

Sensitivity Analysis and Uniform Regularity for the Boltzmann Equation with Uncertainty and Multiple Scales

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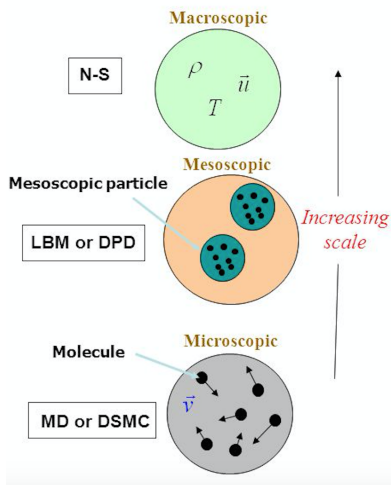
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Schedule

- 1 The Boltzmann Equation with uncertainty
- 2 Sensitivity of the system under the initial perturbation
- 3 Stability of the system after gPC-SG

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Kinetic equations with uncertainty



The Boltzmann Equation without uncertainty

Dimensionless Boltzmann Equation without uncertainty

$$\partial_t f + \mathbf{v} \cdot \nabla_{\mathbf{x}} f = \underbrace{\frac{1}{\epsilon} Q(f, f)}_{\text{binary collisions of hard sphere}}, \quad [\text{Boltzmann, 1872}]$$

$$\begin{aligned} Q(f, f) &= Q_{\text{gain}} - Q_{\text{loss}} \\ &= \int_{\mathbb{R}^3} \int_{\mathbb{S}^2} f(\mathbf{v}') f(\mathbf{v}') \sigma(\mathbf{v} - \mathbf{v}_*, \omega) d\omega d\mathbf{v}_* - \int_{\mathbb{R}^3} \int_{\mathbb{S}^2} f(\mathbf{v}) f(\mathbf{v}_*) \sigma(\mathbf{v} - \mathbf{v}_*, \omega) d\omega d\mathbf{v}_*. \end{aligned}$$

- $f(t, \mathbf{x}, \mathbf{v})$: the possibility of finding particles at time t and position \mathbf{x} with velocity \mathbf{v} .
- $\epsilon = \frac{\text{mean free path}}{\text{macroscopic length scale}}$

ϵ describes both mesoscopic and macroscopic system $\epsilon \rightarrow 0$:
$$f \rightarrow \frac{\rho}{(2\pi T)^{3/2}} e^{-\frac{|\mathbf{v}-\mathbf{u}|^2}{2T}} \quad (\text{Equilibrium}), \quad \text{where}$$

$$\rho(t, \mathbf{x}) = \int f d\mathbf{v}, \quad \mathbf{u}(t, \mathbf{x}) = \frac{1}{\rho} \int \mathbf{v} f d\mathbf{v}, \quad T(t, \mathbf{x}) = \frac{1}{\rho} \int \frac{1}{3} (\mathbf{v} - \mathbf{u})^2 f d\mathbf{v},$$

and the macroscopic quantities satisfy the **Euler equation** for a compressible fluid,

$$\begin{aligned} \partial_t \rho + \nabla_{\mathbf{x}} \cdot (\rho \mathbf{u}) &= 0 \\ \partial_t \mathbf{u} + \mathbf{u} \cdot \nabla_{\mathbf{x}} \mathbf{u} + \frac{1}{\rho} \nabla_{\mathbf{x}} (\rho T) &= 0 \\ \partial_t T + \mathbf{u} \cdot \nabla_{\mathbf{x}} T + \frac{2}{3} T \nabla_{\mathbf{x}} \cdot \mathbf{u} &= 0 \end{aligned} \quad (1.1)$$

The Boltzmann Equation with uncertainty

Dimensionless Boltzmann Equation with uncertainty

$$\partial_t f + \mathbf{v} \cdot \nabla_{\mathbf{x}} f = \frac{1}{\epsilon} Q(f, f), \quad (1.2)$$

where $Q(f, g)$ describes the binary collisions of hard sphere,

$$Q(f, g) = \int_{\mathbb{R}^3} \int_{S^2} (f(\mathbf{v}')g(\mathbf{v}'_*) - f(\mathbf{v})g(\mathbf{v}_*)) |(v - v_*) \cdot \omega| d\omega d\mathbf{v}_*, \quad (1.3)$$

with periodic boundary condition, and, initial data

$$f(0, \mathbf{x}, \mathbf{v}, \mathbf{z}) = f_0(\mathbf{x}, \mathbf{v}, \mathbf{z}), \quad \mathbf{z} \in I_{\mathbf{z}} \subset \mathbb{R}^d, \quad \mathbf{x} \in \mathbb{T}^3, \quad \mathbf{v} \in \mathbb{R}^3. \quad (1.4)$$

$$\mathbf{v}' = \mathbf{v} - [(\mathbf{v} - \mathbf{v}_*) \cdot \omega] \omega, \quad \mathbf{v}'_* = \mathbf{v}_* + [(\mathbf{v} - \mathbf{v}_*) \cdot \omega] \omega. \quad (1.5)$$

$$\pi(\mathbf{z}) : I_{\mathbf{z}} \rightarrow \mathbb{R}^+ \text{ is the probability density function of } \mathbf{z}. \quad (1.6)$$

