

# On the asymptotic stabilization of a generalized hyperelastic-rod wave equation

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# Outline

- 1 General setting and physical motivations
- 2 A stabilization problem
- 3 A semigroup of exponentially decaying weak solns
- 4 Hyperelastic-rod wave equation with more general source

## Nonlinear dispersive wave equation

$$\partial_t u - \partial_{txx}^3 u + \partial_x \left( \frac{g(u)}{2} \right) = \gamma \left( 2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u \right),$$

- $t \geq 0$  time
- $x \in \mathbb{R}$  space (one-dimensional)
- $u(t, x) \in \mathbb{R}$  unknown (one-dimensional)
- $\gamma > 0$  is a given constant
- $g: \mathbb{R} \rightarrow \mathbb{R}$  smooth map

# The models

$$g(u) = 3u^2$$

## Hyperelastic-rod wave equation

$$\partial_t u - \partial_{txx}^3 u + 3u\partial_x u = \gamma \left( 2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u \right)$$

- finite length, small amplitude waves
- $u(t, x)$ : radial deformation in cylindrical compressible hyperelastic rod
- $\gamma$ : constant depending on the material and on the pre-stress of the rod

- Dai (1998 - 1998)
- Dai & Huo (2002)

$$g(u) = 2\kappa u + 3u^2, \quad \gamma = 1$$

### Camassa-Holm equation

$$\partial_t u - \partial_{xxx}^3 u + 3u\partial_x u + 2\kappa\partial_x u = \left(2\partial_x u \partial_{xx}^2 u + u\partial_{xxx}^3 u\right)$$

Unidirectional Shallow Water Waves



Depth of the water  $\ll$  Length of the waves

- $u(t, x)$ : wave velocity above the bottom
- flat bottom
- $\kappa > 0$ : water depth

- Camassa & Holm (1993)
- Johnson (2002)

# No (global in time) classical solutions

$$\partial_t u - \partial_{txx}^3 u + \partial_x \left( \frac{g(u)}{2} \right) - \gamma \left( 2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u \right) = 0 \quad (\text{GHR})$$

## Remark

### Solutions to (GHR)

- may produce *wave breaking*: spatial derivatives of sol'ns become unbounded in finite time
- experience presence of *peakons* and *antipeakons*: solitary waves (travelling waves decaying at infinity) with discontinuous first derivative
- when *peakons* and *antipeakons* collide annihilating each other two scenarios are possible:
  - *conservative sol'ns* (a switching phenomena occurs: the waves pass through each other  $\implies$  energy is preserved)
  - *dissipative sol'ns* (total annihilation at collision time: null solution after annihilation  $\implies$  loss of energy)

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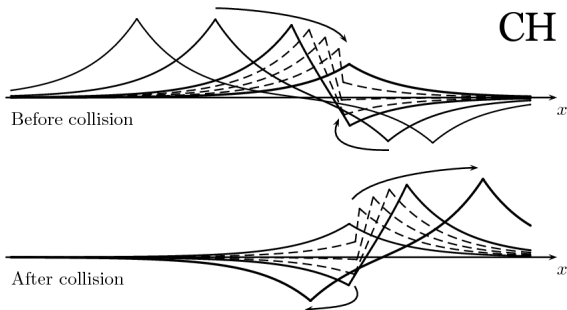
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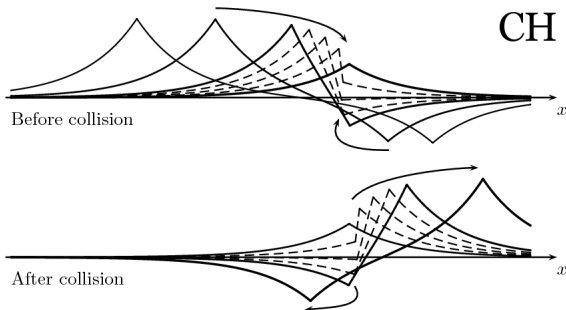
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## Peakons and antipeakons collision for conservative sol'ns:



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The generalized hyperelastic-rod wave equation

$$\partial_t u - \partial_{txx}^3 u + \partial_x \left( \frac{g(u)}{2} \right) - \gamma \left( 2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u \right) = 0 \quad (\text{GHR})$$

rewritten as

$$(1 - \partial_{xx}^2) \partial_t u + \gamma (1 - \partial_{xx}^2) (u \partial_x u) + \partial_x \left( \frac{g(u) - \gamma (u^2 - (\partial_x u)^2)}{2} \right) = 0$$

is **formally** equivalent to the **elliptic-hyperbolic system**

$$\begin{cases} \partial_t u + \gamma \partial_x \left( \frac{u^2}{2} \right) + \partial_x P = 0, \\ -\partial_{xx}^2 P + P = \frac{g(u) - \gamma (u^2 - (\partial_x u)^2)}{2}. \end{cases} \quad (\text{E-H})$$

Since

$$\frac{e^{-|x|}}{2}$$

is the Green's function of the Helmholtz operator  $-\partial_{xx}^2 + 1$ , one can recast the elliptic-hyperbolic system (E-H) as a **balance law** with a **nonlocal source term**

$$\partial_t u + \gamma \partial_x \left( \frac{u^2}{2} \right) + \partial_x P[u] = 0,$$

with

$$P[u] \doteq \frac{e^{-|x|}}{2} * \left( \frac{g(u) - \gamma(u^2 - (\partial_x u)^2)}{2} \right).$$

Notice:

$$u \in H^1(\mathbb{R}) \quad \implies \quad P[u] \in H^1(\mathbb{R})$$

# Weak solutions

Thus we say that a Lipschitz continuous map

$$t \mapsto u(t) \in H^1(\mathbb{R}), \quad t \geq 0,$$

is a **weak solution** of the elliptic-hyperbolic system if it satisfies the equality between functions of  $L^2(\mathbb{R})$

$$\frac{d}{dt}u = -\gamma u \partial_x u - \partial_x P[u], \quad \text{for a.e. } t \geq 0,$$

# Asymptotic Stabilization

Hyperelastic-rod wave equation

$$g(u) = 3u^2$$

## Problem

Find an operator

$$f : H^1(\mathbb{R}) \longrightarrow H^{-1}(\mathbb{R})$$

such that for every initial condition  $u_0 \in H^1(\mathbb{R})$  the solution of the Cauchy problem

$$\begin{cases} \partial_t u - \partial_{xxx}^3 u + 3u \partial_x u = \gamma (2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u) + f[u] \\ u(0, x) = u_0(x) \end{cases}$$

decays as  $t \rightarrow \infty$ , i.e.,

$$\lim_{t \rightarrow \infty} \|u(t)\|_{H^1} = 0.$$

## Goal

Damp the waves on hyperelastic rods

- source term  $f[u] \equiv$  external force

## Literature (on control problems)

- O. Glass (2008): compactly supported, source type feedback,  $H^2$  sol'ns
- V. Perrollaz (2010): boundary feedback,  $H^2$  solutions

## $H^1$ Weak solutions

- Exhibit unbounded and discontinuous spatial derivatives
- Solitary waves: peakons and antipeakons
- Interactions of peakons and antipeakons may occur



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## Our feedback law

$$f[u] = -\lambda(1 - \partial_{xx}^2)u, \quad \lambda > 0$$

$$\partial_t u - \partial_{xxx}^3 u + 3u\partial_x u = \gamma \left( 2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u \right) - \lambda(1 - \partial_{xx}^2)u$$

$$\Downarrow$$

$$\begin{cases} \partial_t u + \gamma u \partial_x u + \partial_x P = -\lambda u \\ -\partial_{xx}^2 P + P = \frac{3-\gamma}{2} u^2 + \frac{\gamma}{2} (\partial_x u)^2 \end{cases}$$

$$\Downarrow$$

$$\frac{d}{dt} u = -\gamma u \partial_x u - \partial_x P[u] - \lambda u$$

$$P[u] \doteq \frac{e^{-|x|}}{2} * \left( \frac{3-\gamma}{2} u^2 + \frac{\gamma}{2} (\partial_x u)^2 \right)$$

