Measure of the compactifying effect of conservation laws

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I. Introduction. Systems of conservation laws

▶ We consider the class of hyperbolic systems of conservation laws :

$$u_t + f(u)_x = 0 \text{ for } (t, x) \in \mathbb{R}^+ imes \mathbb{R},$$

 $u : \mathbb{R}^+ imes \mathbb{R} o \mathbb{R}^d \text{ and } f : \Omega \subset \mathbb{R}^d o \mathbb{R}^d,$

where for any $u \in \Omega$:

df(u) has d distinct and real eigenvalues $\lambda_1 < \cdots < \lambda_n$.

Denote $(r_i(u))$ a family of corresponding eigenvectors of df(u).

- This class appears in many applications : gas dynamics (Euler equations), shallow-water flows (Saint-Venant equations), chromatography, traffic flows, etc.
- It is frequent to add conditions the characteristic fields. One says that (λ_i, r_i) is genuinely nonlinear/linearly degenerate when :

 $\forall u \in \Omega, \ r_i(u) \cdot \nabla \lambda_i(u) \neq 0 \ / \ \forall u \in \Omega, \ r_i(u) \cdot \nabla \lambda_i(u) = 0.$

A (much) simpler particular case : scalar conservation laws

• (1-D) scalar conservation laws correspond to d = 1:

$$u_t + f(u)_x = 0$$
 for $(t, x) \in \mathbb{R}^+ \times \mathbb{R}$,
 $u_{|t=0} = u_0$ on \mathbb{R} ,

where

$$u: \mathbb{R}^+ \times \mathbb{R} \to \mathbb{R}$$
 and $f: \mathbb{R} \to \mathbb{R}$.

- We will mainly consider the case where the flux f is of class C² (though frequently, Lipschitz is sufficient).
- Genuine nonlinearity condition is transformed here into strict uniform convexity :

$$f'' \ge a > 0.$$

Singularities, entropy conditions

It is quite classical (and easy to see using characteristics) that in general the solutions of this equation become singular in finite time.



It is hence natural to consider possibly discontinuous weak solutions. But in this framework uniqueness is lost.

Entropy conditions

- One introduces then entropy conditions :
 - Vanishing viscosity condition : one requires that solutions can be obtained by vanishing viscosity : u is limit of u^ε, ε → 0⁺, where :

$$u_t^{\varepsilon} + f(u^{\varepsilon})_x - \varepsilon u_{xx}^{\varepsilon} = 0.$$

2. One introduces the entropy couples $(\eta, q) : \Omega \to \mathbb{R}^2$ as functions that satisfy :

$$dq = d\eta df$$
.

One requires that for all (η, q) with η convex, u satisfies :

 $\eta(u)_t + q(u)_x \leq 0$ in the sense of measures.

3. Conditions on the speed of propagation of discontinuities. Given a discontinuity separating u_l on the left and u_r on the right, moving at speed s given by Rankine-Hugoniot relations :

$$f(u_r)-f(u_l)=s(u_r-u_l),$$

one introduces Lax's inequalities :

$$\lambda_i(u_r) < s < \lambda_i(u_l),$$

so in the convex scalar case this gives :

$$u_l \geq u_r$$
.

- All these conditions are essentially equivalent in the convex/GNL case.
- Regular solutions are in particular entropy solutions.

A general question

Some of these systems present a form of nonlinear regularization mechanism.

- Many references on the subject in the scalar case : Lax, Dafermos, Lions-Perthame-Tadmor, Jabin-Perthame, De Lellis-Westdickenberg, Cheverry, etc.
- The goal of this talk is not to prove of a new regularization property, but to try to describe the compactification effect of this type of equations, which is of course connected to this regularizing effect.

II. Simplest case : convex scalar equations

Different authors, in particular E. Hopf, P.D. Lax and O. Oleinik, have shown global existence and uniqueness of an entropy solution for initial data in L¹ ∩ L[∞] (or even L¹), with

 $\|u(t)\|_{L^1} \le \|u(0)\|_{L^1}, \ \|u(t)\|_{L^{\infty}} \le \|u(0)\|_{L^{\infty}} \text{ and } TV(u(t)) \le TV(u(0)).$

Moreover, P.D. Lax has shown a regularizing effect of the associated nonlinear semi-group S(t). More precisely, given a bounded set B ⊂ L¹(ℝ) and R > 0, one has :

 $\left\{(S(t)u_0)_{|(-R,R)}, \ u_0 \in B\right\} \text{ is relatively compact in } L^1(-R,R).$

► The following question was raised by P.D. Lax in 2002 :

Is it possible to give a quantitative estimate of this regularizing effect ?