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Other related works

- Regularity in random space for Boltzmann [Hu, Jin, 16]

$$\|f(t)\|_{H_{z,\mu}^m}^2 = \sum_{i=0}^m \int (\partial_z^i f)^2 d\mu(z) d\mathbf{v} d\mathbf{x} \quad \|f(t)\|_{H_{z,\mu}^m}^2 \lesssim e^{\frac{t}{\epsilon}} \|f(0)\|_{H_{z,\mu}^m}^2 \quad (2.1)$$

According to the density function $\pi(\mathbf{z})$, one has a corresponding L^2 space in the measure of $d\mu(\mathbf{z}) = \pi(\mathbf{z})d\mathbf{z}$.

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- Uniform regularity in random space:
 - Linear kinetic equation [Jin, Liu, Ma, 16], [Li, Wang, 17]
 - Nonlinear VPFP system [Jin, Zhu, 17]

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- Uniform regularity in random space:
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 - Nonlinear VPFP system [Jin, Zhu, 17]
- Regularity result for deterministic Boltzmann equation without ϵ , [Y. Guo 2004], [R. Duan, 2007]

$$\partial_t f + \mathbf{v} \cdot \nabla_{\mathbf{x}} f = Q(f, f), \quad f(0, \mathbf{x}, \mathbf{v}) = f_0(\mathbf{x}, \mathbf{v}) \quad (2.2)$$

$$\text{If} \quad \left\| \frac{f(0) - M}{\sqrt{M}} \right\|_{H_x^N(L_v^2)} \leq \delta, \quad (2.3)$$

$$\text{then} \quad \left\| \frac{f(t) - M}{\sqrt{M}} \right\|_{H_x^N(L_v^2)} \lesssim e^{-t} \left\| \frac{f(0) - M}{\sqrt{M}} \right\|_{H_x^N(L_v^2)}. \quad (2.4)$$

For $N \geq 4$.

Main Theorem for the Sensitivity (Jin-Zhu, '17)

Define $\partial_{\mathbf{z}}^{\beta} f = f_{\beta}$, $\|f\|_{H_{\mathbf{z},\mu}^m(H_{\mathbf{x}}^4)} = \sum_{|\alpha| \leq 4} \int (\partial_{\mathbf{x}}^{\alpha} f_{\beta})^2 d\mu(\mathbf{z}) d\mathbf{x} d\mathbf{v}$

Sensitivity of the system under the initial perturbation

If initially the solution to the Boltzmann equation f satisfies

$$\left\| \frac{f(0) - M}{\sqrt{M}} \right\|_{H_{\mathbf{z},\mu}^m(H_{\mathbf{x}}^4(L_{\mathbf{v}}^2))} \leq \epsilon C_0, \quad (2.5)$$

then

$$\left\| \frac{f(t) - M}{\sqrt{M}} \right\|_{H_{\mathbf{z},\mu}^m(L_{\mathbf{x},\mathbf{v}}^2)} \leq \xi e^{-\epsilon\beta t} \left\| \frac{f(0) - M}{\sqrt{M}} \right\|_{H_{\mathbf{z},\mu}^m(H_{\mathbf{x}}^4(L_{\mathbf{v}}^2))}. \quad (2.6)$$

where C_0 , ξ , β are constants, and C_0 depends only on m .

Where $M = \frac{1}{(2\pi)^{3/2}} e^{-\frac{|\mathbf{v}|^2}{2}}$

Uniform regularity in random space

Under the same condition,

$$\begin{aligned} \|f\|_{H_{z,\mu}^m} &\leq \left\| \frac{f - M + M}{\sqrt{M}} \right\|_{H_{z,\mu}^m} \leq \left\| \frac{f(t) - M}{\sqrt{M}} \right\|_{H_{z,\mu}^m} + \|\sqrt{M}\| \\ &\leq \xi e^{-\epsilon\beta t} \left\| \frac{f(0) - M}{\sqrt{M}} \right\|_{H_{z,\mu}^m(H_x^4)} + |\mathbb{T}^3|. \end{aligned} \quad (2.7)$$

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Another problem we care about in UQ

- How to quantify the uncertainty?
 - Stochastic Collocation (SC) [Xiu, Hesthaven, 05]
 - Generalized Polynomial Chaos Stochastic Galerkin(gPC-SG) [Xiu, Karniadakis, 02], [Ghanem, Spanos, 91]
- The high order accuracy of gPC-SG depends on the regularity of the solution in random space and the stability of the system after gPC-SG.