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$$P[u] \doteq \frac{e^{-|x|}}{2} * \left( \frac{3-\gamma}{2} u^2 + \frac{\gamma}{2} (\partial_x u)^2 \right)$$

# Formal Energy Estimate

$$\begin{cases} \partial_t u + \gamma u \partial_x u + \partial_x P = -\lambda u \\ -\partial_{xx}^2 P + P = \frac{3-\gamma}{2} u^2 + \frac{\gamma}{2} (\partial_x u)^2 \end{cases}$$

$$\Downarrow$$

$$\partial_t \left( \frac{u^2 + (\partial_x u)^2}{2} \right) + \partial_x \left( \frac{\gamma}{2} u (\partial_x u)^2 - \frac{1-\gamma}{2} u^3 + uP \right) = -\lambda (u^2 + (\partial_x u)^2)$$

The total energy

$$E(t) := \|u(t, \cdot)\|_{H^1(\mathbb{R})}^2 = \int_{\mathbb{R}} \left( u(t, x)^2 + (\partial_x u(t, x))^2 \right) dx$$

satisfies the following ordinary differential equation

$$\frac{d}{dt} E(t) = -2\lambda E(t)$$

and therefore

$$E(t) = E(0) e^{-2\lambda t}, \quad t \geq 0.$$

## Definition 1 (Weak Dissipative Solutions)

A function  $u : [0, \infty) \times \mathbb{R} \rightarrow \mathbb{R}$  is a **weak dissipative solution** of the Cauchy problem

$$\begin{cases} \partial_t u - \partial_{xxx}^3 u + 3u\partial_x u = \gamma (2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u) u - \lambda(1 - \partial_{xx}^2)u \\ u(0, x) = u_0(x) \end{cases}$$

if

- $u = u(t, x)$  is Hölder continuous;
- $u(t, \cdot) \in H^1(\mathbb{R})$  at every  $t \in [0, \infty)$ ;
- $t \mapsto u(t, \cdot)$  is Lipschitz continuous from  $[0, \infty)$  into  $L^2(\mathbb{R})$ , satisfies the initial condition and the following equality between functions in  $L^2(\mathbb{R})$ :

$$\frac{d}{dt} u = -\gamma u \partial_x u - \partial_x P[u] - \lambda u, \quad \text{for a.e. } t \in [0, \infty).$$

- Oleinik type inequality: there exists  $C = C(\|u_0\|_{H^1})$  s.t.

$$\partial_x u(t, x) \leq C(1 + t^{-1}) \quad t > 0$$

## The Main Result (F.A. &amp; G.M. Coclite, 2014)

Let  $\gamma, \lambda > 0$  be fixed. There exists a semigroup

$$S : [0, \infty) \times H^1(\mathbb{R}) \longrightarrow H^1(\mathbb{R}), \quad (t, u_0) \mapsto S_t u_0$$

such that the following properties hold.

- For every  $u_0 \in H^1(\mathbb{R})$ ,  $u(t, x) \doteq S_t(u_0)(x)$  is a weak dissipative solution of

$$\begin{cases} \partial_t u - \partial_{txx}^3 u + 3u \partial_x u = \gamma (2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u) u - \lambda(1 - \partial_{xx}^2)u, \\ u(0, x) = u_0(x). \end{cases}$$

- $E(t) \leq E(0)e^{-2\lambda t}$ ,  $t \geq 0$ .
- For every  $\{u_{0,n}\}_n \subset H^1(\mathbb{R})$  and  $u_0 \in H^1(\mathbb{R})$

$$u_{0,n} \longrightarrow u_0 \text{ in } H^1(\mathbb{R}) \implies S(u_{0,n}) \longrightarrow S(u_0) \text{ in } L_{loc}^\infty((0, \infty) \times \mathbb{R}).$$

