

Optimal Control in Coefficients for Degenerate Elliptic Equations

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Workshop on PDE's, Optimal Design and Numerics,
Benasque, 2009

Main Notation

Let Ω be a bounded open subset of \mathbb{R}^N with Lipschitz boundary.

Degenerate Weight Function

A weight function $\rho : \Omega \rightarrow \mathbb{R}_+$ is called to be degenerate on Ω if

$$\rho + \rho^{-1} \in L^1_{loc}(\mathbb{R}^N). \quad (1)$$

Non-Degenerate Weight Function

We say that a nonnegative function $\rho(x) \geq 0$ is a non-degenerate weight if

$$\rho + \rho^{-1} \in L^\infty(\Omega). \quad (2)$$

Definition of W and H -spaces

With the degenerate weight function $\rho(\mathbf{x}) \geq 0$ we will associate two weighted Sobolev spaces

- 1 $W = W(\Omega, \rho \, d\mathbf{x})$ is the set of functions $y \in W_0^{1,1}(\Omega)$ for which the norm

$$\|y\|_{\rho} = \left(\int_{\Omega} (y^2 + |\nabla y|^2) \rho \, d\mathbf{x} \right)^{1/2} \quad (3)$$

is finite;

- 2 $H = H(\Omega, \rho \, d\mathbf{x})$ is the closure of $C_0^{\infty}(\Omega)$ in $\|\cdot\|_{\rho}$ -norm.

For a "typical" degenerate weight ρ we have: W and H are Hilbert spaces, $H \subseteq W$, and the identity $W = H$ is not valid in general.

Admissible Controls

Definition of Admissible Controls

We say that a matrix $A = [a_{ij}]$ is an admissible control ($A \in U_{ad}$) if $A = [\vec{a}_1, \dots, \vec{a}_N] \in M_\alpha^\beta(\Omega)$ (i.e., $A \in L^\infty(\Omega; \mathbb{R}^{N \times N})$ and $A(x) \geq \alpha I$, $(A(x))^{-1} \leq \beta^{-1} I$, a.e. in Ω , $0 < \alpha \leq \beta$), and

$$|\operatorname{div}_\rho \vec{a}_i| \leq \gamma_i, \quad \rho \, dx - \text{a.e. in } \Omega, \quad \forall i = 1, \dots, N. \quad (4)$$

where the elements $\operatorname{div}_\rho \vec{a}_i \in L^2(\Omega, \rho \, dx)$ are defined as

$$\int_\Omega \operatorname{div}_\rho \vec{a}_i \varphi \rho \, dx = - \int_\Omega (\vec{a}_i, \nabla \varphi)_{\mathbb{R}^N} \rho \, dx, \quad \forall \varphi \in C_0^\infty(\Omega), \quad (5)$$

and $\gamma = (\gamma_1, \dots, \gamma_N) \in \mathbb{R}^N$ is a given strictly positive vector.

Statement of the Optimal Control Problem

For given functions $y_d \in L^2(\Omega, \rho \, dx)$, $f \in C_0^\infty(\mathbb{R}^N)$, and a penalization parameter $\zeta > 0$, we consider the following problem:

$$I(A, y) = \zeta \int_{\Omega} |y(x) - y_d(x)|^2 \rho \, dx + \int_{\Omega} |\nabla y(x)|_{\mathbb{R}^N}^2 \rho \, dx \rightarrow \inf, \quad (6)$$

subject to the constraints

$$A \in U_{ad}, \quad (7)$$

$$-\operatorname{div}(\rho A(x) \nabla y) + \rho y = f \quad \text{in } \Omega, \quad y \in W(\Omega, \rho \, dx). \quad (8)$$

Remark 1.

The boundary value problem (8) can exhibit the Lavrentiev phenomenon and nonuniqueness of the weak solutions. As a result, the corresponding optimal control problem can be stated in different forms.

Classification of the Solutions to the Dirichlet BVP

Definition 1

We say that a function $y = y(A, f) \in W$ is a **weak solution** to BVP (7)–(8) if the integral identity

$$\int_{\Omega} \left((A(x) \nabla y, \nabla \varphi)_{\mathbb{R}^N} + y \varphi \right) \rho \, dx = \int_{\Omega} f \varphi \, dx \quad \forall \varphi \in C_0^\infty(\Omega). \quad (9)$$

Definition 2.