The framework of gPC-SG

For $\mu(\mathbf{z})$ -measure, it has a set of corresponding orthogonal polynomial basis $\{\Phi_i\}_{i=0}^{\infty}$, s.t $\int \Phi_i \Phi_j d\mu(\mathbf{z}) = \delta_{ij}$. Find

$$\hat{f}^K = \sum_{i=0}^K \hat{f}_i(t, \mathbf{x}, \mathbf{v}) \Phi_i(\mathbf{z}), \quad (3.1)$$

in the K -th order subspace $\{\Phi_i\}_{i=0}^K$. [Hu, Jin, 2017]

$$\left\langle \partial_t \hat{f}^K + \mathbf{v} \cdot \nabla_{\mathbf{x}} \hat{f}^K, \Phi^K \right\rangle_{\pi} = \frac{1}{\epsilon} \left\langle Q(\hat{f}^K, \hat{f}^K), \Phi^K \right\rangle_{\pi}. \quad (3.2)$$

The deterministic system for the approximate solution after gPC-SG

$$\partial_t \hat{f}_j + \mathbf{v} \cdot \nabla_{\mathbf{x}} \hat{f}_j = \frac{1}{\epsilon} \sum_{k,l=0}^K E_{klj} Q(\hat{f}_k, \hat{f}_l), \quad \text{for } 0 \leq j \leq K$$

where $E_{klj} = \int_{I_{\mathbf{z}}} \Phi_k \Phi_l \Phi_j d\mu(\mathbf{z})$.

Condition on the random basis

Condition on the random basis

The basis functions $\Phi_k(z)$ satisfy,

$$|\Phi_k| \leq (k+1)^p, \quad k \geq 0, \quad (3.3)$$

eg. Legendre ($p = 1/2$), Chebyshev ($p = 0$)

[Jin, Shu, 17] And accordingly, we define the new energy term of the approximate solution \hat{E}_f^N ,

$$q \geq p + 2, \quad \hat{E}_f^N(t) := \sum_{k=0}^K \left\| (k+1)^q \hat{f}_k(t) \right\|_{H_x^N}^2 \quad (3.4)$$

Stability of the system after gPC-SG

For $N \geq 4$, if initially satisfies $\hat{E}_{\hat{f}-M}^N(0) \leq \epsilon^2 C_0$, then

$$\hat{E}_f^N(t) \leq 2\hat{E}_{\hat{f}-M}^N(0) + 2|\mathbb{T}^3|, \quad t > 0 \quad (3.5)$$

Here all the constants are independent of ϵ and K .

K dependency on initial condition

The deterministic system after gPC-SG

$$\partial_t \hat{h}_j + \mathbf{v} \cdot \nabla_{\mathbf{x}} \hat{h}_j - \frac{1}{\epsilon} \mathcal{L} \hat{h}_j = \frac{1}{\epsilon} \sum_{k,l=0}^K E_{klj} \Gamma(\hat{h}_k, \hat{h}_l), \quad \text{for } 0 \leq j \leq K$$

The system for the $\{h_{\beta}\}_{\{|\beta| \leq m\}}$

$$\partial_t h_{\beta} + \mathbf{v} \cdot \nabla_{\mathbf{x}} h_{\beta} - \frac{1}{\epsilon} \mathcal{L} h_{\beta} = \frac{1}{\epsilon} \sum_{\mathbf{j} \leq \beta} \binom{\beta}{\mathbf{j}} \Gamma(h_{\mathbf{j}}, h_{\beta-\mathbf{j}}), \quad \text{for } 0 \leq |\beta| \leq m$$

Recall the result for the $\sum_{|\beta| \leq m} \|h_{\beta}(t)\|_{H_{\mathbf{x}}^4}$, we request $\sum_{|\beta| \leq m} \|h_{\beta}(0)\|_{H_{\mathbf{x}}^4} \leq \epsilon C(m)$, so if we directly adopt the energy estimate framework, we request

$$\|h^K(0)\|_{H_{\mathbf{x}}^N} \leq \epsilon C(K), \quad (3.6)$$

which is bad in terms of K .

- Open Problem:
 - Get rid of the ϵ dependency on initial data.
 - Rigorous proof of the spectral convergence of the gPC-SG method
- Thanks for your attention!