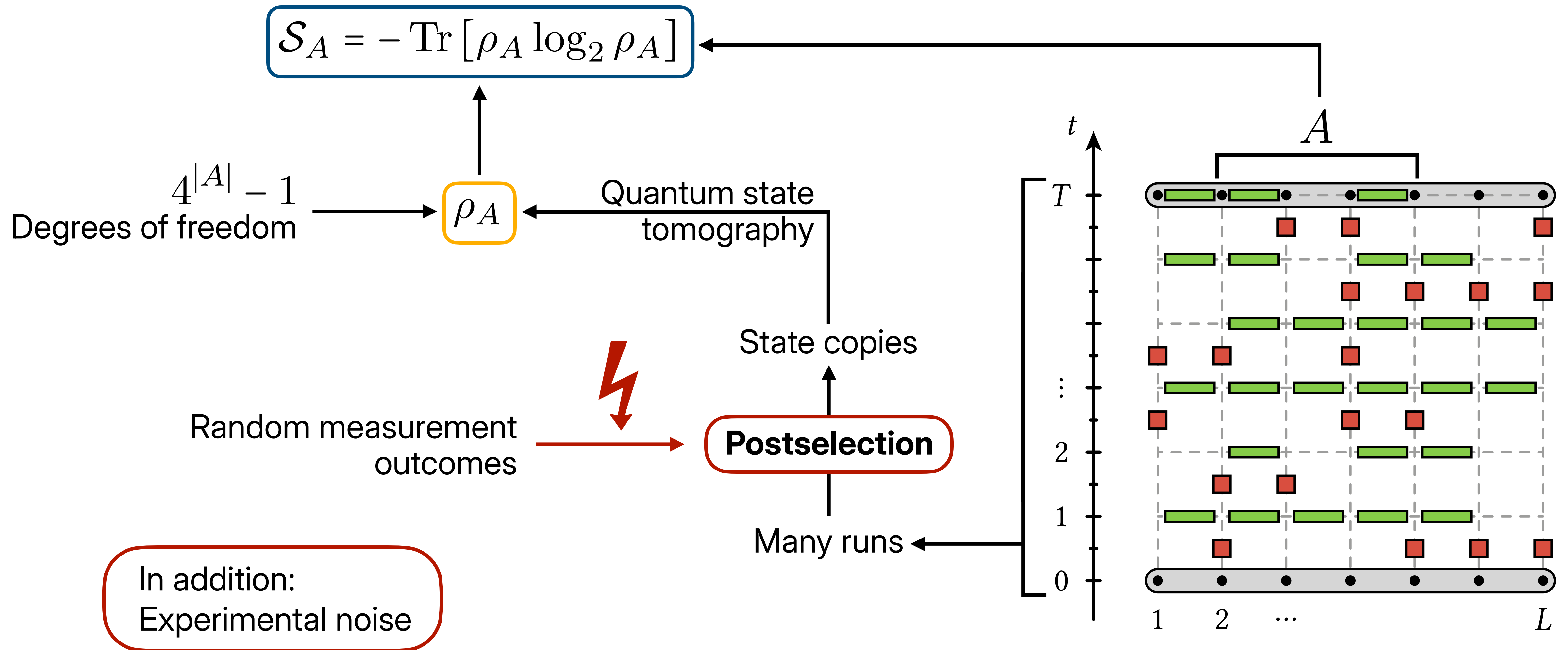
# Distinguishing PTIM phases



"Does the system remember its initial state?"

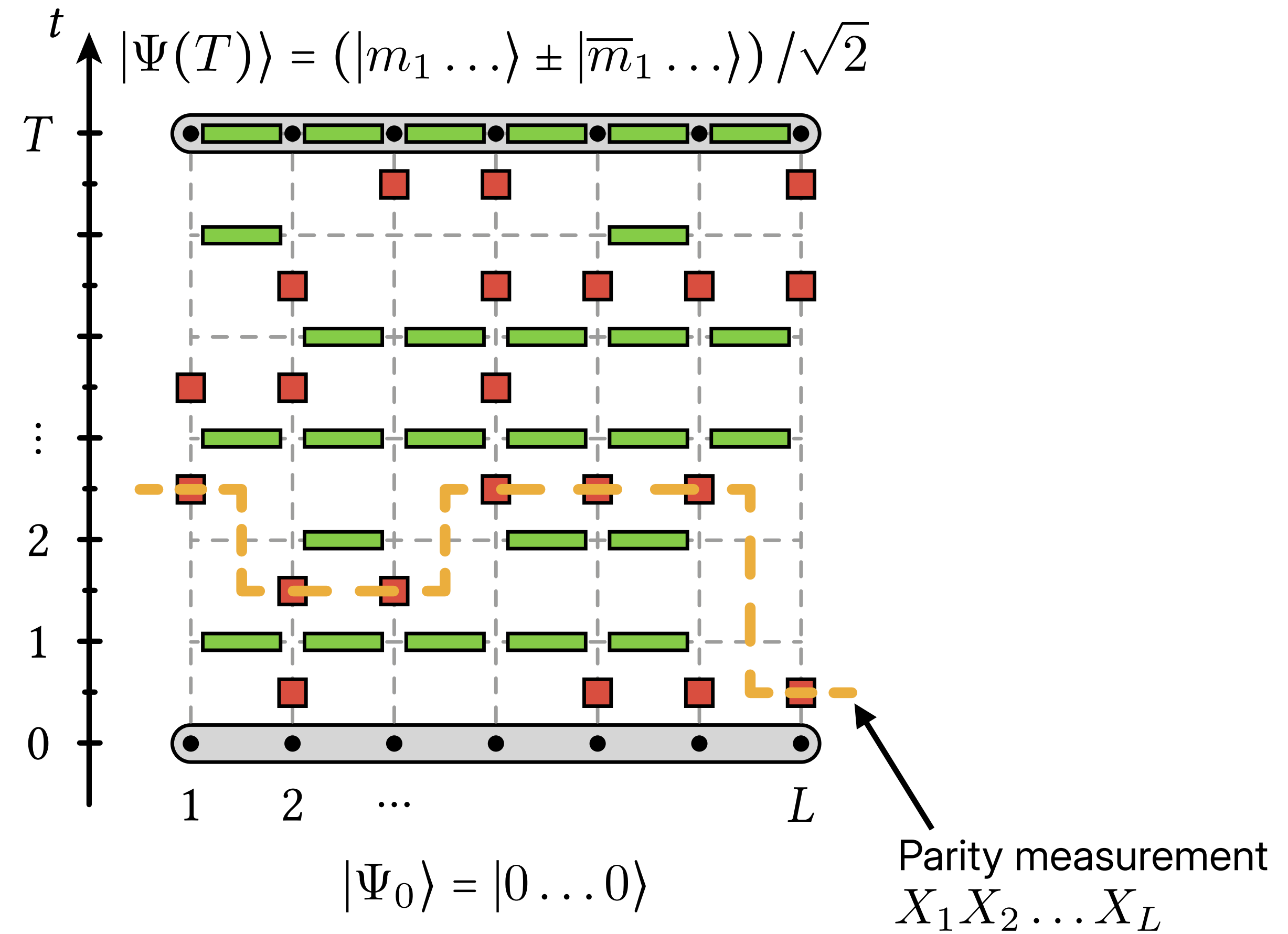
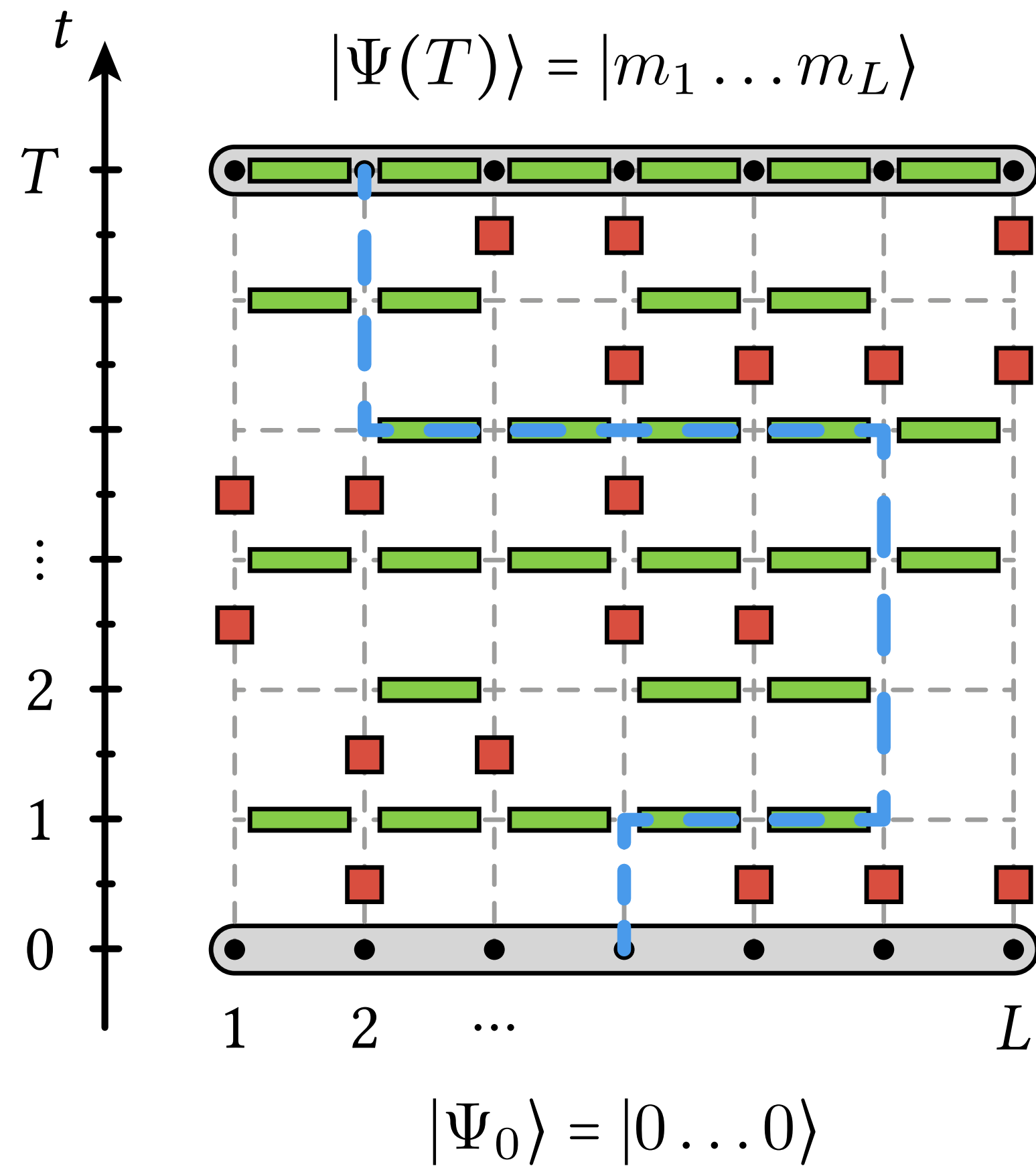


