

An extension of the Goldberg-Sachs theorem in five and higher dimensions ¹

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Null frames

“Null” frame $(\boldsymbol{l}, \boldsymbol{n}, \boldsymbol{m}^{(i)})$ in n -dimensions ($n \geq 4$):

$$\boldsymbol{l} \cdot \boldsymbol{n} = 1, \quad \boldsymbol{m}^{(i)} \cdot \boldsymbol{m}^{(j)} = \delta_{ij} \quad (i = 2, \dots, n-1)$$

Metric $g_{ab} = 2l_{(a}n_{b)} + \delta_{ij}m_a^{(i)}m_b^{(j)}$ invariant under:

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Null rotations

$$l' = l, \quad n' = n + z_i m^{(i)} - \frac{1}{2} z^i z_i l, \quad m'^{(i)} = m^{(i)} - z_i l$$

Spatial rotations

$$l' = l, \quad n' = n, \quad m'^{(i)} = X^i_j m^{(j)}$$

Boosts

$$l' = \lambda l, \quad n' = \lambda^{-1} n, \quad m'^{(i)} = m^{(i)}$$

Classification of the Weyl tensor

Frame decomposition of Weyl:

$$\begin{aligned}
 C_{abcd} = & \overbrace{4C_{0i0j} n_{\{a} m_b^{(i)} n_c m_d^{(j)}\}}^{b=+2} + \overbrace{8C_{010i} n_{\{a} l_b n_c m_d^{(i)}\} + 4C_{0ijk} n_{\{a} m_b^{(i)} m_c^{(j)} m_d^{(k)}\}}^{b=+1} \\
 & + 4C_{0101} n_{\{a} l_b n_c l_d\} + C_{01ij} n_{\{a} l_b m_c^{(i)} m_d^{(j)}\} \\
 & + 8C_{0i1j} n_{\{a} m_b^{(i)} l_c m_d^{(j)}\} + C_{ijkl} m_{\{a} m_b^{(i)} m_c^{(j)} m_d^{(k)} m_d^{(l)}\} \left. \vphantom{C_{ijkl} m_{\{a} m_b^{(i)} m_c^{(j)} m_d^{(k)} m_d^{(l)}\}} \right\}_{b=0} \\
 & + \underbrace{8C_{101i} l_{\{a} n_b l_c m_d^{(i)}\} + 4C_{1ijk} l_{\{a} m_b^{(i)} m_c^{(j)} m_d^{(k)}\}}_{b=-1} + \underbrace{4C_{1i1j} l_{\{a} m_b^{(i)} l_c m_d^{(j)}\}}_{b=-2},
 \end{aligned}$$

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 \end{aligned}$$

Classification:

- find a frame “as aligned as possible”
- characterize C_{abcd} by the maximal *boost weight* $b \in \{+2, +1, 0, -1, -2\}$ of non-zero components.

Weyl types

- **G**: $b = +2$ (general case)
- **I**: $b = +1$ (l is a WAND \equiv Weyl Aligned Null Direction)
- **II**: $b = 0$ (l is a *double* WAND)
- **III**: $b = -1$ (l is a *triple* WAND)
- **N**: $b = -2$ (l is a *quadruple* WAND)

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The resulting classification scheme is:

- for $n = 4$: *equivalent* to the Petrov classification
- based on a preferred null vector field l
- pointwise
- invariant (frame independent) (cf. also [M.O.'09, Senovilla'11])
- useful for studying spacetimes with vanishing invariants
[Coley-Milson-Pravda-Pravdová'04, Hervik'11]

Any tensor can be classified similarly (e.g., F_{ab} , R_{abcd} , R_{ab} , ...).

Geometric optics

Frame components of the covariant derivative of l :

$$l_{a;b} = \gamma l_a l_b + \varepsilon l_a n_b + \beta_i l_a m_b^{(i)} + \tau_i m_a^{(i)} l_b + \kappa_i m_a^{(i)} n_b + \rho_{ij} m_a^{(i)} m_b^{(j)}$$

Geodesic vector field l

$$0 = l_{a;b} l^b = \varepsilon l_a + \kappa_i m_a^{(i)} \Leftrightarrow \varepsilon = 0 = \kappa_i$$

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Optics of $l \rightarrow$ matrix $\rho_{ij} \equiv l_{a;b} m^{(i)a} m^{(j)b} = (\sigma_{ij} + \theta \delta_{ij}) + \rho_{[ij]}$.

Optical scalars

expansion $\theta = \frac{1}{n-2} \rho_{ii} = \frac{1}{n-2} l^a_{;a}$

twist $\omega^2 \equiv \rho_{[ij]} \rho_{[ij]} = -l_{[a;b]} l^{a;b}$

shear $\sigma^2 \equiv \sigma_{ij} \sigma_{ij} = l_{(a;b)} l^{a;b} - \frac{1}{n-2} (l^a_{;b})^2$

Interpretation for $n = 4$:

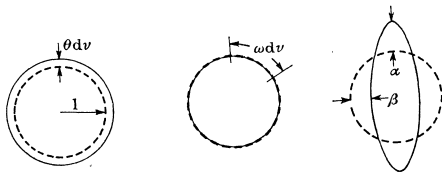


FIGURE 3. The shadow (solid lines) cast by an object will differ from the parallel displace of the object (dotted lines) by an expansion θdv , a rotation ωdv , and shear $|\sigma| dv = \frac{1}{2}(\alpha + \beta)$.

