

# Stationary solutions in theories beyond GR

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## Motivation

Why theories beyond-GR? How to proceed?

## GR

Brief outline

## Theories beyond GR

What's out there?

Scalar-tensor theories

Quadratic gravity theories

## Parametrised deviations from GR

Deformations of Kerr

Designer metrics

## Conclusions

## Why beyond-GR theories:

See morning talk by Thomas (Theoretical motivation for beyond-GR theories).

### 1 point to remember:

To test GR we also need solutions from theories other than GR in order to form a testbed.

### 2 approaches:

- Find solutions in specific modifications to GR and work on a case by case basis.
- Construct generic parametric deviations from known GR solutions, like the Kerr solution.

### 3 ways to proceed:

- Generate an analytic parameterised solution without approximations
- Employ some approximation scheme (slow rotation, small coupling)
- Numerical solution

The Einstein-Hilbert action in GR is  $S = \frac{1}{16\pi} \int d^4x \sqrt{-g} R + S_m(g_{\mu\nu}, \psi)$ ,  
 which results to the field equations  $R_{ab} = 8\pi (T_{ab} - \frac{1}{2}g_{ab}T)$

Stationary spacetime: symmetry with respect to time translations and rotations (the spacetime admits a timelike,  $\xi^a$ , and a spacelike,  $\eta^a$ , killing vector).

The line element for such a spacetime can be written as<sup>1</sup>

$$ds^2 = -e^{2\nu} dt^2 + r^2 \sin^2 \theta B^2 e^{-2\nu} (d\varphi - \omega dt)^2 + e^{2(\zeta-\nu)} (dr^2 + r^2 d\theta^2)$$

This line element describes the spacetime of a rotating compact object.

The field equations can be solved either for vacuum spacetimes (BH solutions) or spacetimes that have matter (NS solutions).

- In vacuum we have the well known BH solutions of the Kerr family (which can be extended to include electromagnetic fields as well).
- For NSs the full field equations can only be solved numerically.

<sup>1</sup>E. M. Butterworth and J. R. Ipser, ApJ **204**, 200 (1976).

- The alternative is to employ the slow rotation Hartle-Thorne method.<sup>2</sup>  

$$ds^2 = -e^{\bar{\nu}} dt^2 + e^{\lambda} dr^2 + r^2 [d\theta^2 + \sin^2 \theta d\varphi^2] - 2\varepsilon(\Omega - \omega_1)r^2 \sin^2 \theta d\varphi dt.$$

where  $\varepsilon$  is a slow rotation small bookkeeping parameter. The first order correction  $\omega_1$  is given by the equation

$$\omega_1'' = \frac{4}{r} [\pi r^2 (\epsilon + \rho) e^{\lambda} - 1] \omega_1' + 16\pi (\epsilon + \rho) e^{\lambda} \omega_1.$$

- Finally there is a general algorithm for constructing any vacuum stationary axisymmetric space-time. Such a spacetime can be described by the Weyl-Papapetrou line element<sup>3</sup>,

$$ds^2 = -f (dt - w d\varphi)^2 + f^{-1} [e^{2\gamma} (d\rho^2 + dz^2) + \rho^2 d\varphi^2].$$

By introducing the complex potential  $\mathcal{E}(\rho, z) = f(\rho, z) + i\psi(\rho, z)$ <sup>4</sup>, the Einstein field equations take the form,  $(\text{Re}(\mathcal{E}))\nabla^2 \mathcal{E} = \nabla \mathcal{E} \cdot \nabla \mathcal{E}$ ,

where,  $f = \xi^a \xi_a$  and  $\psi$  is the scalar twist,  $\nabla_a \psi = \varepsilon_{abcd} \xi^b \nabla^c \xi^d$ . By prescribing an Ernst potential  $\mathcal{E}$  one can calculate a vacuum GR solution.

<sup>2</sup>Hartle J. B., *Astrophys.J.* 150, 1005 (1967); Hartle J. B., Thorne K. S., *ApJ* 153, 807 (1968)

<sup>3</sup>A. Papapetrou, *Ann. Phys.*, 12, 309 (1953).

<sup>4</sup>F.J. Ernst, *Phys. Rev.*, 167, 1175 (1968); *Phys. Rev.*, 168, 1415 (1968).

A brief (incomplete) list of theories beyond GR.