# Measuring entanglement is difficult!

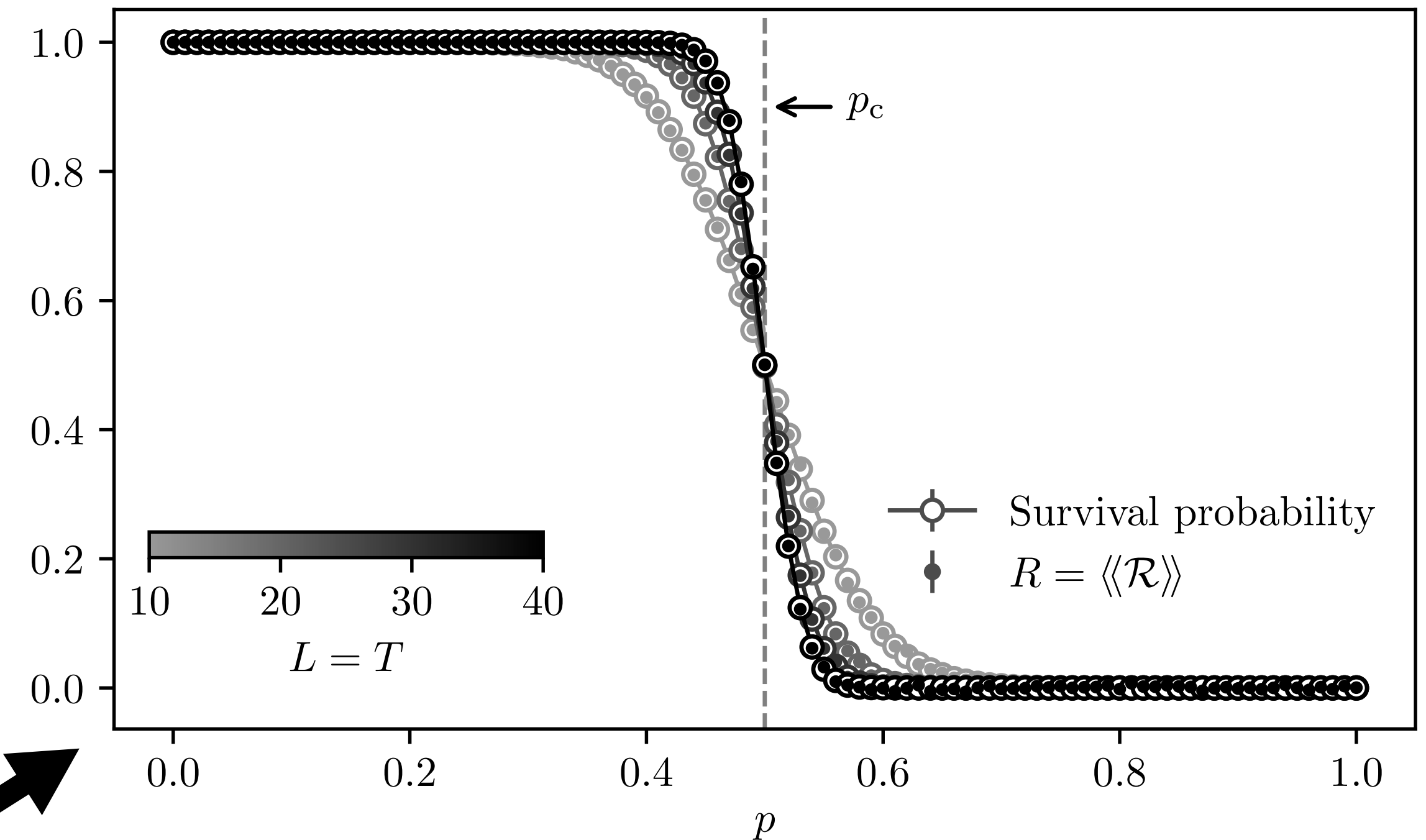
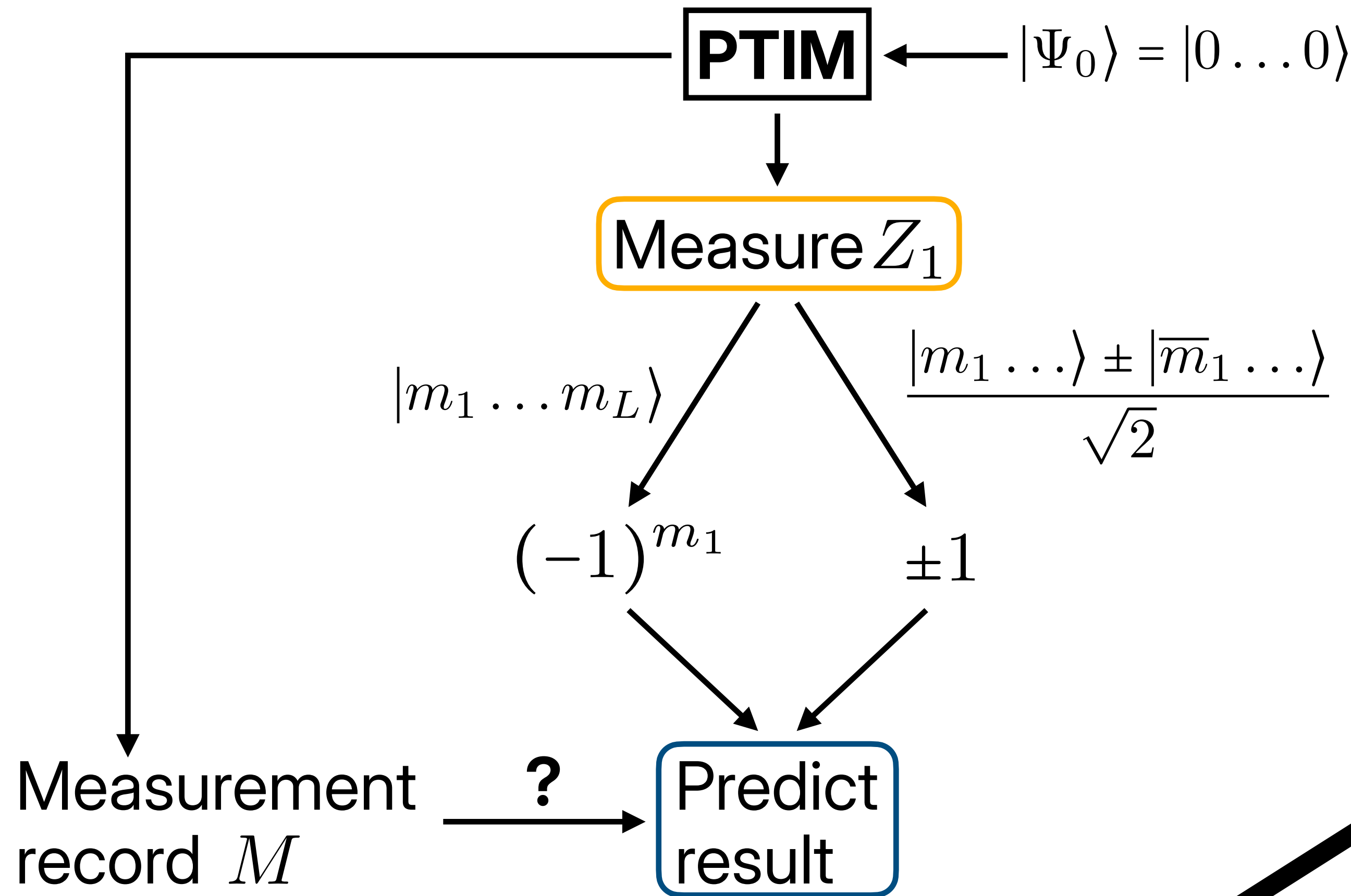