We say that $y = y(A, f) \in V$ is a **V-solution** ($H \subseteq V \subseteq W$) to BVP (7)–(8) if

$$\int_{\Omega} \left((A(x) \nabla y, \nabla \varphi)_{\mathbb{R}^N} + y \varphi \right) \rho \, dx = \int_{\Omega} f \varphi \, dx \quad \forall \varphi \in V. \quad (10)$$

or the energy equality

$$\int_{\Omega} \left((A(x) \nabla y, \nabla y)_{\mathbb{R}^N} + y^2 \right) \rho \, dx = \int_{\Omega} f y \, dx \quad (11)$$

holds true.

Classification of Optimal Control Problems

Remark 2

For a "typical" degenerate weight function ρ the space of smooth functions $C_0^\infty(\Omega)$ is not dense in W , and hence there is no uniqueness of the weak solutions.

Hence for the given control object we have the continuum of the different statements of the original OCP, namely

$$\left\{ \left\langle \inf_{(A,y) \in \Xi^w} I(A,y) \right\rangle, \left\langle \inf_{(A,y) \in \Xi_v} I(A,y) \right\rangle, H \subseteq V \subseteq W \right\}, \quad (12)$$

where

$$\Xi_v = \{(A,y) \in U_{ad} \times V \mid y \in V, (A,y) \text{ are related by (11)}\}, \quad (13)$$

$$\Xi^w = \{(A,y) \in U_{ad} \times W \mid y \in W, (A,y) \text{ satisfy (9)} \forall \varphi \in C_0^\infty(\Omega)\}. \quad (14)$$

Definition of Optimal Solutions

Definition 3

We say that a pair $(A^0, y^0) \in L^\infty(\Omega; \mathbb{R}^{N \times N}) \times W(\Omega, \rho \, dx)$ is a **weak** optimal (**H**- and **W**-optimal, resp.) solution to the problem (6)–(8), if (A^0, y^0) is a minimizer for $\langle \inf_{(A,y) \in \Xi^w} I(A, y) \rangle$ (for $\langle \inf_{(A,y) \in \Xi_H} I(A, y) \rangle$, and for $\langle \inf_{(A,y) \in \Xi_W} I(A, y) \rangle$, resp.), i.e.,

$$(A^0, y^0) \in \Xi^w \quad \text{and} \quad I(A^0, y^0) = \inf_{(A,y) \in \Xi^w} I(A, y),$$

$$(A^0, y^0) \in \Xi_H \quad \text{and} \quad I(A^0, y^0) = \inf_{(A,y) \in \Xi_H} I(A, y),$$

$$(A^0, y^0) \in \Xi_W \quad \text{and} \quad I(A^0, y^0) = \inf_{(A,y) \in \Xi_W} I(A, y).$$

Lavrentiev Phenomenon in OCP

For any V ($H \subseteq V \subseteq W$) we have $\emptyset \neq \Xi_V \subseteq \Xi^W$. Hence

$$\inf_{(A,y) \in \Xi^W} I(A,y) \leq \inf_{(A,y) \in \Xi_V} I(A,y) \quad \forall V \text{ s.t. } H \subseteq V \subseteq W. \quad (15)$$

Proposition 1

Assume that $H \neq W$, and variational problems

$$\left\langle \inf_{(A,y) \in \Xi_V} I(A,y) \right\rangle \quad \text{and} \quad \left\langle \inf_{(A,y) \in \Xi^W} I(A,y) \right\rangle \quad (16)$$

are solvable for any $f \in C_0^\infty(\mathbb{R}^N)$ and $y_d \in L^2(\Omega, \rho \, dx)$. Then there are a constant $\zeta^* > 0$ and functions $f^* \in C_0^\infty(\mathbb{R}^N)$, $y_d^* \in L^2(\Omega, \rho \, dx)$ such that the corresponding optimal solutions to (16) are different and

$$\inf_{(A,y) \in \Xi^W} I(A,y) < \inf_{(A,y) \in \Xi_V} I(A,y).$$

Auxiliaries Notion

Definition 4

We say that a sequence $\{\rho^\varepsilon\}_{\varepsilon>0}$ is a **non-degenerate perturbation** of a weight function ρ if:

$$\rho^\varepsilon + (\rho^\varepsilon)^{-1} \in L^\infty(\Omega), \quad \forall \varepsilon > 0, \quad (17)$$

$$\rho^\varepsilon \rightarrow \rho, \quad (\rho^\varepsilon)^{-1} \rightarrow \rho^{-1} \quad \text{in } L^1(\Omega) \quad \text{as } \varepsilon \rightarrow 0. \quad (18)$$

Definition 5

A bounded sequence $\{v_\varepsilon \in L^2(\Omega, \rho^\varepsilon dx)\}$ converges weakly to $v \in L^2(\Omega, \rho dx)$ if

$$\lim_{\varepsilon \rightarrow 0} \int_{\Omega} v_\varepsilon \varphi \rho^\varepsilon dx = \int_{\Omega} v \varphi \rho dx \quad \text{for any } \varphi \in C_0^\infty(\Omega),$$

and it is written as $v_\varepsilon \rightharpoonup v$ in $L^2(\Omega, \rho^\varepsilon dx)$.