In 2005, C. De Lellis and F. Golse gave an answer to this question by using the notion of ε-entropy (a.k.a. Kolmogorov's entropy).

Kolmogorov's entropy

Definition

Let (X, d) a metric space, and let K a totally bounded subset of X. We call an ε -covering of K, a covering of K by subsets of diameter no more than 2ε .

Let $N_{\varepsilon}(K)$ the minimal number of subsets in an ε -covering of K. The ε -entropy of K is defined as

$$H_{\varepsilon}(K \mid X) \doteq \log_2 N_{\varepsilon}(K).$$

Example. $H_{\varepsilon}([0, L]^n | \mathbb{R}^n) \sim -n \log_2(\varepsilon)$ as $\varepsilon \to 0^+$ (whatever L and the norm...)

Higher bound for the ε -entropy

Theorem (De Lellis-Golse, 2005) For L > 0, m > 0 and M > 0, one defines

 $\mathcal{C}_{L,m,M} := \big\{ u_0 \in L^\infty(\mathbb{R}) \ / \ \text{Supp} \ u_0 \subset [-L,L], \ \|u_0\|_{L^1} \le m, \ \|u_0\|_{L^\infty} \le M \big\}.$

Then for T > 0 and $\varepsilon > 0$ sufficiently small, the ε -entropy of $S(T)C_{L,m,M}$ in $L^1(\mathbb{R})$ satisfies

$$H_{\varepsilon}(S(T)\mathcal{C}_{L,m,M} \mid L^{1}(\mathbb{R})) \leq \frac{4}{\varepsilon} \left(\frac{4L(T)^{2}}{a T} + 4L(T)\sqrt{\frac{2m}{a T}} \right),$$

with

$$L(T) \doteq L + 2 c_M \sqrt{2mT/a}$$
 where $c_M \doteq \max_{[-M,M]} f''$.

(Reminder : a is such that $f'' \ge a > 0$.)

Above, L(T) is an estimate of the support width at time T.

Lower bound for the ε -entropy

Theorem (Ancona-G.-Nguyen, 2012) For L > 0, m > 0 and M > 0, one defines as before $C_{L,m,M} \doteq \{u_0 \in L^{\infty}(\mathbb{R}) \mid Supp \, u_0 \subset [-L, L], \|u_0\|_{L^1} \le m, \|u_0\|_{L^{\infty}} \le M\}.$ Then for T > 0 and $\varepsilon > 0$ sufficiently small, the ε -entropy of

Then for T > 0 and $\varepsilon > 0$ sufficiently small, the ε -entropy of $S(T)C_{L,m,M}$ in $L^1(\mathbb{R})$ satisfies

$$H_{\varepsilon}(S(T)\mathcal{C}_{L,m,M} \mid L^1(\mathbb{R})) \geq rac{1}{arepsilon} rac{L^2}{48 \ln(2) \mid f''(0) \mid T}.$$

Remarks

As a consequence one has

$$H_{\varepsilon}(S(T)\mathcal{C}_{L,m,M} | L^{1}(\mathbb{R})) \approx \frac{1}{\varepsilon}.$$

A motivation for P.D. Lax's question is numerical analysis of these equations. Indeed, the result above gives an idea of the complexity of a numerical scheme for such an equation (whatever its nature).

A scheme with precision ε in L^1 norm must use at least $\mathcal{O}(\frac{1}{\varepsilon})$ operations...

III. Extensions.

1. Conservation laws with source term

A generalization of scalar conservation laws consist in scalar conservation laws with source term :

$$u_t + f(u)_x = g(t, x, u),$$

where f is as before and g is a source term of class C^1 , with at most linear growth at infinity.

- ► Under reasonable assumptions, S. N. Kruzkov has shown global existence and uniqueness of an entropy solution for initial data u₀ ∈ L[∞]. (Kruzkov's result is actually much more general !)
- One can have in mind a flow in presence of external force, in non-flat channels, etc.
- We denote E(t) the evolution operator which maps u_0 into u(t).