# PTIM as quantum memory

Gullans & Huse, PRL **125**, 070606 (2019)  
 Gullans & Huse, PRX **10**, 041020 (2020)  
 Choi, Bao, Qi & Altman, PRL **125**, 030505 (2020)  
 Roser, Büchler, Lang, PRB **107**, 214201 (2023)



# Detecting the PTIM transition

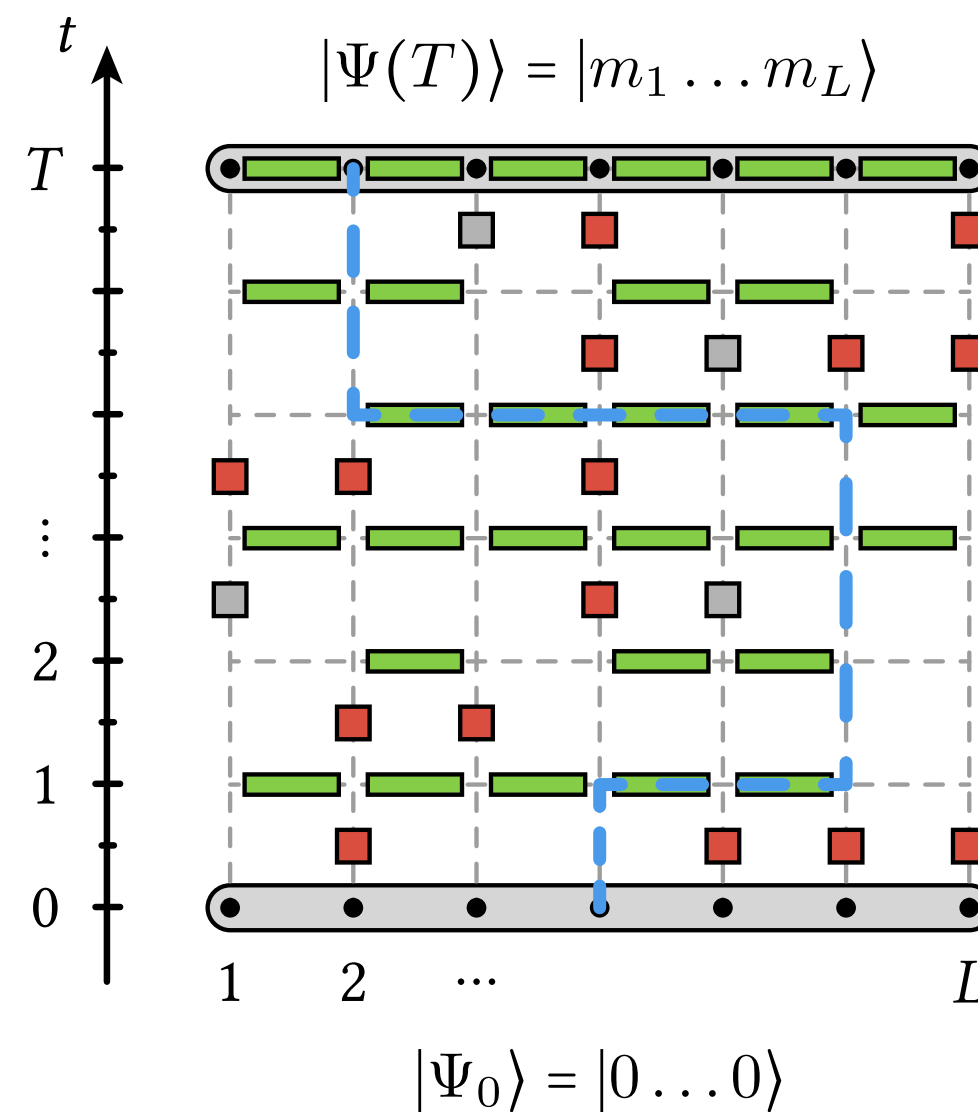
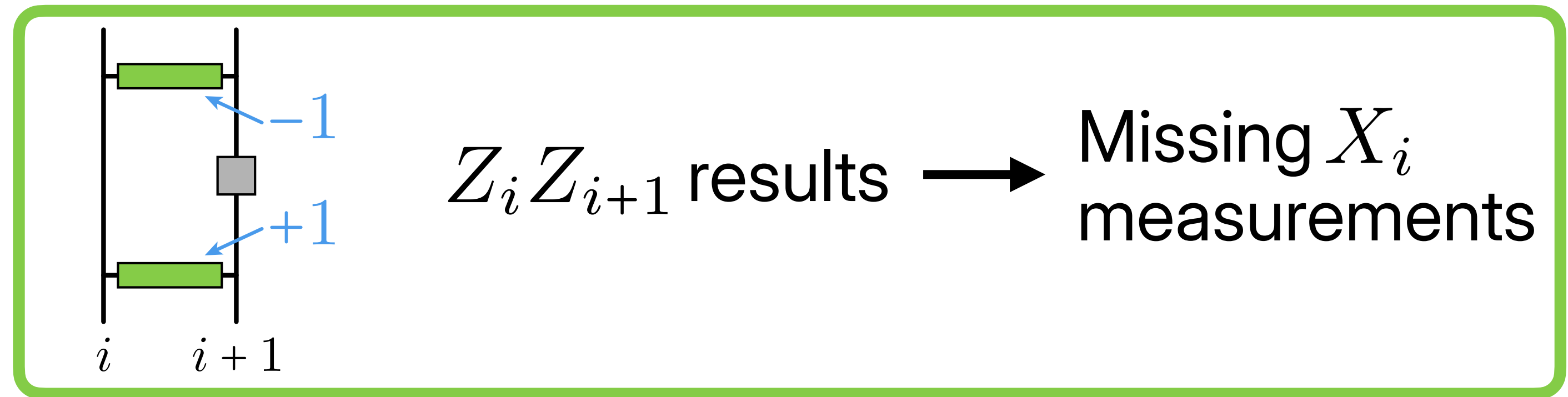
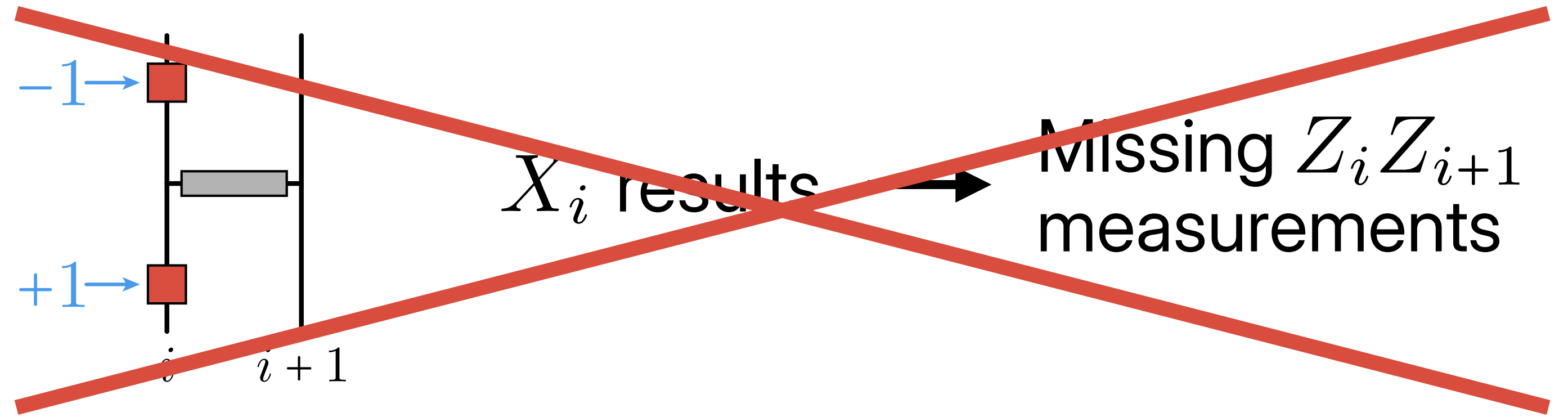
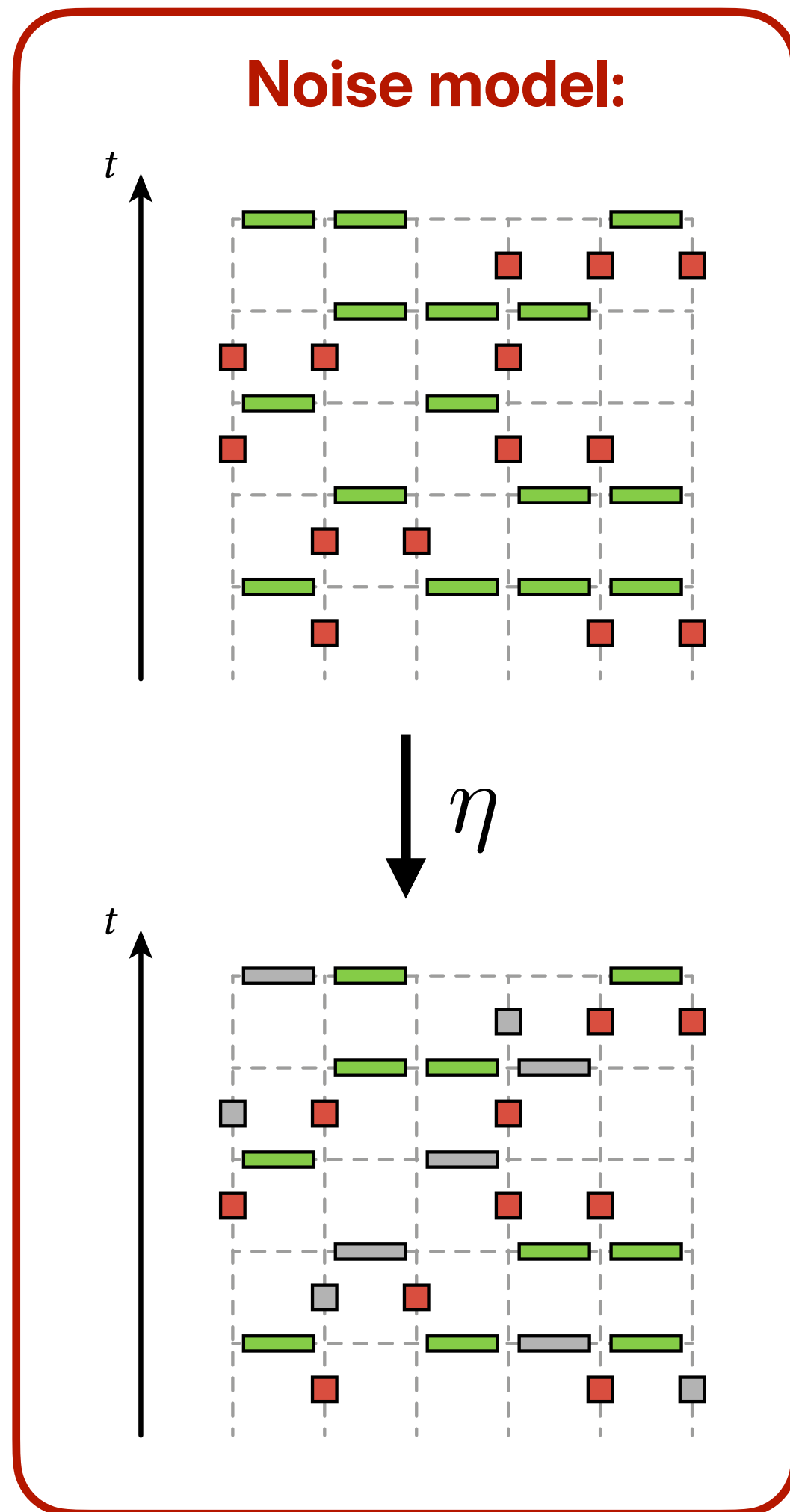