From [Sachs'61]

Goldberg-Sachs in 4D

Goldberg-Sachs theorem ($n = 4$) [Goldberg-Sachs'62, Newman-Penrose'62]

In *vacuum*, l is a **multiple WAND** (i.e., **type II** or more special) \Leftrightarrow
 l is **geodesic** ($\kappa_i = 0$) + **shearfree** ($\sigma = 0$)

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 l is **geodesic** ($\kappa_i = 0$) + **shearfree** ($\sigma = 0$)

- analogy with “null” Maxwell fields (Mariot-Robinson theorem)
- $\kappa_i = 0 = \sigma$ drastically simplifies NP equations, e.g.:
 - Kerr metric [Kerr'63]
 - all type D vacua [Kinnersley'69]

Goldberg-Sachs in higher dimensions?

Goldberg-Sachs extends to $n > 4$? How?

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Early results:

	Weyl type	Geodesic	Shearfree
Schwarzschild	D	✓	✓
Myers-Perry	D	✓	✗
Black string	D	✓	✗
Expanding III/N	III, N	✓	✗
VSI	III, N, O	✓	✓
\subset Kerr-Schild	II, D	✓	✗
\subset Robinson-Trautman	D	✗	

[Myers-Perry'86, Horowitz-Ross'98, Frolov-Stojković'03, Pravda-Pravdová-Coley-Milson'04,
Coley-Milson-Pravda-Pravdová'04, Podolský-M.O.'06, Pravda-Pravdová-M.O.'07, M.O.-Pravda-Pravdová'09]
Review papers: [Coley'08, M.O.-Pravda-Pravdová'13]

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Natural to split the HD study into two parts:

- 1 “geodesic part”
- 2 “shearfree part”.

Goldberg-Sachs in HD: geodesic part

We have:

- type III, N \Rightarrow l geodesic [Pravda-Pravdová-Coley-Milson'04]
- type II \Rightarrow l geodesic [Durkee-Reall'09]
- type D $\not\Rightarrow$ l geodesic [Pravda-Pravdová-M.O.'07]

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Proposition (Geodesic part [Durkee-Reall'09])

*An $n > 4$ Einstein spacetime admits a multiple WAND \Leftrightarrow it admits a **geodesic** multiple WAND.*

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However,

Proposition (Geodesic part [Durkee-Reall'09])

*An $n > 4$ Einstein spacetime admits a multiple WAND \Leftrightarrow it admits a **geodesic** multiple WAND.*

All such spacetimes explicitly known for $n = 5$ [Durkee-Reall'09]
(e.g., $dS_3 \times S^2$).

Goldberg-Sachs in HD: “shearfree” part

Shear is generically non-zero. How to generalize “ $\sigma = 0$ ” to $n > 4$?

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Note:

- $n = 4$:

$$\sigma = 0 \Leftrightarrow \boldsymbol{\rho} = b \begin{pmatrix} \mathbf{1} & a \\ -a & \mathbf{1} \end{pmatrix}.$$

- type III/N [Pravda-Pravdová-Coley-Milson'04]:

$$\boldsymbol{\rho} = \text{diag} \left(b \begin{bmatrix} \mathbf{1} & a \\ -a & \mathbf{1} \end{bmatrix}, 0, \dots, 0 \right).$$

- Kerr-Schild [M.O.-Pravda-Pravdová'09]:

$$\boldsymbol{\rho} = \alpha \text{diag} \left(b_1 \begin{bmatrix} \mathbf{1} & a_1 \\ -a_1 & \mathbf{1} \end{bmatrix}, \dots, b_\nu \begin{bmatrix} \mathbf{1} & a_\nu \\ -a_\nu & \mathbf{1} \end{bmatrix}, 1, \dots, 1, 0, \dots, 0 \right).$$

Goldberg-Sachs in HD: “shearfree” part

Idea: look for canonical forms of $\rho_{ij} \equiv l_{a;b} m_{(i)}^a m_{(j)}^b$.

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Full result known for $n = 5$:

Proposition (“Shearfree” part $n = 5$ [M.O.-Pravda-Pravdová-Reall’12])

Five-dimensional Einstein spacetimes of type II (or more special) admit a geodesic multiple WAND l for which, in a suitable frame, ρ takes one of the forms ($\text{rank}(\rho)=3,2,1,0$)

$$\begin{aligned}
 i) \quad \rho &= b \begin{pmatrix} \textcolor{red}{1} & a & 0 \\ -a & \textcolor{red}{1} & 0 \\ 0 & 0 & 1+a^2 \end{pmatrix}, & ii) \quad \rho &= b \begin{pmatrix} \textcolor{red}{1} & a & 0 \\ -a & \textcolor{red}{1} & 0 \\ 0 & 0 & 0 \end{pmatrix}, \\
 iii) \quad \rho &= b \begin{pmatrix} 1 & a & 0 \\ -a & -a^2 & 0 \\ 0 & 0 & 0 \end{pmatrix}, & iv) \quad \rho &= 0.
 \end{aligned}$$

- obtained from Bianchi/Ricci identities (plus derivatives)
- *i)–iii)* are generically shearing
- invariant meaning (integrability of null distributions, “optical structures”, ...)
- examples are known for each case:
 - i)* Myers-Perry
 - ii)* Kerr black string
 - iii)* $dS_3 \times S^2$
 - iv)* Kundt
- conditions on ρ are necessary but **not sufficient**, in general (counterexample)

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Used to find all 5D non-twisting vacuum solutions of type II, III, N
[Reall-Graham-Turner'13].