## Remark

- **Semigroup of solutions**
  - no uniqueness of weak solutions established so far (within dissipative sol'ns)
  - solitons interaction may occur
- **Oleinik type estimate**
  - $\partial_x u$  is bounded from above
  - $\partial_x u$  may go to  $-\infty$
- $S$  is **not continuous** as a map with values in  $H^1$  (even  $t \mapsto S_t u_0$  may fail to be continuous as a map with values in  $H^1$  due to the complete annihilation of peakons and antipeakons of the same strength when they collide).
- **Energy exponential decay**



## General strategy

- We introduce a **new set of independent and dependent variables** which yield a **semilinear system** of ODEs in a Banach space.
- **Local existence** of solutions for the semilinear system as fixed points of a contraction.
- An energy estimate gives the **global existence** of solutions for the semilinear system.
- **Continuous dependence** with respect to the initial conditions for the semilinear system.
- We come back to the **original variables** and prove our result.

- Semigroup of dissipative solns for CH  
Bressan & Constantin (Anal. & Appl. - 2007)

## New independent variable

**Energy variable**  $\xi \in \mathbb{R}$ .

Assume  $u_0 \in H^1(\mathbb{R})$ . The map

$$y \in \mathbb{R} \mapsto \int_0^y \left(1 + (\partial_x u_0)^2\right) dx$$

is continuous, increasing, and goes to  $\pm\infty$  as  $y \rightarrow \pm\infty$ . So we can define implicitly the function  $y_0 = y_0(\xi)$  by the relation

$$\int_0^{y_0(\xi)} \left(1 + (\partial_x u_0)^2\right) dx = \xi, \quad \xi \in \mathbb{R}.$$

- $\xi$  plays the role of a **Lagrangian variable** (it is constant along characteristics)

# New dependent variables

**Characteristic curve**  $t \mapsto y(t, \xi)$

$$\partial_t y(t, \xi) = \gamma u(t, y(t, \xi)), \quad y(0, \xi) = y_0(\xi).$$

**Notation**

$$u(t, \xi) := u(t, y(t, \xi)), \quad P(t, \xi) := P(t, y(t, \xi)).$$

**New variables**  $v = v(t, \xi)$  and  $q = q(t, \xi)$

$$v := 2 \arctan(\partial_x u), \quad q := (1 + (\partial_x u)^2) \partial_\xi y.$$

- $v$  is bounded ( $v \rightarrow -\pi$  as  $\partial_x u \rightarrow -\infty$ )
- $q \geq 0$

The semilinear system for  $u = u(t, \xi)$ ,  $v = v(t, \xi)$ ,  $q = q(t, \xi)$

$$\begin{cases} \partial_t u = -\partial_x P - \lambda u \\ \partial_t v = \left( \frac{3-\gamma}{2} u^2 - P \right) (1 + \cos(v)) - \gamma \sin^2\left(\frac{v}{2}\right) - \lambda \sin(v) \\ \partial_t q = \left( \frac{3-\gamma}{2} u^2 - P + \frac{\gamma}{2} \right) \sin(v) q - 2\lambda \sin^2\left(\frac{v}{2}\right) q \\ u(0, \xi) = u_0(y_0(\xi)) \\ v(0, \xi) = 2 \arctan(\partial_x u_0(y_0(\xi))) \\ q(0, \xi) = 1 \end{cases}$$

can be regarded as an ODE in the Banach space

$$X \doteq H^1(\mathbb{R}) \times (L^2(\mathbb{R}) \cap L^\infty(\mathbb{R})) \times L^\infty(\mathbb{R}).$$