Assumptions

In what follows one supposes that :

 $\begin{array}{l} \forall \ (t,x) \in \mathbb{R}^+ \times \mathbb{R}, \qquad g(t,x,0) = 0, \\ \exists \ C > 0 \ \text{t.q.} \ \forall \ (t,x,u) \in \mathbb{R}^+ \times \mathbb{R} \times \mathbb{R}, \ |g_x(t,x,u)| \leq C|u|, \\ \exists \ \omega \in L^1_{loc}(\mathbb{R}^+) \ \text{t.q. p.p. tout} \ t \in \mathbb{R}^+, \ \forall \ (x,u) \in \mathbb{R}^2, \ |g_u(t,x,u)| \leq \omega(t). \end{array}$

The first condition ensures that for a compactly supported initial data, the corresponding solution remains compactly supported for all times.

It can be replaced in what follows by : g is independent of x and

$$g(\cdot,0)\in L^1_{loc}(\mathbb{R}^+),$$

and obtain a similar result.

Higher ε -entropy bound for conservation laws with source term

Theorem (ibid.)

Under the above assumptions, for T>0 and for $\varepsilon>0$ sufficiently small, one has :

$$H_{\varepsilon}(E(T)(\mathcal{C}_{L,m,M}) | L^{1}(\mathbb{R})) \leq \frac{1}{\varepsilon} \frac{8 L_{T}^{2} \left(1 + 2(1 + aT^{2}K) \exp\left(\|\omega\|_{L^{1}}\right)\right)}{aT},$$

where

$$\mathcal{K}\doteq \maxig\{|g_x(s,x,u)|\,;\,\,(s,x)\in\Delta,\,\,u\in[-M_{\mathcal{T}},M_{\mathcal{T}}]ig\},$$

with

$$M_{\mathcal{T}} \doteq \exp\left(\|\omega\|_{L^1}\right) M, \ \ L_{\mathcal{T}} \doteq L + \|f''\|_{L^{\infty}(-M_{\mathcal{T}}, M_{\mathcal{T}})} M_{\mathcal{T}} T,$$

$$\Delta \doteq \Big\{ (s, x) \, | \, s \in [0, T], \\ -L_T - (T - s) \, \|f'\|_{L^{\infty}(-M_T, M_T)} \le x \le L_T + (T - s) \, \|f'\|_{L^{\infty}(-M_T, M_T)} \Big\}.$$

Lower $\varepsilon\text{-entropy}$ bounds for conservation laws with source term

Theorem (ibid.)

Under the above assumptions, for T>0 and for $\varepsilon>0$ sufficiently small, one has :

$$H_{\varepsilon}(E(T)(\mathcal{C}_{L,m,M}) | L^{1}(\mathbb{R})) \geq \frac{1}{\varepsilon} \frac{L^{2} \exp\left(-\|\omega\|_{L^{1}}\right)}{48 \ln(2) |f''(0)| T}.$$

Remark Hence in that case also $H_{\varepsilon}(E(T)(\mathcal{C}_{L,m,M})) \approx \frac{1}{\varepsilon}$.

2. Nonconvex conservation laws

Now we consider the nonconvex case. In this situation, we use instead the following nondegeneracy condition : f : ℝ → ℝ is a smooth, non convex function with a single inflection point at zero having polynomial degeneracy, i.e. such that

$$\begin{array}{lll} f^{(j)}(0) &=& 0 \quad \text{for all} \quad j=2,\ldots,m, \qquad f^{(m+1)}(0) \ \neq \ 0\,, \\ \\ f^{\prime\prime}(u) \cdot u \cdot \mathrm{sign}\big(f^{(m+1)}(0)\big) \ > \ 0 \qquad \forall \ u \in \mathbb{R} \setminus \{0\}. \end{array}$$

In this nonconvex situation, the entropy condition becomes at the level of a discontinuity (u_ℓ, u_r) :

$$\frac{f(u_\ell)-f(u)}{u_\ell-u} \geq \frac{f(u_r)-f(u)}{u_r-u}$$

for every u between u_{ℓ} and u_r . (Oleinik's E-condition)

Nonconvex conservation laws, continued

Theorem (Ancona-G.-Nguyen, 2019)