Compensated Compactness Lemma in Variable Spaces

Lemma 1

Let $\{\rho^\varepsilon\}_{\varepsilon>0}$ be a non-degenerate perturbation of a weight function $\rho(x) \geq 0$. Let $\{\vec{f}_\varepsilon \in L^2(\Omega, \rho^\varepsilon dx)^N\}_{\varepsilon>0}$ and $\{g_\varepsilon \in W^{1,2}(\Omega, \rho^\varepsilon dx)\}_{\varepsilon>0}$ be such that

- 1 $\{\vec{f}_\varepsilon\}_{\varepsilon>0}$ is bounded in the variable space

$$X(\Omega, \rho^\varepsilon dx) = \left\{ \vec{f} \in L^2(\Omega, \rho^\varepsilon dx)^N \mid \operatorname{div}_{\rho^\varepsilon} \vec{f} \in L^2(\Omega, \rho^\varepsilon dx) \right\},$$

and $\vec{f}_\varepsilon \rightharpoonup \vec{f}$ in $L^2(\Omega, \rho^\varepsilon dx)^N$;

- 2 $g_\varepsilon \rightarrow g$ in $L^2(\Omega, \rho^\varepsilon dx)$, and $\nabla g_\varepsilon \rightharpoonup \nabla g$ in $L^2(\Omega, \rho^\varepsilon dx)^N$.

Then $\lim_{\varepsilon \rightarrow 0} \int_{\Omega} \varphi \left(\vec{f}_\varepsilon, \nabla g_\varepsilon \right)_{\mathbb{R}^N} \rho^\varepsilon dx = \int_{\Omega} \varphi \left(\vec{f}, \nabla g \right)_{\mathbb{R}^N} \rho dx, \forall \varphi \in C_0^\infty(\Omega)$.

Compensated Compactness Lemma in Variable Spaces

Remark 3

In the previous Lemma the supposition "let $\{\rho^\varepsilon\}_{\varepsilon>0}$ be a non-degenerate perturbation of a weight function $\rho(\mathbf{x}) \geq 0$ " can be replaced by the following one: let $\{\rho^\varepsilon\}_{\varepsilon>0}$ be a sequence with properties:

- 1 $\rho^\varepsilon(\mathbf{x}) \geq 0, \forall \varepsilon > 0$;
- 2 $\rho^\varepsilon \rightarrow \rho, (\rho^\varepsilon)^{-1} \rightarrow \rho^{-1}$ in $L^1(\Omega)$ as $\varepsilon \rightarrow 0$;
- 3 for every $\varepsilon > 0$ the subspace $C_0^\infty(\Omega)$ is dense in $W(\Omega, \rho^\varepsilon d\mathbf{x})$ with respect to the norm $\|\cdot\|_{\rho^\varepsilon}$.

Existence Theorem for H -optimal solutions

Theorem 1

Let $\rho(x) \geq 0$ be a degenerate weight function. Then the optimal control problem

$$I(A, y) = \zeta \int_{\Omega} |y(x) - y_d(x)|^2 \rho \, dx + \int_{\Omega} |\nabla y(x)|_{\mathbb{R}^N}^2 \rho \, dx \rightarrow \inf, \quad (19)$$

$$A \in U_{ad}, \quad y \in H(\Omega, \rho \, dx), \quad (20)$$

$$\int_{\Omega} \left((A(x) \nabla y, \nabla \varphi)_{\mathbb{R}^N} + y \varphi \right) \rho \, dx = \int_{\Omega} f \varphi \, dx \quad \forall \varphi \in H(\Omega, \rho \, dx) \quad (21)$$

admits at least one H -solution

$$(A^{opt}, y^{opt}) \in \Xi_H \subset L^\infty(\Omega; \mathbb{R}^{N \times N}) \times H(\Omega, \rho \, dx)$$

for every $f \in L^2(\Omega, \rho^{-1} \, dx)$.