The nonlocal term  $P(t, \xi) \doteq P[u, v, q](t, \xi)$

$$\begin{aligned}
 P(t, \xi) &= \frac{1}{2} \int_{\mathbb{R}} e^{-\left| \int_{\xi}^{\xi'} \cos^2 \left( \frac{v(t,s)}{2} \right) ds \right|} \times \\
 &\quad \times \left( \frac{3-\gamma}{2} u(t, \xi')^2 \cos^2 \left( \frac{v(t, \xi')}{2} \right) + \frac{\gamma}{2} \sin^2 \left( \frac{v(t, \xi')}{2} \right) \right) \times \\
 &\quad \times q(t, \xi') d\xi',
 \end{aligned}$$

$$\begin{aligned}
 \partial_x P(t, \xi) &= \frac{1}{2} \int_{\mathbb{R}} e^{-\left| \int_{\xi}^{\xi'} \cos^2 \left( \frac{v(t,s)}{2} \right) ds \right|} \times \\
 &\quad \times \text{sign}(\xi - \xi') \times \\
 &\quad \times \left( \frac{3-\gamma}{2} u(t, \xi')^2 \cos^2 \left( \frac{v(t, \xi')}{2} \right) + \frac{\gamma}{2} \sin^2 \left( \frac{v(t, \xi')}{2} \right) \right) \times \\
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In order to obtain global **dissipative** solutions, a modification of the system for  $u$ ,  $v$ ,  $q$  is needed.

Assume that, along a given characteristic  $t \mapsto y(t, \xi)$ , the wave breaks at a first time  $t = \tau(\xi)$ . Arguing as for the Burgers equation and reminding that  $\partial_x u$  satisfies an **Oleinik** type inequality, the wave break means  $\partial_x u(t, \xi) \rightarrow -\infty$ , as  $t \rightarrow \tau(\xi)^-$ .

For all  $t \geq \tau(\xi)$  we then set  $v(t, \xi) \equiv -\pi$  and remove the values of  $u(t, \xi)$ ,  $v(t, \xi)$ ,  $q(t, \xi)$  from the computation of nonlocal terms  $P$  and  $\partial_x P$ .

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The **dissipative** semilinear system for  $u = u(t, \xi)$ ,  $v = v(t, \xi)$ ,  $q = q(t, \xi)$

$$\left\{ \begin{array}{l} \partial_t u = -\partial_x P - \lambda u \\ \partial_t v = \begin{cases} \left( \frac{3-\gamma}{2} u^2 - P \right) (1 + \cos(v)) - \gamma \sin^2\left(\frac{v}{2}\right) - \lambda \sin(v) & \text{if } v > -\pi \\ 0 & \text{if } v \leq -\pi \end{cases} \\ \partial_t q = \begin{cases} \left( \frac{3-\gamma}{2} u^2 - P + \frac{\gamma}{2} \right) \sin(v)q - 2\lambda \sin^2\left(\frac{v}{2}\right) q & \text{if } v > -\pi \\ 0 & \text{if } v \leq -\pi \end{cases} \\ u(0, \xi) = u_0(y_0(\xi)) \\ v(0, \xi) = 2 \arctan(\partial_x u_0(y_0(\xi))) \\ q(0, \xi) = 1 \end{array} \right.$$

Notice: r.h.s. **ODE is discontinuous**

The **dissipative** nonlocal terms  $P, \partial_x P$  are also discontinuous

$$\begin{aligned}
 P(t, \xi) &= \frac{1}{2} \int_{\{v(\xi') > -\pi\}} e^{-\left| \int_{\{\xi' \leq \xi, v(\xi') > -\pi\}} \cos^2\left(\frac{v(t,s)}{2}\right) q(t,s) ds \right|} \times \\
 &\quad \times \left( \frac{3-\gamma}{2} u(t, \xi')^2 \cos^2\left(\frac{v(t, \xi')}{2}\right) + \frac{\gamma}{2} \sin^2\left(\frac{v(t, \xi')}{2}\right) \right) \times \\
 &\quad \times q(t, \xi') d\xi',
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 \partial_x P(t, \xi) &= \frac{1}{2} \int_{\{v(\xi') > -\pi\}} e^{-\left| \int_{\{\xi' \leq \xi, v(\xi') > -\pi\}} \cos^2\left(\frac{v(t,s)}{2}\right) q(t,s) ds \right|} \times \\
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 &\quad \times q(t, \xi') d\xi'.
 \end{aligned}$$