For any given L, M, T > 0, and for every ε > 0 sufficiently small, the following estimates hold :

$$\mathcal{H}_{\varepsilon}\Big(S_{\mathcal{T}}(\mathcal{C}_{L,M}) \mid \mathbf{L}^{1}(\mathbb{R})\Big) \leq \mathsf{\Gamma}_{2}^{+} \cdot \frac{1}{\varepsilon^{m}}, \qquad (1)$$

$$\mathcal{H}_{\varepsilon}\Big(S_{\mathcal{T}}(\mathcal{C}_{L,M}) \mid \mathbf{L}^{1}(\mathbb{R})\Big) \geq \Gamma_{2}^{-} \cdot \frac{1}{\varepsilon^{m}}, \qquad (2)$$

where

$$\begin{split} \mathcal{C}_{L,M} &\doteq \big\{ u_0 \in L^{\infty}(\mathbb{R}) \; / \; \text{Supp} \, u_0 \subset [-L,L], \; \|u_0\|_{L^{\infty}} \leq M \big\}, \\ & \Gamma_2^+ = c_2 \bigg(1 + L + T + \frac{L^2}{T} \bigg)^{m+1} \\ & \Gamma_2^- = c_2 \cdot \frac{L^{m+1}}{T}. \end{split}$$

for some constant $c_2 > 0$ depending only on f and M.

3. Systems of conservation laws

- Now we consider systems of conservation laws. Here the functional framework is different, and the standard one considers solutions with (small) total variation in space.
- This goes back to Glimm (1965), and then T.P. Liu, Bianchini-Bressan, etc.
- In that case, one can define a semigroup S : [0,∞[×D₀ → D₀ defined on a closed domain D₀ ⊂ L¹(ℝ, ℝ^N), with the properties :

 (i)

$$\begin{split} \Big\{ \nu \in L^1(\mathbb{R},\Omega) \, \big| \, \mathsf{Tot.Var.}(\nu) \leq \delta_0 \Big\} \subset \mathcal{D}_0 \\ & \subset \Big\{ \nu \in L^1(\mathbb{R},\Omega) \, \big| \, \mathsf{Tot.Var.}(\nu) \leq 2\delta_0 \Big\}, \end{split}$$

for suitable constant $\delta_0 > 0$.

(ii) For every u

 ū ∈ D₀, the semigroup trajectory t → S_t u
 i = u(t, ·)

 provides an entropy weak solution of the Cauchy problem, with initial

 data

$$u(0,\cdot)=\overline{u},$$

that satisfy

Liu stability condition. A shock discontinuity of the *i*-th family (u_{ℓ}, u_r) , traveling with speed $\sigma_i[u_{\ell}, u_r]$, is *Liu admissible* if, for any state *u* lying on the *i*-th Hugoniot curve between u_{ℓ} and u_r , the shock speed $\sigma_i[u_{\ell}, u]$ of the discontinuity (u_{ℓ}, u) satisfies

 $\sigma_i[u_\ell, u] \geq \sigma_i[u_\ell, u_r].$

Result in the system case

Theorem (Ancona-G.-Nguyen, 2014)

Given any L, m, M, T > 0, for any interval $I \subset \mathbb{R}$ of length |I| = 2L, and for $\varepsilon > 0$ sufficiently small, the following estimates hold.

$$H_{\varepsilon}\Big(S_{\mathcal{T}}ig(\mathcal{C}_{[L,m,M]}\cap\mathcal{D}_0ig)\mid L^1(\mathbb{R},\Omega)\Big)\geq crac{N^2L^2}{T}\cdotrac{1}{arepsilon},$$

where c > 0 is an ugly explicit constant depending on f.

(ii)

(i)

$$H_{\varepsilon}\Big(S_{\mathcal{T}}\big(\mathcal{L}_{[I,m,M]}\cap\mathcal{D}_{0}\big)\mid L^{1}(\mathbb{R},\Omega)\Big)\leq 48N\delta_{0}\cdot L_{\mathcal{T}}\cdot\frac{1}{\varepsilon},$$

where

$$L_{\mathcal{T}} \doteq L + rac{\Delta_{ee}\lambda}{2} \cdot \mathcal{T}, \qquad \Delta_{ee}\lambda \doteq \sup \left\{ \lambda_{\mathcal{N}}(u) - \lambda_1(v) \, ; \, u, v \in \Omega
ight\}.$$

Other results

- Other results concern :
 - strictly convex (but not uniformly strictly convex) scalar equations (op. cit.)
 - Temple systems (op. cit.)
 - Hamilton-Jacobi equations (Ancona-Cannarsa-Nguyen, 2015)

IV. Ideas of proof (scalar convex case). Higher ε -entropy bounds

Let us begin by briefly describing De Lellis and Golse's proof of the conservative case.