- ▶ Scalar-tensor theories
- ▶  $f(R)$  theories
- ▶ Quadratic gravity theories
  - ▶ Einstein-dilaton-Gauss-Bonnet (EdGB)
  - ▶ dynamical Chern-Simons (dCS)
- ▶ Lorentz-violating theories
- ▶ Massive gravity theories
- ▶ Theories with non-dynamical fields

The *Bergmann-Wagoner* action for Scalar-Tensor theories is,

$$S = \int d^4x \sqrt{-\hat{g}} \left( \varphi \hat{R} - \frac{\omega(\varphi)}{\varphi} \hat{\nabla}^\mu \varphi \hat{\nabla}_\mu \varphi U(\varphi) \right) + S_m(\hat{g}_{\mu\nu}, \psi)$$

In the Einstein frame it takes the form,

$$S = \frac{1}{16\pi} \int d^4x \sqrt{-\tilde{g}} \left( \tilde{R} - 2\tilde{\nabla}^\mu \phi \tilde{\nabla}_\mu \phi - V(\phi) \right) + S_m(\hat{g}_{\mu\nu}, \psi)$$

where  $\varphi$  is redefined to  $\phi$ ,  $\hat{g}_{\mu\nu} = A^2(\phi)\tilde{g}_{\mu\nu}$ , and  $V(\phi) \equiv A^4(\phi)U(\varphi(\phi))$ . Then the field equations take the form,

$$\tilde{R}_{ab} = 2\partial_a\phi\partial_b\phi + 8\pi \left( T_{ab} - \frac{1}{2}\tilde{g}_{ab}T \right) + 2V\tilde{g}_{ab}, \quad \tilde{g}^{ab}\tilde{\nabla}_a\tilde{\nabla}_b\phi = -4\pi\alpha(\phi)T + \frac{1}{4}\frac{dV}{d\phi}$$

These equations can be solved as in GR in vacuum or in the presence of matter.<sup>5</sup> Since the actual physics is done in the Jordan frame (the particles follow the geodesics of the Jordan metric), one can return to that frame by the conformal transformation  $\hat{g}_{\mu\nu} = A^2(\phi)\tilde{g}_{\mu\nu}$ .

<sup>5</sup>D.D. Doneva, S.S. Yazadjiev, N. Stergioulas, K.D. Kokkotas, Phys. Rev. D 88, 084060 (2013) 

- In the case of a massless scalar field ( $V(\phi) = 0$ ), the vacuum field equations

$$\tilde{R}_{ab} = 2\partial_a\phi\partial_b\phi, \quad \tilde{g}^{ab}\tilde{\nabla}_a\tilde{\nabla}_b\phi = 0$$

can admit an Ernst formulation as in GR,<sup>6</sup> having the metric,

$$ds^2 = -f(dt - wd\varphi)^2 + f^{-1} \left[ e^{2\gamma} (d\rho^2 + dz^2) + \rho^2 d\varphi^2 \right]$$

and the field equations,  $(\text{Re}(\mathcal{E}))\nabla^2\mathcal{E} = \nabla\mathcal{E} \cdot \nabla\mathcal{E}$ ,

with the addition of a Laplace equation for the scalar field,  $\nabla^2\phi = 0$ , and a set of equations for the metric function  $\gamma$  of the Weyl-Papapetrou metric,

$$\frac{\partial\gamma}{\partial\rho} = \left( \frac{\partial\gamma}{\partial\rho} \right)_{GR} + \rho \left[ \left( \frac{\partial\phi}{\partial\rho} \right)^2 - \left( \frac{\partial\phi}{\partial z} \right)^2 \right], \quad \frac{\partial\gamma}{\partial z} = \left( \frac{\partial\gamma}{\partial z} \right)_{GR} + 2\rho \left( \frac{\partial\phi}{\partial\rho} \right) \left( \frac{\partial\phi}{\partial z} \right),$$

Any vacuum stationary axisymmetric GR solution can be turned into a scalar-tensor solution with a massless scalar field.<sup>7</sup>

<sup>6</sup> GP, T.P. Sotiriou, Phys. Rev. D91, 044011 (2015)

<sup>7</sup> GP, MNRAS, 466, 4381 (2017)



- In the case of a massive scalar field, one doesn't have the Ernst formulation, but can still do a fully numerical calculation,
  - Or employ a HT-like slow rotation approximation, like in GR.<sup>8</sup>
- The TOV equations then become (0th-order in the rotation),

$$M' = 4\pi r \left( rA^4 \epsilon_0 + \frac{1}{2}(r - 2M)\phi_0'^2 + rV \right),$$

$$\nu' = \frac{2(4\pi r^3(A^4 p_0 - V) + M)}{r(r - 2M)} + 4\pi r (\phi_0')^2,$$

$$p' = -(p_0 + \epsilon_0) \frac{1}{2} \nu' - \alpha \phi_0',$$

$$\phi_0'' = \frac{2\phi_0' (r(2\pi r^2(A^4(\epsilon_0 - p_0) + 2V) - 1) + M) + r^2(A^3 A'(\epsilon_0 - 3p_0) + V')}{r(r - 2M)},$$

and at 1st-order in the rotation,

$$\omega_1'' = \frac{4 \left( \pi A^4 r^2 (p_0 + \epsilon_0) (r\omega_1' + 4\omega_1) + (r - 2M)\omega_1' \left( \pi r^2 (\phi_0')^2 - 1 \right) \right)}{r(r - 2M)}$$