Correlation function:  $\mathcal{R} = \begin{cases} +1 & \text{correct prediction} \\ -1 & \text{incorrect prediction} \end{cases}$

- Can this be measured? ✓
- Can this be scaled? ✓
- Is this robust under noise? ✗

# PTIM with noise

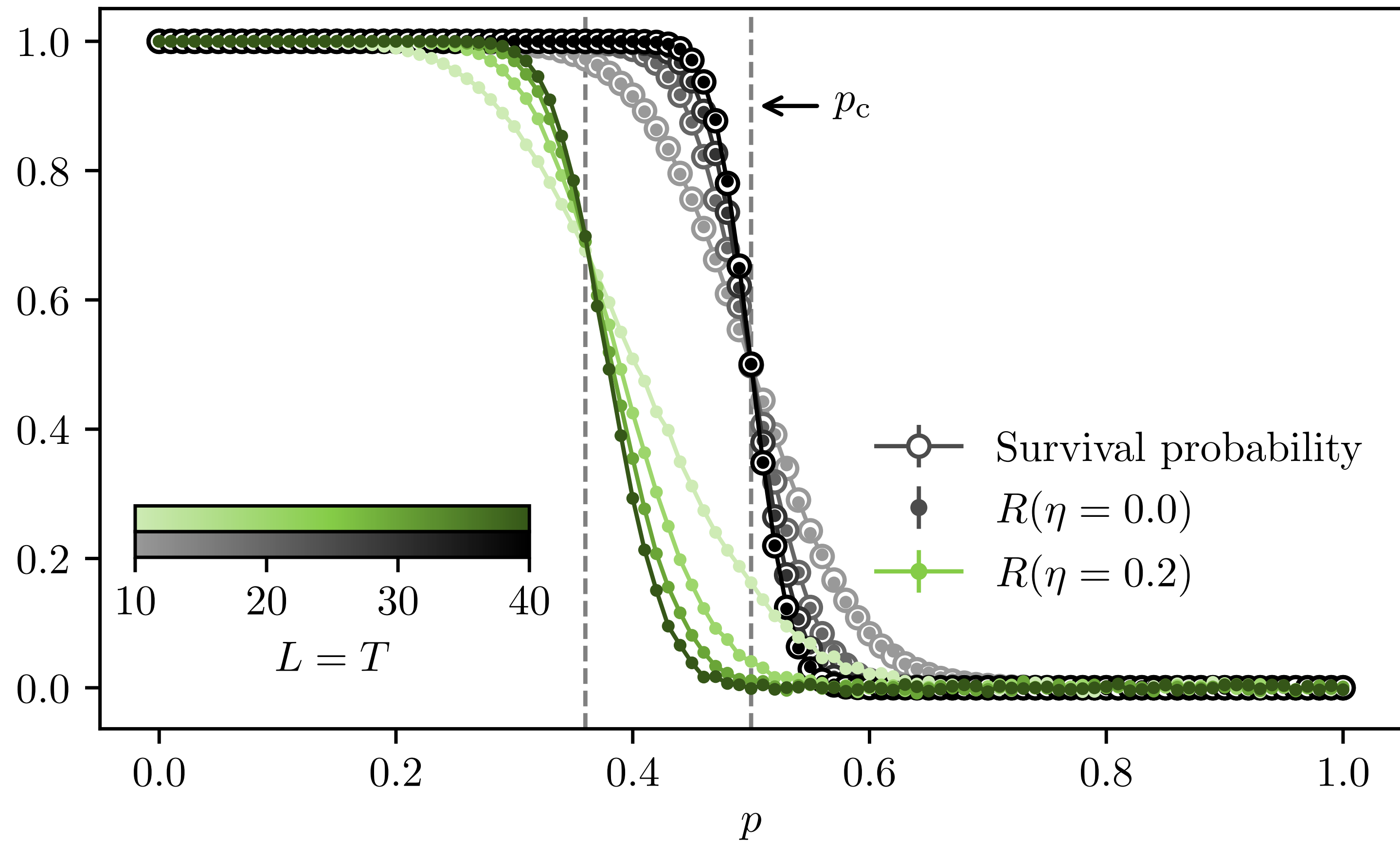
## Error correction



Augment measurement record

Find least number of additional measurements

# Accessible lower bound for the entanglement transition



Can we also measure an upper bound?

# Upper-bounding entanglement

What if a single run only yields limited information?

Probing Postmeasurement Entanglement without Postselection

Samuel J. Garratt<sup>1,\*</sup> and Ehud Altman<sup>1,2</sup>

<sup>1</sup>Department of Physics, University of California, Berkeley, California 94720, USA

<sup>2</sup>Materials Science Division, Lawrence Berkeley National Laboratory, Berkeley, California 94720, USA

(Received 17 October 2023; revised 11 May 2024; accepted 13 June 2024; published 18 July 2024)

Cannot be measured  $\rightarrow S_A = \langle\langle -\text{Tr} [\rho_A \log_2 \rho_A] \rangle\rangle \leq \langle\langle -\text{Tr} [\rho_A^S \log_2 \rho_A^C] \rangle\rangle = S_A^{\text{SC}} \leftarrow$  Can be measured