We cite two important ingredients in the proof.

• On the one side, one has the following L^1 -to- L^∞ estimate :

Proposition (Lax) If $f'' \ge a > 0$, for $u_0 \in L^1(\mathbb{R})$ and t > 0, one has :

$$\|S(t)u_0\|_{L^{\infty}} \leq \sqrt{\frac{2\|u_0\|_1}{a t}}$$

On the other side, another ingredient is Oleinik's inequality :

Theorem (Oleinik) If $f'' \ge a > 0$, for all $u_0 \in L^{\infty}(\mathbb{R})$, one has, denoting $u(t, \cdot) = S(t)u_0$:

$$\forall t > 0, \ \forall x < y, \quad \frac{u(t, y) - u(t, x)}{y - x} \le \frac{1}{at}$$

(In particular u is locally BV for t > 0.)

- One can see that the first ingredient can be deduced from the second one.
- A way to prove these two results is to use Lax-Oleinik's formula giving an explicit (yet nontrivial) form to solution of convex scalar conservation laws scalaires.

One deduces from what precedes and from the finite propagation speed that

$$S(T)\mathcal{C}_{L,m,M} \subset \left\{ u_T \in L^1(\mathbb{R}) / \|u_T\|_{L^1} \leq m, \|u_T\|_{L^\infty} \leq \sqrt{\frac{2m}{aT}}, \\ \operatorname{Supp}(u_T) \subset [-L - 2c_M\sqrt{2mT/a}, L + 2c_M\sqrt{2mT/a}], \\ (u_T)_x \leq \frac{1}{aT} \right\}.$$

▶ In particular, denoting $q: x \mapsto x/aT$, one has

$$\begin{split} q - S(\mathcal{T})\mathcal{C}_{L,m,M} &\subset \mathcal{J}_{\overline{L},\overline{V}} \\ &\doteq \Big\{ w : [-\overline{L}/2,\overline{L}/2] \to [-\overline{V}/2,\overline{V}/2], \ w \text{ non-decreasing} \Big\}, \end{split}$$

for \overline{L} and \overline{V} that can easily be computed.

After translation, we are hence interested in the ε-entropy of :

$$\mathcal{I}_{\overline{L},\overline{V}} \doteq \Big\{ w : [0,\overline{L}] \to [0,\overline{V}], \ w \text{ non-decreasing} \Big\}.$$

Consequently the result is a consequence of :

Lemme (De Lellis-Golse) For $0 \le \varepsilon < \frac{\overline{LV}}{6}$, one has :

$$H_{\varepsilon}(\mathcal{I}_{\overline{L},\overline{V}} \mid L^1(0,\overline{L})) \leq 4 \left\lfloor rac{\overline{L} \, \overline{V}}{arepsilon}
ight
brace.$$

- One introduces $N \in \mathbb{N} \setminus \{0\}$, $\Delta x \doteq \overline{L}/N$ and $\Delta y \doteq \overline{V}/N$.
- One considers suitable non-decreasing step-functions χ on this grid :



• One introduces the subsets U consisting in non-decreasing functions between two such step-functions χ_- and χ^+ satisfying

$$\chi^{-}(k\Delta x) \leq \chi^{+}(k\Delta x) \leq \chi^{-}((k+1)\Delta x) + \Delta y.$$

► Choosing N so that these subsets are of diameter ≤ 2ε and counting these subsets, we reach the result.

V. Ideas of proof in the convex scalar case. Lower ε -entropy bounds

- ► To establish a lower bound on $H_{\varepsilon}(S(T)C_{L,m,M} | L^1(\mathbb{R}))$, we cut the proof in two parts :
 - We look for a class of functions A_T , of simple form, and such that

$$\mathcal{A}_T \subset S(T)\mathcal{C}_{L,m,M}.$$

• One introduces next a finite family \mathcal{I} of functions of $\mathcal{A}_{\mathcal{T}}$, of cardinal N large enough, and such that for each $\overline{f} \in \mathcal{I}$,

Card
$$\{f \in \mathcal{I} / ||f - \overline{f}||_{L^1} \leq 2\varepsilon\} \doteq \widetilde{N}(\overline{f}),$$

is sufficiently small. We can then conclude that the minimal number of parts in a ε -covering satisfies :

$$N_{\varepsilon} \geq rac{N}{\max_{\overline{f}} ilde{N}_{\overline{f}}}.$$

This last point uses arguments from Bartlett-Kulkarni-Posner (1997).