For $n > 5$, form of ρ determined in special cases:

- type III/N [Pravda-Pravdová-Coley-Milson'04]
- Kerr-Schild [M.O.-Pravda-Pravdová'09a, Málek-Pravda'11]
- asymptotically flat [M.O.-Pravda-Pravdová'09b]

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Systematic study in the **non-twisting** case [M.O.-Pravda-Pravdová'13]:

- constraints on ρ (at least one multiple eigenvalue)
- many subcases depending on $\text{rank}(\rho)$, form of C_{abcd} , ...
- geometric meaning
- again, many of the obtained conditions are only necessary
- m distinct non-zero eigenvalues are possible (contrary to $n = 4, 5$), e.g. $dS_{m+2} \times S_{n-2-m}$ ($1 \leq m \leq n - 4$)

For example, for $n = 6$:

Case	rank(ρ)	Possible form of ρ	Examples
$\Phi_{ij} \neq 0$	4	$\text{diag}(a, a, a, a)$	Rob.-Tra.
	3	$\text{diag}(a, a, b, 0)$	$?(†)$
	2	$\text{diag}(a, b, 0, 0)$	$dS_4 \times S^2$
	1	$\text{diag}(a, 0, 0, 0)$	$dS_3 \times S^3$
	0	$\text{diag}(0, 0, 0, 0)$	Kundt
$\Phi_{ij} = 0$	4	$\text{diag}(a, a, a, a)^2$	Rob.-Tra. (" $\mu = 0$ ")
	3	X	X
	2	$\text{diag}(a, a, 0, 0)$?
	1	X	X
	0	$\text{diag}(0, 0, 0, 0)$	Kundt

²Cf. also [Reall-Graham-Turner'13]

Compare possible forms for $n = 4, 5, 6$ (**non-twisting**):

$\text{rank}(\rho)$	$n = 4$	$n = 5$	$n = 6, \Phi_{ij} \neq 0$	$n = 6, \Phi_{ij} = 0$
0	$\text{diag}(00)$	$\text{diag}(000)$	$\text{diag}(0000)$	$\text{diag}(0000)$
1	X	$\text{diag}(a00)$	$\text{diag}(a000)$	X
2	$\text{diag}(aa)$	$\text{diag}(aa0)$	$\text{diag}(ab00)$	$\text{diag}(aa00)?$
3	—	$\text{diag}(aaa)$	$\text{diag}(aab0)?$	X
4	—	—	$\text{diag}(aaaa)$	$\text{diag}(aaaa)$

A geometric perspective on Goldberg-Sachs

In 4D, if $\{l, n, m, \bar{m}\}$ is a null frame:

$$[m, l] = (\bar{\alpha} + \beta - \pi)l + \kappa n - \sigma \bar{m} - (\bar{\rho} + \epsilon - \bar{\epsilon})m$$

i.e., l is geodesic and shearfree $\Leftrightarrow \mathcal{D} \equiv \text{Span}\{m, l\}$ is **integrable**.

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- emphasis on the complex 2-dimensional totally null distribution \mathcal{D} (rather than on l)
- natural for extensions to arbitrary signature and *complex geometries* [Plebański-Hacyan'75] (cf. [Gover-Hill-Nurowski'10])

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- partial results also in HD (e.g., “optical structure” in 5D)
- or viceversa, *inequivalent formulation of HD Goldberg-Sachs*: conditions on the Weyl tensor that *ensure* certain integrability properties [Taghavi-Chabert'11,'12].

An example

Einstein spacetime with

- a twistfree multiple WAND l
- $\det \rho \neq 0$
- *distinct*, non-zero eigenvalues.

Metric ($R \sim \lambda$, $n \geq 7$):

$$ds^2 = \lambda r^2 du^2 + 2dudr + (\lambda ur - 1)^2 \tilde{g}_{AB} dx^A dx^B + r^2 \hat{g}_{IJ} dx^I dx^J.$$

with \tilde{g}_{AB} Einstein and \hat{g}_{IJ} Ricci-flat.

Multiple WAND:

$$\ell_a dx^a = du, \quad \ell^a \partial_a = \partial_r.$$

Optical matrix:

$$\rho_{AB} = \frac{\lambda u}{\lambda ur - 1} \delta_{AB}, \quad \rho_{IJ} = \frac{1}{r} \delta_{IJ}.$$

For $n = 7$: $\rho = \text{diag}(a, a, a, a, b)$.