Shadow  $\langle\langle \rho_A^S \rangle\rangle \rightarrow \rho_A$

$$\rho_i^S = \frac{3}{2} (\mathbb{1} + O_i \cdot o) - \mathbb{1}$$

Random Pauli measurement  
 $O_i \in \{X_i, Y_i, Z_i\}$

Measurement result  
 $o \in \{\pm 1\}$

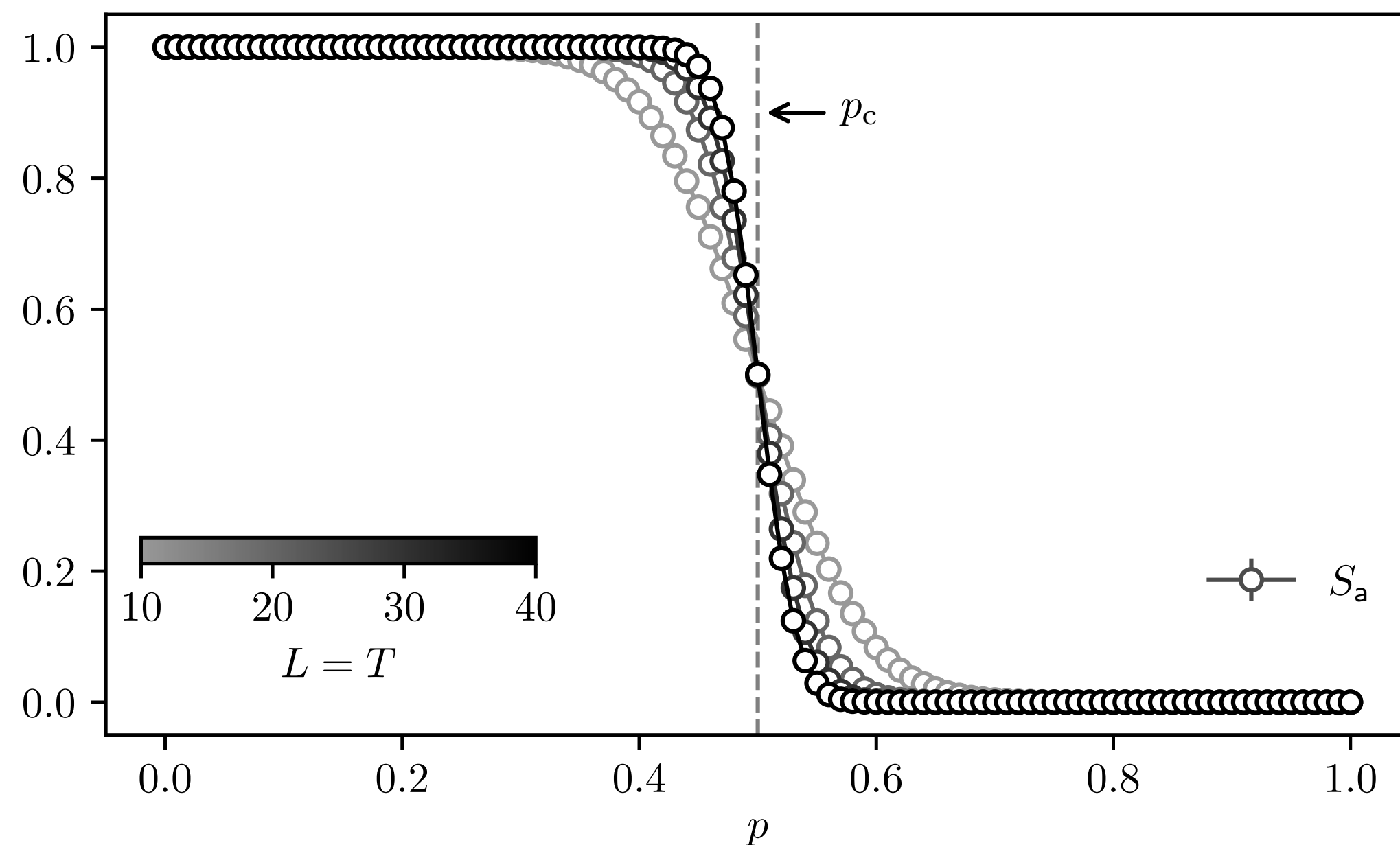
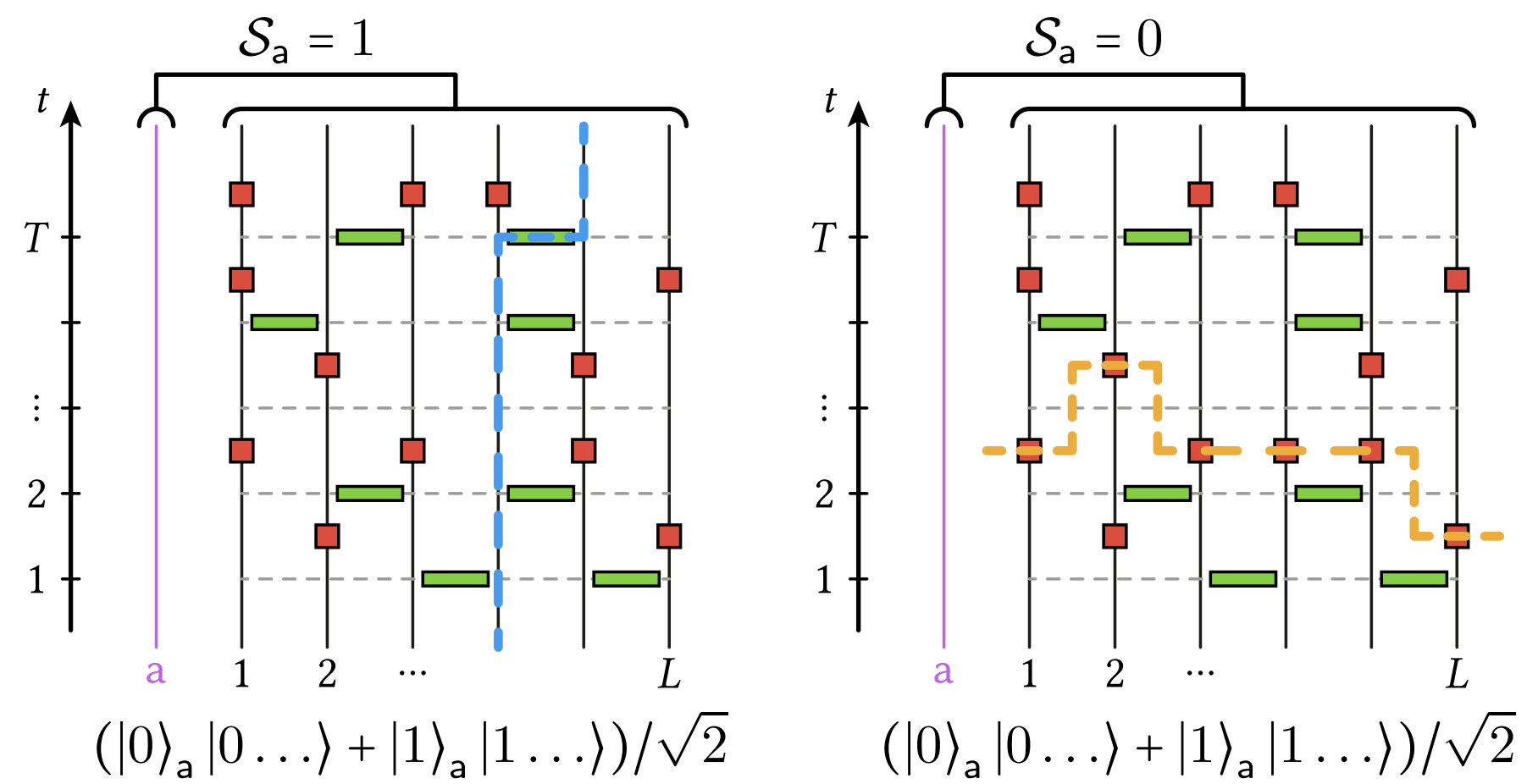
Classical state prediction  $\rho_A^C(M)$

Depolarizing:

$$\rho_A^C(M, \varepsilon) = (1 - \varepsilon) \rho_A^C(M) + \frac{\varepsilon}{2^{|A|}} \mathbb{1}$$

- Errors diverge for large subsystems  $A$ !
- Not robust under noise!
- Entanglement entropy  $\neq$  entanglement transition!