Part 1. Description of certain attainable states

- ► We know that states of the system at time *T*, associated to an initial data in C_{L,m,M}, satisfy naturally an L¹ estimate, an L[∞] estimate, Oleinik's inequality, and are compactly supported.
- A first idea is to show that, changing the constants if necessary, one can reach states that satisfy these conditions.
- More precisely, one has the following result.

Proposition

For L, m, M, b > 0, we fix :

$$\mathcal{A}_{[L,m,M,b]} \doteq \Big\{ u_{T} \in BV(\mathbb{R}) \mid Supp(u_{T}) \subset [-L,L], \\ \|u_{T}\|_{L^{1}} \leq m, \|u_{T}\|_{L^{\infty}} \leq M, Du_{T} \leq b \Big\},$$
Then for h > 0 sufficiently small, one has :

$$\mathcal{A}_{[L_{\mathcal{T}}, 2Lh, h, (2\mathcal{T}|f''(0)|)^{-1}]} \subset S(\mathcal{T})(\mathcal{C}_{L,m,M}),$$

where

$$L_T \doteq L - 2T|f''(0)|h.$$

Attainable states, continued

Remark

In the above statement, h is small, but not very small. If one replaces

$$\mathcal{A}_{[L_T, 2Lh, h, (2T|f''(0)|)^{-1}]} \subset S(T)(\mathcal{C}_{L,m,M}),$$

with

$$\mathcal{A}_{[L_T, 2Lh, h, (T \parallel f'' \parallel_{\infty})^{-1}]} \subset S(T)(\mathcal{C}_{L,m,M}) \text{ with } L_T \doteq L - T \parallel f'' \parallel_{\infty} h,$$

the only constraint on h is $h \le M$ and $Lh \le m$. But the above formula yields a better estimate in the end.

Ideas of proof.

▶ To prove this resultat, one shows in a first time that

$$\mathcal{A}_{[L_T, 2Lh, h, (2T|f''(0)|)^{-1}]} \cap C^1(\mathbb{R}) \subset S(T)(\mathcal{C}_{L,m,M}),$$

- ► For $u_T \in \mathcal{A}_{[L_T, 2Lh, h, (2T|f''(0)|)^{-1}]} \cap C^1(\mathbb{R})$, one applies the local existence theory in C^1 to the initial data $u_T(-x)$.
- If one shows that the corresponding solution w exists in C¹ (without blow-up) until time T and that w(T, −x) ∈ C_{L,m,M}, by invariance of the regular solutions with respect to

$$(t,x) \rightarrow (T-t,-x),$$

one has etablished $u_T \in S(T)(\mathcal{C}_{L,m,M})$.

- ▶ The question becomes : use the assumptions on u_T to prove that the solution remains regular till t = T.
- It suffices to show that

 w_x remains bounded in $L^{\infty}(\mathbb{R})$ on any compact of [0, T).

• Denoting $v \doteq w_x$, we have the equation :

$$v_t(t,x) + f'(w(t,x)) \cdot v_x(t,x) = -f''(w(t,x)) \cdot v(t,x)^2$$

$$\dot{z}(t) = -f''(w(t,x(t))) \cdot z^2(t).$$

- It suffices to establish a lower bound for z. Oleinik's condition gives estimates on (z(0))_.
- With the a priori estimates on w in L[∞], one sees that this suffices to avoid the blow up of v in C¹ before time T.
- One finally deduces by a density argument that

$$\mathcal{A}_{[L_T, 2Lh, h, (2T|f''(0)|)^{-1}]} \subset S(T)(\mathcal{C}_{L,m,M}),$$

thanks to the classical property of L^1 contraction of the semi-group S(t):

$$||S(T)u_0 - S(T)\tilde{u}_0||_{L^1} \le ||u_0 - \tilde{u}_0||_{L^1}.$$

Part 2. Description of the finite family ${\cal I}$

- We consider *h* as in the above proposition.
- One introduces for n ≥ 2, the family of functions F_i : ℝ → [-h, h] for ι ∈ {-1, 1}ⁿ, supported in [-L, L] and defined in [-L, L] by