## Remark

- We regard the dissipative semilinear system as an ODE on the Banach space  $X \doteq L^\infty(\mathbb{R}; \mathbb{R}^3)$ .
- The r.h.s. of the ODE is discontinuous and discontinuity occurs along the plane  $v = -\pi$ .
- The second equation of the system implies that  $v$  approaches the value  $-\pi$  transversally, i.e.  $\partial_t v \approx -\gamma \implies$  r.h.s of ODE is transversal to plane  $v = -\pi$ . This transversality condition guarantees well-posedness of the system.

# Global existence and uniqueness for the semilinear system

## Local existence and uniqueness

- General thms on directionally continuous ODEs in functional spaces do not apply (r.h.s. has unbounded variation in the direction of a cone in  $L^\infty$ )
- Ad hoc analysis for discontinuous ODEs with non local terms as in: Bressan & Shen - 2006

## Global existence

- Energy estimate
- Global bound on the total energy

$$\begin{aligned}
 E(t) &= \|u(t, \cdot)\|_{H^1(\mathbb{R})}^2 = \int_{\mathbb{R}} \left( u(t, x)^2 + (\partial_x u(t, x))^2 \right) dx \\
 &= \int_{\{v(t, \xi) > -\pi\}} \left( u^2(t, \xi) \cos^2 \left( \frac{v(t, \xi)}{2} \right) + \sin^2 \left( \frac{v(t, \xi)}{2} \right) \right) q(t, \xi) d\xi
 \end{aligned}$$

## Stability for the semilinear system

**Remark:** local existence by fixed point argument in  $L^\infty$  yields continuous dependence of sol'ns w.r.t. convergence of initial data in  $L^\infty$ .

**However:** introducing a suitable distance functional  $\Gamma$  s.t.

$$\Gamma((u, v, q), (\tilde{u}, \tilde{v}, \tilde{q})) \geq \|u - \tilde{u}\|_{L^\infty(\mathbb{R})},$$

$$u_n \longrightarrow u \quad \text{in } H^1(\mathbb{R}) \quad \implies \quad \Gamma((u_n, v_n, q_n), (u, v, q)) \longrightarrow 0,$$

and providing a priori bounds on the time increase of  $\Gamma$  along two sol'ns of semilinear dissipative system we derive

### Theorem

Let  $\{u_{0,n}\}_n \subset H^1(\mathbb{R})$  and  $u_0 \in H^1(\mathbb{R})$ . If

$$u_{0,n} \longrightarrow u_0 \quad \text{in } H^1(\mathbb{R}),$$

then

$$u_n \longrightarrow u \quad \text{in } L^\infty((0, T) \times \mathbb{R}) \text{ for every } T > 0,$$

where  $u_n$  and  $u$  are (1st components of) the sol'ns of the semilinear dissipative system with initial data  $u_{0,n}$  and  $u_0$ , respectively.

# Global Dissipative Solutions in the Original Variables

$$u = u(t, x), \quad P = P(t, x)$$

Let  $(u, v, q)$  be the solution of the **semilinear** system.

Define

$$y(t, \xi) = y_0(\xi) + \int_0^t u(\tau, \xi) d\tau.$$

For each fixed  $\xi$ , the function  $t \mapsto y(t, \xi)$  solves

$$\partial_t y(t, \xi) = \gamma u(t, \xi), \quad y(0, \xi) = y_0(\xi).$$

We set

$$u(t, x) = u(t, \xi) \quad \text{if } y(t, \xi) = x.$$

Clearly

$$u(0, x) = u_0(x) \quad x \in \mathbb{R}.$$

## The facts

- the energy estimate on  $\|u(t, \cdot)\|_{H^1(\mathbb{R})}$
- the image of the singular set where  $v = -\pi$  has measure zero (in the  $x$ -variable), i.e.,

$$\text{meas}(\{y(t, \xi); v(t, \xi) = -\pi\}) = 0 \quad \forall t > 0$$

give that

- $u = u(t, x)$  is Hölder continuous
- $t \mapsto u(t, \cdot) \in L^2(\mathbb{R})$  is Lipschitz continuous
- $\frac{d}{dt}u = -\gamma u \partial_x u - \partial_x P - \lambda u$ .