# Upper-bounding the entanglement transition



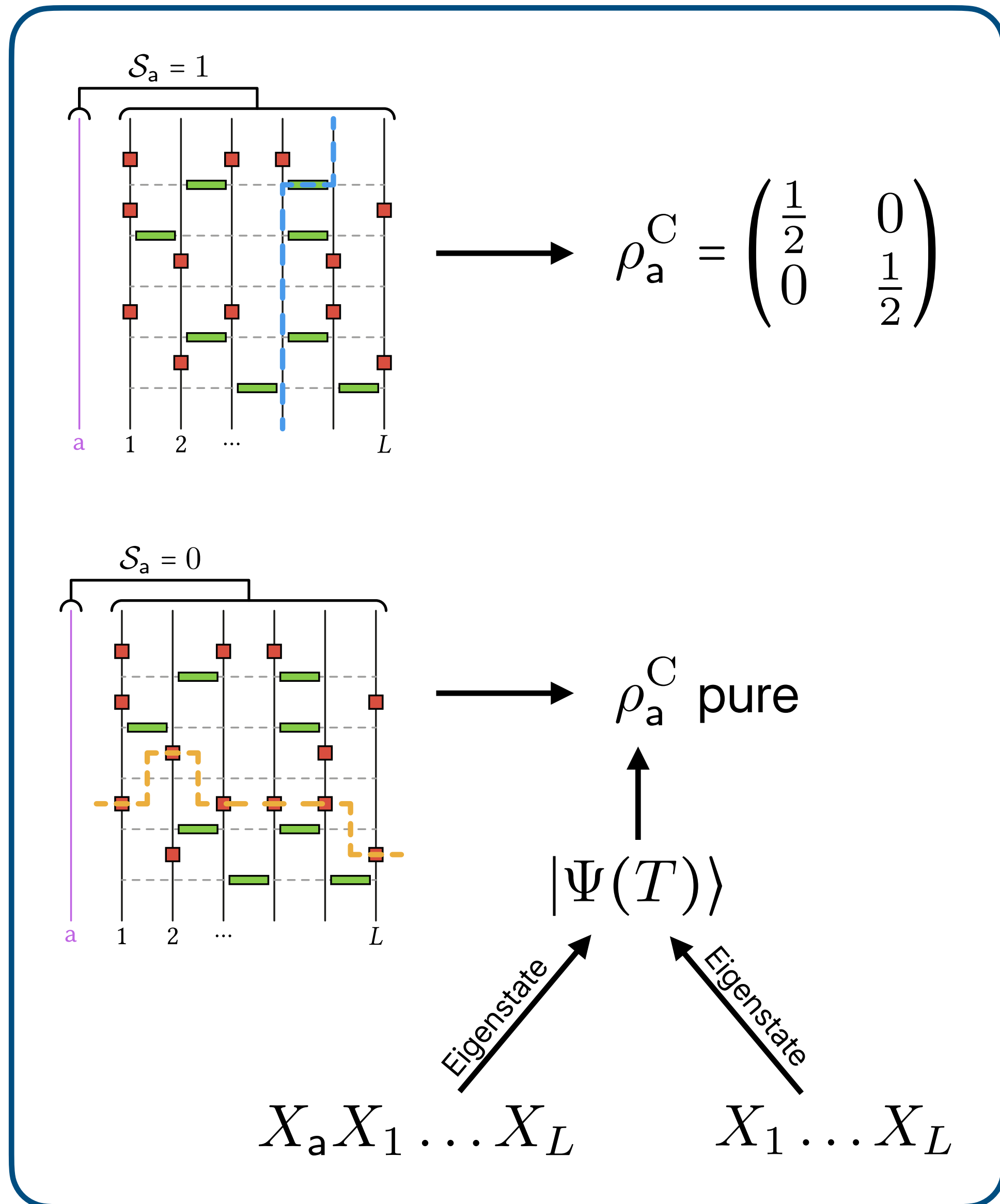
Upper bound

$$S_a \leq \langle\langle -\text{Tr} [\rho_a^S \log_2 \rho_a^C] \rangle\rangle$$

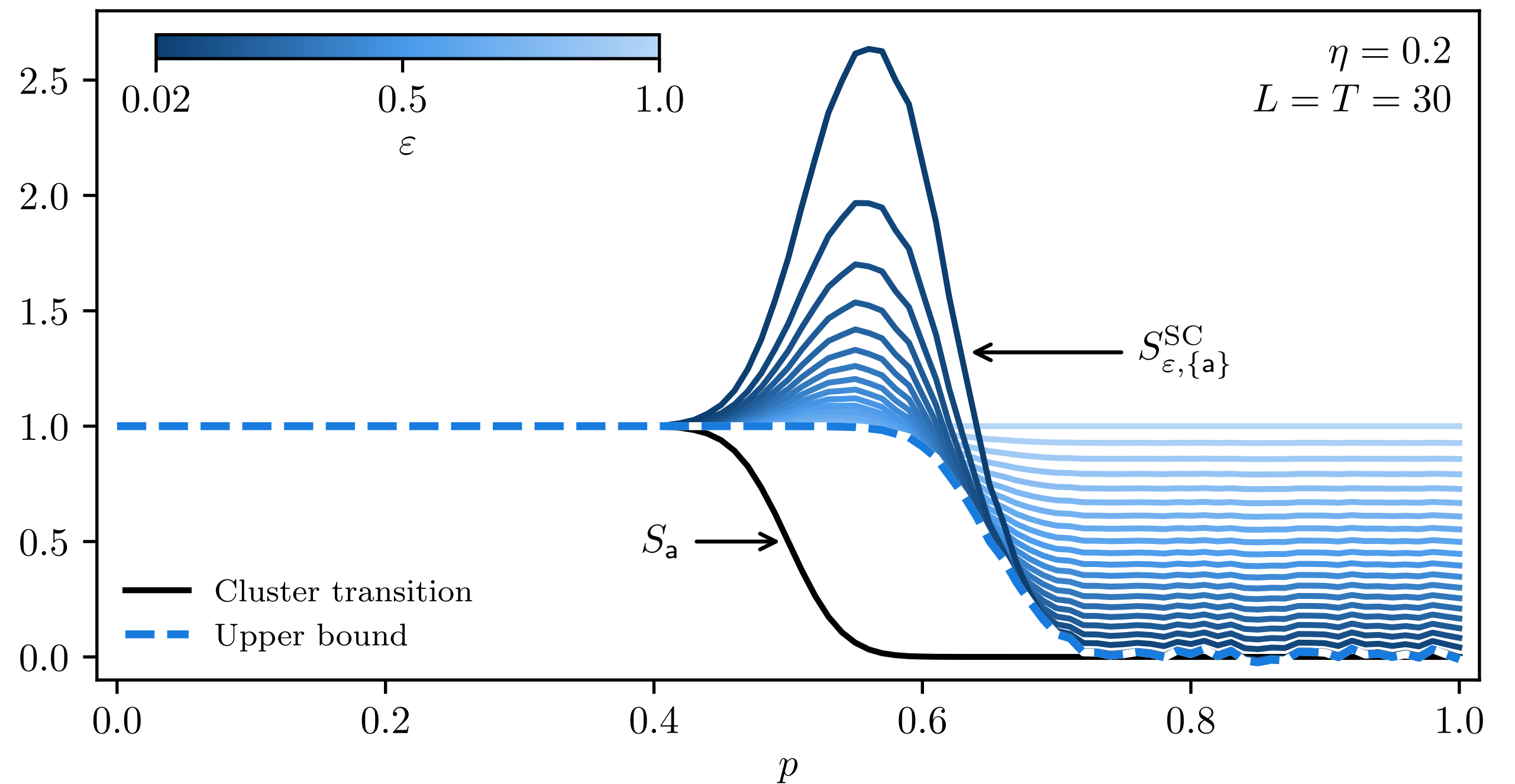
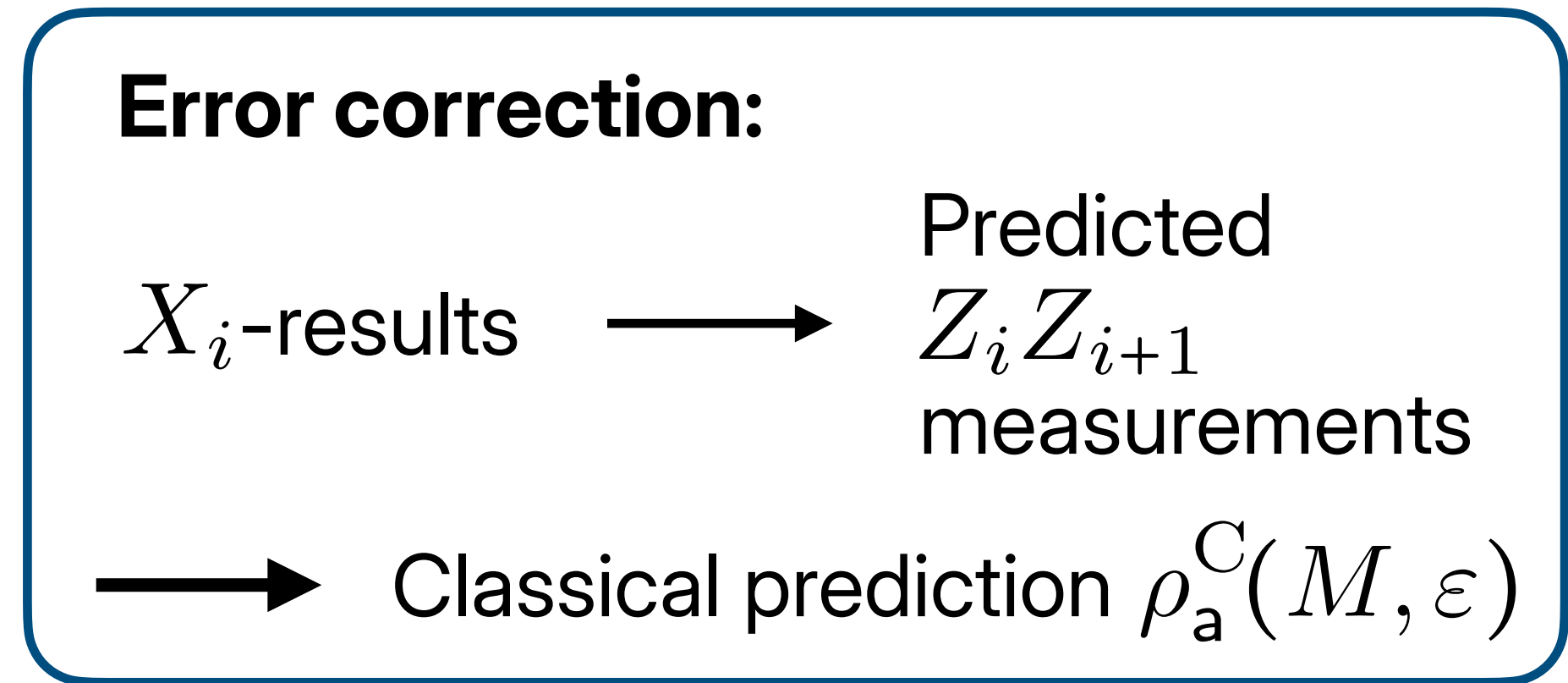
Random shadow  
measurement  
 $O_a \in \{X_a, Y_a, Z_a\}$