$$\mathcal{F}_{\iota}(x) = \begin{cases} \frac{hn}{2L} \left(x + L - k\frac{2L}{n} \right) & \text{if } \iota_k = 1, \\ \frac{hn}{2L} \left(x + L - (k+1)\frac{2L}{n} \right) & \text{if } \iota_k = -1, \end{cases}$$

for
$$x \in \left[-L+k\frac{2L}{n}, -L+(k+1)\frac{2L}{n}\right)$$
, and $k \in \{0,\ldots,n-1\}$.



(The example corresponds to n = 10 and $\iota = (-1, -1, 1, 1, 1, -1, 1, -1, -1, 1)$)

• The functions \mathcal{F}_{ι} belong to $\mathcal{A}_{[L, 2Lh, h, b]}$ as soon as :

$$\frac{nh}{2L} \leq b$$

Clearly, there are 2ⁿ such functions.

• It remains to estimate, fixed $\bar{\iota} \in \{-1,1\}^n$, the number of functions \mathcal{F}_{ι} such that :

$$\|\mathcal{F}_{\iota}-\mathcal{F}_{\overline{\iota}}\|_{L^{1}}\leq 2\varepsilon.$$

But

$$\|\mathcal{F}_{\iota} - \mathcal{F}_{\bar{\iota}}\|_{L^{1}} = \frac{2hL}{n} \operatorname{Card} \left\{ k \in \{1, \ldots, n\} \mid \iota_{k} \neq \bar{\iota}_{k} \right\}.$$

• We want to count $\iota \in \{-1,1\}^n$ such that

Card
$$\{k \in \{1, \ldots, n\} \mid \iota_k \neq \overline{\iota}_k\} \leq \frac{n\varepsilon}{hL}$$
.

Remark that this cardinal doe not depend on $\overline{\iota}$. Call it $\mathcal{C}(\varepsilon)$.

- The number of ι differing from $\overline{\iota}$ for exactly k indices is $\binom{n}{k}$.
- It follows that

$$\mathcal{C}(\varepsilon) = \sum_{k=0}^{\lfloor \frac{n\varepsilon}{hL} \rfloor} \binom{n}{k}.$$

- We can interpret the right-hand side in terms of a random walk in an elementary manner.
- ▶ If $X_1, ..., X_n$ are i.i.d. Bernoulli variables with $\mathbb{P}(X_i = 0) = \mathbb{P}(X_i = 1) = \frac{1}{2}$, then for all $\ell \le n$ one has :

$$\mathbb{P}(X_1+\cdots+X_n\leq \ell)=\frac{1}{2^n}\sum_{k=0}^{\ell}\binom{n}{k}.$$

We set S_n = X₁ + · · · + X_n. One uses Chernoff-Hoeffding's inequality : for µ > 0,

$$\mathbb{P}(S_n - \mathbb{E}(S_n) \leq -\mu) \leq \exp\left(-\frac{2\mu^2}{n}\right),$$

• We suppose (since ε is small!) that :

$$\frac{n\varepsilon}{hL} < \frac{n}{2}$$

and we choose

$$\mu = \frac{n}{2} - \left\lfloor \frac{n\varepsilon}{hL} \right\rfloor.$$

We obtain

$$\frac{1}{2^n}\mathcal{C}(\varepsilon) \leq \exp\left(-2\frac{\left(\frac{n}{2} - \lfloor\frac{n\varepsilon}{hL}\rfloor\right)^2}{n}\right) \leq \exp\left(-\frac{n}{2}\left(1 - \frac{\varepsilon}{hL}\right)^2\right).$$

It remains to minimize the expression

$$\exp\left(-\frac{n}{2}\left(1-\frac{\varepsilon}{hL}\right)^2\right),\,$$

with respect to n and h under the constraint

$$rac{nh}{2L} \leq b$$
 and $rac{narepsilon}{hL} \leq rac{n}{2}.$

After computation we obtain

$$\frac{\mathcal{C}(\varepsilon)}{2^n} \leq \exp\left(-\frac{1}{\varepsilon}\,\frac{4bL^2}{27}\right).$$

► The result follows.

Thank you for your attention !