<sup>8</sup>Pani, Berti, Phys. Rev. D 90, 024025 (2014); Yazadjiev et al., Phys. Rev. D 93, 084038 (2016)

A lot of work has been done in scalar-tensor theories for both BHs and NSs. These results also extend to  $f(R)$  theories due to the equivalence between them (although there are subtleties).

▶ Black Holes:

▶ Real scalar field:

No-hair theorems. Same BH solutions as in GR, i.e., Kerr BHs.

▶ Complex scalar field:

Evade the no-hair theorems for  $\Psi(t, \varphi, x^i) = e^{-i\omega t} e^{im\varphi} \phi(x^i)$ .  
Stationary BH solutions with scalar clouds when  $\omega = m\Omega_H$ .

▶ Neutron Stars:

Systematic studies in slow rotation and rapid rotation for massless and massive scalar fields. Spontaneously scalarised solutions.

$f(R)$  theories such as  $f(R) = R + aR^2$  studied in their scalar-tensor formulation.

The most general action for quadratic gravity with a scalar field is

$$S = \frac{1}{16\pi} \int d^4x \sqrt{-g} \left[ R - 2\nabla^\mu \phi \nabla_\mu \phi - V(\phi) + f_1(\phi)R^2 + f_2(\phi)R_{\mu\nu}R^{\mu\nu} \right. \\ \left. + f_3(\phi)R_{\mu\nu\rho\sigma}R^{\mu\nu\rho\sigma} + f_4(\phi)^*RR \right] + S_m(\gamma(\phi)g_{\mu\nu}, \psi)$$

Special cases are the EdGB gravity (Gauss-Bonnet scalar)

$$R_{GB}^2 \equiv R^2 - 4R_{\mu\nu}R^{\mu\nu} + R_{\mu\nu\rho\sigma}R^{\mu\nu\rho\sigma},$$

and dCS gravity (Pontryagin scalar),  $*RR \equiv \frac{1}{2}R_{\mu\nu\rho\sigma}\epsilon^{\nu\mu\lambda\kappa}R_{\lambda\kappa}^{\rho\sigma}$ .

Quite some work has been done in quadratic gravity for both BHs and NSs.

► Black Holes:

Solutions have been found in the perturbative slow-rotation limit. The BH solutions are scalarised. In EdGB solutions have been also found for rapidly rotating BHs. EdGB also has spontaneously scalarised BHs.

► Neutron Stars:

► EdGB: Studies in slow rotation and rapid rotation.

Spontaneously scalarised solutions. There exists a critical  $p_c$ .

► dCS: Studies in 1st and 2nd order in rotation. Scalar dipole.

No-scalar-monopole theorem for both theories at the perturbative level.

It is probably impossible to study all solutions of all the theories beyond GR. Still, without committing to a specific theory, one could construct parameterised spacetimes that can be used to test GR.

These spacetimes do not necessarily satisfy some specific field equations.

- One such example is the Cardoso, Pani, Rico extension of the Johannsen-Psaltis non-Kerr metric,<sup>9</sup>

$$ds^2 = -fdt^2 + \frac{\Sigma(1+h^r)}{\Delta + a^2 \sin^2 \theta h^r} dr^2 + \Sigma d\theta^2 - 2a \sin^2 \theta (H-f) d\varphi dt + \sin^2 \theta \left[ \Sigma + a^2 \sin^2 \theta (2H-f) \right] d\varphi^2$$

where  $f = \left(1 - \frac{2mr}{\Sigma}\right) (1 + h^t)$ ,  $H = \sqrt{(1+h^r)(1+h^t)}$ ,  $\Sigma = r^2 + a^2 \cos^2 \theta$ ,  $\Delta = r^2 + a^2 - 2mr$ , and  $h^{r,t} = \sum_{k=0}^{k=\infty} \left( \varepsilon_{2k}^{r,t} + \varepsilon_{2k+1}^{r,t} \frac{mr}{\Sigma} \right) \left( \frac{m^2}{\Sigma} \right)^k$

Asymptotic flatness imposes  $\varepsilon_0^{r,t} = 0$ , while the mass is  $M = m(1 - \varepsilon_1^t/2)$ .