Moreover

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## Generalized hyperelastic-rod wave equation with source

$$\partial_t u - \partial_{txx}^3 u + \partial_x \left( \frac{g(u)}{2} \right) = \gamma \left( 2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u \right) + f(t, x, u),$$

- $(t, x) \in \mathbb{R}^+ \times \mathbb{R}$
- $u(t, x) \in \mathbb{R}$
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- $g : \mathbb{R} \rightarrow \mathbb{R}$  smooth map,  $|g(u)| \leq M|u|^2 \quad \forall u$
- $f : \mathbb{R}^+ \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  smooth map,

$$|f(\cdot, \cdot, u)|, |\partial_t f(\cdot, \cdot, u)| \leq L|u|, \quad |\partial_u f(\cdot, \cdot, u)| \leq L \quad \forall u$$

**Applications:** Analyze controllability and stabilizability problems where  $f(t, x, u)$  is treated as a distributed control.

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The generalized hyperelastic-rod wave equation with source

$$\partial_t u - \partial_{txx}^3 u + \partial_x \left( \frac{g(u)}{2} \right) - \gamma \left( 2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u \right) = f(t, x, u) \quad (\text{GHR})_f$$

rewritten as

$$(1 - \partial_{xx}^2) \partial_t u + \gamma (1 - \partial_{xx}^2) (u \partial_x u) + \partial_x \left( \frac{g(u) - \gamma (u^2 - (\partial_x u)^2)}{2} \right) = f(t, x, u)$$

is **formally** equivalent to the **elliptic-hyperbolic system**

$$\begin{cases} \partial_t u + \gamma \partial_x \left( \frac{u^2}{2} \right) + \partial_x P = F, \\ -\partial_{xx}^2 P + P = \frac{g(u) - \gamma (u^2 - (\partial_x u)^2)}{2}, \\ -\partial_{xx}^2 F + F = f(t, x, u). \end{cases} \quad (\text{E-H})_f$$

## Definition 2 (Weak Dissipative Solutions)

A function  $u : [0, \infty) \times \mathbb{R} \rightarrow \mathbb{R}$  is a **weak dissipative solution** of

$$\begin{cases} \partial_t u - \partial_{txx}^3 u + \partial_x \left( \frac{g(u)}{2} \right) - \gamma (2\partial_x u \partial_{xx}^2 u + u \partial_{xxx}^3 u) = f(t, x, u) \\ u(0, x) = u_0(x) \end{cases} \quad x \in \mathbb{R}, t \geq 0,$$

if

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Moreover (higher integrability):

$$\partial_x u \in L_{loc}^p([0, \infty) \times \mathbb{R}) \quad \forall 1 \leq p < 3$$

**Goal:** Analyze stabilizability properties for **distributed control  $f$  supported on a subset of  $\mathbb{R}$**  (damp the waves of hyperelastic rods by an external force  $f$ ).

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Consider the **elliptic-parabolic approximation** of the (E-H)<sub>f</sub> system:

$$\begin{cases} \partial_t u_\varepsilon + \gamma u_\varepsilon \partial_x u_\varepsilon + \partial_x P_\varepsilon = F_\varepsilon + \varepsilon \partial_{xx}^2 u_\varepsilon, \\ -\partial_{xx}^2 P_\varepsilon + P_\varepsilon = \frac{g(u_\varepsilon) - \gamma (u_\varepsilon^2 - (\partial_x u_\varepsilon)^2)}{2}, \\ -\partial_{xx}^2 F_\varepsilon + F_\varepsilon = f(t, x, u_\varepsilon), \end{cases} \quad t > 0, \quad x \in \mathbb{R}, \quad (\text{E-H})_{f,\varepsilon}$$