Perturbation Approach to the Existence of W -Optimal Solutions

Let $\{\rho^\varepsilon = ((\rho^{-1})_\varepsilon)^{-1}\}_{\varepsilon>0}$ be an "inverse" smoothing of a degenerate weight function $\rho(x) \geq 0$, i.e. $\rho^\varepsilon = ((\rho^{-1})_\varepsilon)^{-1} \forall \varepsilon > 0$, where $(\rho^{-1})_\varepsilon(x) = \int_{\mathbb{R}^N} K(z) \rho^{-1}(x + \varepsilon z) dz$.

We introduce the following collection of perturbed optimal control problems in coefficients for non-degenerate elliptic equations:

$$I_\varepsilon(A, y) = \zeta \int_{\Omega} |y(x) - y_d(x)|^2 \rho^\varepsilon dx + \int_{\Omega} |\nabla y(x)|_{\mathbb{R}^N}^2 \rho^\varepsilon dx \rightarrow \inf, \quad (22)$$

$$A \in U_{ad}^\varepsilon, \quad y \in W_0^{1,2}(\Omega, \rho^\varepsilon dx), \quad (23)$$

$$-\operatorname{div}(\rho^\varepsilon A(x) \nabla y) + \rho^\varepsilon y = f \quad \text{in } \Omega, \quad (24)$$

$$U_{ad}^\varepsilon = \left\{ A = [\vec{a}_1, \dots, \vec{a}_N] \in M_\alpha^\beta(\Omega) \mid |\operatorname{div}_{\rho^\varepsilon} \vec{a}_i| \leq \gamma_i \quad \forall i = 1, \dots, N \right\}, \quad (25)$$

where the elements $f \in C_0^\infty(\mathbb{R}^N)$, $\zeta > 0$, and $\gamma = (\gamma_1, \dots, \gamma_N) \in \mathbb{R}^N$ are the same as it was for the original problem (6)–(8), (4).

Existence Theorem for W -optimal solutions

Theorem 2

The minimization problem $\left\langle \inf_{(A,y) \in \Xi_W} I(A,y) \right\rangle$ is the weak variational limit of the sequence (22)–(25) with respect to the weak convergence in the variable space $\mathbb{Y}(\Omega, \rho^\varepsilon dx) = L^\infty(\Omega; \mathbb{R}^{N \times N}) \times W_0^{1,2}(\Omega, \rho^\varepsilon dx)$.

Theorem 3

Let $\{(A_\varepsilon^0, y_\varepsilon^0) \in \Xi_\varepsilon\}_{\varepsilon > 0}$ be a sequence of optimal pairs to the perturbed problems (22)–(25). Then

$$A_\varepsilon^0 \overset{*}{\rightharpoonup} A^0 \text{ in } L^\infty(\Omega; \mathbb{R}^{N \times N}); \quad (26)$$

$$y_\varepsilon^0 \rightarrow y^0 \text{ in } L^2(\Omega, \rho^\varepsilon dx), \quad \nabla y_\varepsilon^0 \rightarrow \nabla y^0 \text{ in } L^2(\Omega, \rho^\varepsilon dx)^N, \quad (27)$$

$$\inf_{(A,y) \in \Xi_W} I(A,y) = I(A^0, y^0) = \lim_{\varepsilon \rightarrow 0} \inf_{(A_\varepsilon, y_\varepsilon) \in \Xi_\varepsilon} I_\varepsilon(A_\varepsilon, y_\varepsilon). \quad (28)$$

where $(A^0, y^0) \in \Xi_W$ is a W -optimal solution to the original problem.

Intermediate Result

Representation Formula

Let $\{\rho^\varepsilon = ((\rho^{-1})_\varepsilon)^{-1}\}_{\varepsilon>0}$ be an "inverse" smoothing of a degenerate weight function $\rho(\mathbf{x}) \geq \mathbf{0}$, and let $(\vec{\mathbf{a}}_k)_\varepsilon$ be a "direct" smoothing of k -th column of \mathbf{A} , i.e.

$$(\vec{\mathbf{a}}_k)_\varepsilon(\mathbf{x}) = \int_{\mathbb{R}^N} K(z) \vec{\mathbf{a}}_k(\mathbf{x} + \varepsilon z) dz.$$

Then the smoothness of the functions $(\vec{\mathbf{a}}_k)_\varepsilon$ and ρ^ε produces the following representation formula for elements $\operatorname{div}_{\rho^\varepsilon}(\vec{\mathbf{a}}_k)_\varepsilon \in L^2(\Omega, \rho^\varepsilon d\mathbf{x})$

$$\operatorname{div}_{\rho^\varepsilon}(\vec{\mathbf{a}}_k)_\varepsilon = (\rho^\varepsilon)^{-1} \operatorname{div}(\rho^\varepsilon(\vec{\mathbf{a}}_k)_\varepsilon) \quad \forall k = 1, \dots, N, \quad \forall \varepsilon > 0,$$

where the element $\operatorname{div}(\rho^\varepsilon(\vec{\mathbf{a}}_k)_\varepsilon)$ is defined in the sense of distributions.