Caveat: seems to be mapped to known static solutions but not stationary.

There are other more successful approaches in that respect.<sup>10</sup>

<sup>9</sup> Cardoso, Pani, Rico, Phys.Rev. D 89, 064007 (2014); Johannsen, Psaltis, Phys.Rev. D 83, 124015 (2011)

<sup>10</sup> Konoplya et al., Phys. Rev. D 93, 064015 (2016): rotating EdGB BHs.

- Another approach: metrics with special properties, i.e., a **Carter constant**. Such examples are the bumpy Kerr and the Johannsen metric,<sup>11</sup>

$$\begin{aligned}
 ds^2 = & -\frac{2a [(r^2 + a^2)A_1(r)A_2(r) - \Delta] \tilde{\Sigma} \sin^2 \theta d\varphi dt}{[(r^2 + a^2)A_1(r) - a^2A_2(r) \sin^2 \theta]^2} + \frac{\tilde{\Sigma} dr^2}{\Delta A_5(r)} + \tilde{\Sigma} d\theta^2 \\
 & - \frac{\tilde{\Sigma} [\Delta - a^2A_2(r)^2 \sin^2 \theta] dt^2}{[(r^2 + a^2)A_1(r) - a^2A_2(r) \sin^2 \theta]^2} + \frac{\tilde{\Sigma} \sin^2 \theta [(r^2 + a^2)A_1(r)^2 - a^2\Delta \sin^2 \theta] d\varphi^2}{[(r^2 + a^2)A_1(r) - a^2A_2(r) \sin^2 \theta]^2}
 \end{aligned}$$

where  $\tilde{\Sigma} = \Sigma + f(r)$ , and  $A_1, A_2, A_5$ , and  $f$  are expansions in powers of  $1/r$ . The Johannsen metric can be related to the bumpy Kerr and these two can describe slowly rotating dCS, and some static EdGB BHs.

History note: Johannsen's metric is of the form of Carter's canonical metric<sup>12</sup>,

$$ds^2 = \frac{Z}{\Delta_r} dr^2 + \frac{Z}{\Delta_\theta} d\theta^2 + \frac{\Delta_\theta}{Z} (P_r d\varphi - Q_r dt)^2 + \frac{\Delta_r}{Z} (Q_\theta dt - P_\theta d\varphi)^2,$$

where  $Z = P_r Q_\theta - Q_r P_\theta$ , and the  $P, Q$ , and  $\Delta$  are functions of either  $r$  or  $\theta$ .

<sup>11</sup>Vigeland, Yunes, Stein, Phys.Rev. D83,104027 (2011); Johannsen, Phys.Rev. D88, 044002 (2013)

<sup>12</sup>B. Carter, Comm.Math.Phys. 10,280 (1968).

Theory	Solutions	Stability	Geodesics	Quadrupole
Extra scalar field				
Scalar-tensor	$\equiv$ GR [55–60]	[61–67]	–	–
Multiscalar/Complex scalar	$\supset$ GR [56, 68, 69]	?	?	[68, 69]
Metric $f(R)$	$\supset$ GR [58, 59]	[70, 71]	?	?
Quadratic gravity				
Gauss-Bonnet	NR [72–74]; SR [75, 76]; FR [77]	[78, 79]	SR [75, 80, 81]; FR [77]	[76, 82]
Chern-Simons	SR [83–85]; FR [86]	NR [87–90]; SR [79]	[74, 91]	[85]
Generic	SR [80]	?	[80]	Eq. (3.12)
Horndeski	[92–94]	? [95, 96]	?	?
Lorentz-violating				
Æ-gravity	NR [97–99]	?	[98, 99]	?
Khronometric/ Hofava-Lifshitz	NR, SR [98–101]	? [102]	[98, 99]	?
n-DBI	NR [103, 104]	?	?	?
Massive gravity				
dRGT/Bimetric	$\supset$ GR, NR [105–108]	[109–112]	?	?
Galileon	[113]	?	?	?
Nondynamical fields				
Palatini $f(R)$	$\equiv$ GR	–	–	–
Eddington-Born-Infeld	$\equiv$ GR	–	–	–

**Table 2.** Catalogue of BH properties in several theories of gravity. The column “Solutions” refers to asymptotically-flat, regular solutions. Legend: ST=“Scalar-Tensor,”  $\equiv$ GR=“Same solutions as in GR,”  $\supset$ GR=“GR solutions are also solutions of the theory,” NR=“Non rotating,” SR=“Slowly rotating,” FR=“Fast rotating/Generic rotation,” ?=unknown or uncertain.