Robust state  
prediction  
 $\rho_a^C(M, \varepsilon)$

# Robust state prediction

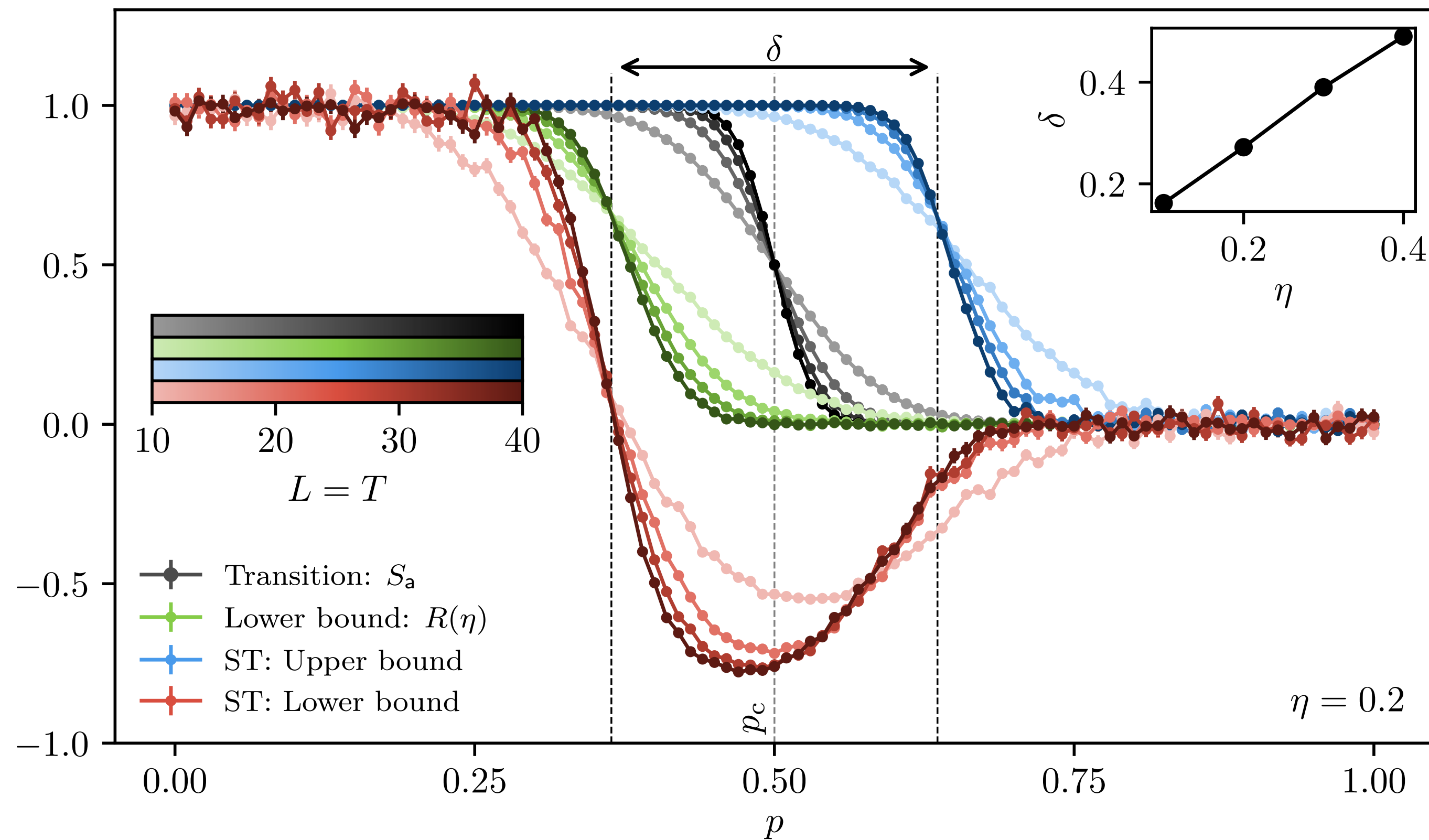


$\eta > 0$



# Summary

## Experimental detection of the PTIM's entanglement transition



- **Accessible lower bound** via decoding
- **Accessible upper bound** via shadow tomography with error correction
- Sharpness  $\delta$  of the bounds measures the noise rate  $\eta$

# Outlook

- This procedure should work for different noise models
  - ➔ If they are symmetric under  $X_1 X_2 \cdots X_L$
  - ➔ Excluding faulty measurements (incorrect outcomes)
- The protocol should work on other models
  - ➔ If they can be simulated efficiently (for state predictions)
  - ➔ If efficient error correction algorithms are known (for robustness)