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#### Well-posedness of (E-H)<sub>f,ε</sub>

- Existence and uniqueness of smooth sol'ns with  $u_\varepsilon(0, \cdot) \in H^1(\mathbb{R})$
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which is equivalent to the fourth order equation

$$\begin{aligned} \partial_t u_\varepsilon - \partial_{txx}^3 u_\varepsilon + \partial_x \left( \frac{g(u_\varepsilon)}{2} \right) \\ = \gamma (2\partial_x u_\varepsilon \partial_{xx}^2 u_\varepsilon + u_\varepsilon \partial_{xxx}^3 u_\varepsilon) + f(t, x, u_\varepsilon) + \varepsilon (\partial_{xx}^2 u_\varepsilon - \partial_{xxxx}^4 u_\varepsilon). \end{aligned}$$

### Well-posedness of (E-H)<sub>f,ε</sub>

- Existence and uniqueness of smooth sol'ns with  $u_\varepsilon(0, \cdot) \in H^1(\mathbb{R})$
- Lipschitz continuity w.r.t.  $\gamma, g, f$  and initial data  $u_\varepsilon(0, \cdot)$ .

[Coclite, Holden and Karlsen, 2005]

# Compactness - Existence of solutions

Given  $u_0 \in H^1(\mathbb{R})$ , consider:

$$\{u_{\varepsilon,0}\}_{\varepsilon>0} \subset C^\infty(\mathbb{R}), \quad \|u_{\varepsilon,0}\|_{H^1(\mathbb{R})} \leq \|u_0\|_{H^1(\mathbb{R})}, \quad \varepsilon > 0, \quad u_{\varepsilon,0} \rightarrow u_0 \text{ in } H^1(\mathbb{R}).$$

Let  $u_\varepsilon : [0, \infty) \times \mathbb{R} \rightarrow \mathbb{R}$  be:

$$\text{solution of (E-H)}_{f,\varepsilon} \quad \text{with} \quad u_\varepsilon(0, \cdot) = u_{\varepsilon,0}$$

Prove compactness of  $\{u_\varepsilon\}_{\varepsilon>0}$  and show  $\exists u \in L^\infty_{loc}([0, \infty); H^1(\mathbb{R}))$  s.t.

- strong convergence:

$$u_\varepsilon \longrightarrow u \text{ in } L^\infty([0, T]; H^1(\mathbb{R})) \quad \forall T > 0,$$

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Compactness of  $\{u_\varepsilon\}_{\varepsilon>0}$ 

$$|f(\cdot, \cdot, u)|, |\partial_t f(\cdot, \cdot, u)| \leq L|u|, \quad |\partial_u f(\cdot, \cdot, u)| \leq L \quad \forall u$$

## Energy estimates:

$$\|u_\varepsilon(t, \cdot)\|_{H^1(\mathbb{R})}^2 + 2\varepsilon e^{2Lt} \int_0^t e^{-2Ls} \|\partial_x u_\varepsilon(s, \cdot)\|_{H^1(\mathbb{R})}^2 ds \leq e^{2Lt} \|u_0\|_{H^1(\mathbb{R})}^2 \quad \forall t \geq 0.$$

Oleřnik type estimates:  $\forall T > 0, \exists C_T = C_T(\|u_0\|_{H^1}, \gamma, g, L, T)$  s.t.

$$\partial_x u_\varepsilon(t, x) \leq \frac{2}{\gamma t} + C_T \quad \forall t \in ]0, T], x \in \mathbb{R}.$$

Higher integrability:  $\forall a, b, T > 0, \exists K_{a,b,T} = K_{a,b,T}(\|u_0\|_{H^1}, a, b, T)$  s.t.

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Equation for first derivative  $q_\varepsilon = \partial_x u_\varepsilon$ :

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Thanks to higher integrability estimates  $\exists \{\varepsilon_j\}_{j \in \mathbb{N}}$ ,  $\varepsilon_j \rightarrow 0$ , s.t.:

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Thank you for your attention!