Some Remarks on Weak Optimal Solutions

Remark 5

The existence of the **weak optimal controls** in coefficients to the degenerate elliptic equation

$$I(A, y) = \zeta \int_{\Omega} |y(x) - y_d(x)|^2 \rho \, dx + \int_{\Omega} |\nabla y(x)|_{\mathbb{R}^N}^2 \rho \, dx \rightarrow \inf, \quad (29)$$

$$A \in U_{ad}, \quad y \in W(\Omega, \rho \, dx), \quad (30)$$

$$\int_{\Omega} \left((A(x) \nabla y, \nabla \varphi)_{\mathbb{R}^N} + y \varphi \right) \rho \, dx = \int_{\Omega} f \varphi \, dx \quad \forall \varphi \in C_0^\infty(\Omega) \quad (31)$$

has not been considered in the literature.

The main reasons:

- 1 there is no appropriate a priori estimates for the weak solutions of boundary value problem (30)– (31) in $\|\cdot\|_{\rho}$ -norm;
- 2 the main topological properties of the set of weak admissible solutions Ξ^w such as closedness, compactness, and etc, are unknown in general.

Illustration of the Specific of Weak Optimal Controls in Coefficients

Proposition 2

Let $(A_w^0, y_w^0) \in \Xi^w$ be a weak (but not variational) optimal solution to the problem (29)–(31). Assume that a subset

$$E = \left\{ x \in \Omega \mid [\bar{a}_{w1}^0, \dots, \bar{a}_{wN}^0] =: A_w^0(x) > \alpha I, \right. \\ \left. (A_w^0(x))^{-1} > \beta^{-1} I, \quad \left| \operatorname{div}_\rho \bar{a}_{wi}^0(x) \right| < \gamma_i \right\} \quad (32)$$

has a nonzero Lebesgue measure, and there exists a matrix $A^* \in U_{ad}$ such that

$$\int_{\Omega} \left(A^*(x) \nabla y_w^0, \nabla \varphi \right)_{\mathbb{R}^N} \rho \, dx = 0 \quad \forall \varphi \in C_0^\infty(\Omega). \quad (33)$$

Then there is a continuum of the weak optimal solutions to the problem (29)–(31), namely, $(A_w^0(x) + \theta \chi_E(x) A^*(x), y_w^0)$ is a weak optimal solution for all $|\theta|$ small enough. Here χ_E denotes the characteristic function of E .

Illustration of the Specific of Weak Optimal Controls in Coefficients

Proposition 3

Assume that $\left\langle \inf_{(A,y) \in \Xi^w} I(A,y) \right\rangle$ is a variational weak limit of the sequence of optimal control problems

$$I_\varepsilon(A,y) = \zeta \int_{\Omega} |y(x) - y_d(x)|^2 \rho^\varepsilon dx + \int_{\Omega} |\nabla y(x)|_{\mathbb{R}^N}^2 \rho^\varepsilon dx \rightarrow \inf, \quad (34)$$

$$A \in U_{ad}^\varepsilon, \quad y \in W_0^{1,2}(\Omega, \rho^\varepsilon dx), \quad (35)$$

$$-\operatorname{div}(\rho^\varepsilon A(x) \nabla y) + \rho^\varepsilon y = f \quad \text{in } \Omega, \quad (36)$$

$$U_{ad}^\varepsilon = \left\{ A = [\vec{a}_1, \dots, \vec{a}_N] \in M_\alpha^\beta(\Omega) \mid |\operatorname{div}_{\rho^\varepsilon} \vec{a}_i| \leq \gamma_i \quad \forall i = 1, \dots, N \right\}, \quad (37)$$

under some non-degenerate perturbation $\{\rho^\varepsilon\}_{\varepsilon>0}$ of a weight function $\rho(x) \geq 0$. Then **none of a weak optimal solution** $(A_w^0, y_w^0) \in \Xi^w$ (which is not a variational one) can be attained via the optimal solutions to the perturbed problems (34)–(37).

Thank you for your unlimited patience

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